Acoustic behaviours of large crustaceans in NE Atlantic coastal habitats

Laura Coquereau1,*, Jacques Grall2, Jacques Clavier1, Aurélie Jolivet1,3, Laurent Chauvaud1,2

1Université de Bretagne Occidentale, Institut Universitaire Européen de la Mer, Laboratoire des Sciences de l’Environnement Marin, UMR 6539, BeBEST, rue Dumont D’Urville, 29280 Plouzané, France
2Observatoire Marin, UMS 3113, Institut Universitaire Européen de la Mer, rue Dumont D’Urville, 29280 Plouzané, France
3TBM environnement/Somme, 115 rue Claude Chappe, Technopole Brest Iroise, 29280 Plouzané, France

ABSTRACT: Although many studies have investigated the benthic environment of temperate marine waters, little is known about the acoustic behaviour of the organisms in these habitats, particularly crustaceans. This study focused on the acoustic behaviour of large crustaceans in NE Atlantic coastal regions. A total of 11 crustacean species were recorded in tank-based experiments to identify sound-producing species and the behaviours associated with their sounds as well as to quantitatively characterise and compare the sounds. A total of 34 sounds were associated with behaviours such as moving, feeding, mandible rubbing, swimming, species-specific behaviour and other unidentified behaviours. The sounds included single pulse and pulse train signals that were distributed across a peak frequency spectrum of 3 to 45 kHz with received levels between 93 and 142 dB re 1 μPa (peak to peak). The results demonstrated that Brachyura had the most diverse sound types. Using a combination of several acoustic features, 24% of the recorded sounds appeared to have a high potential to be differentiated in field recordings: the feeding sound of Cancer pagurus, Carcinus maenas, Necora puber and Pachygrapsus marmoratus, the species-specific sound of C. pagurus and Galathea squamifera; and the pulse train sound associated with unidentified behaviours of Lophozozymus incisus and N. puber. These findings extend the existing crustacean acoustic library in marine ecosystems and contribute to our understanding of in situ acoustic recordings in temperate regions.

KEY WORDS: Acoustic behaviour · Sound library · Crustaceans · Crabs · Snapping shrimps

INTRODUCTION

Both field and tank-based experiments have shown that a variety of crustacean species can produce acoustic signals. These species include the (sub-)classes Cirripedia and Malacostraca (reviewed by Ewing 1989, Budelmann 1992, Schmitz 2002). Several taxa have been investigated in greater detail, including snapping shrimps (Au & Banks 1998, Bohnenstiehl et al. 2016), mantis shrimps (Patek & Caldwell 2006), spiny lobsters (Patek & Oakley 2003) and semi-terrestrial crabs (Boon et al. 2009). These taxa produce sounds through a variety of mechanisms, including stridulation (Guinot-Dumortier & Dumortier 1960, Boon et al. 2009), stick−slip friction (Moulton 1957, Patek 2002, Patek & Baio 2007), carapace vibration (Henninger & Watson 2005, Patek & Caldwell 2006, Ward et al. 2011) and cavitation bubble collapse (Knowlton & Moulton 1963, Versluis et al. 2000). While the behavioural meaning of sound

*Corresponding author: laura.coquereau@univ-brest.fr
production is often unclear, several researchers have attributed communicative functions to some sounds (for example, defence against predators, courtship, orientation and agonistic interactions; Boon et al. 2009, Stanley et al. 2010, Buscaino et al. 2015). These crustacean sounds contribute substantially to the marine soundscapes (Patek & Oakley 2003, Freeman et al. 2014) and may have important information about the local ecology, local populations and, more generally, habitat ecology (Watanabe et al. 2002, Piercy et al. 2014).

Much of our understanding about crustacean sound production comes from recordings of warm-water species. Far less is known about species that inhabit temperate regions where, to date, few studies have been conducted to identify sound production behaviours. The European spiny lobster *Palinurus elephas* creates sound in association with anti-predatory behaviours (Buscaino et al. 2011, de Vincenzi et al. 2015). The lobster *Homarus gammarus* frequently produces vibrations when handled or attacked by octopus; this suggests an escape function, analogous to stridulation in palinurids (Bouwma & Herrnkind 2009). Coquereau et al. (2016) showed that the snapping shrimp *Athanas nitescens* produces loud snapping sounds, while the spider crab *Maja brachydactyla* produces at least 3 different sound types: a feeding sound plus 2 sounds that are not associated with particular behaviours. Beyond these examples, the sound production of several common large crustaceans in temperate waters has not yet been investigated.

Although several authors have demonstrated the influence of crustacean species on temperate coastal habitats (Abele 1974, Brown & Bennett 1980, Sheehy & Prior 2008), the ecology of the local populations (such as changes in their behaviour, migration and abundance) and their biological rhythms remain poorly understood (Boudreau & Worm 2012). The use of passive acoustics as a non-invasive tool might be useful to aid in our understanding of ecological phenomena and processes (Butler et al. 2016). The aims of this study were to identify several soniferous large crustacean species inhabiting NE Atlantic coastal regions and to evaluate the extent to which passive acoustics could provide valuable crustacean ecological information in future field recordings. This exploratory study had 3 parts: (1) assessment of crustacean sound production and associated behaviours in tank-based experiments; (2) quantification of the sound characteristics; and (3) comparison of sound production among the studied species.

**MATERIALS AND METHODS**

**Animal collection and care**

Crustaceans were collected from the Bay of Brest in France during the summer of 2015. The selection of the target crustacean species was based on 3 criteria: the crustacean should be a species of megafauna (>2 cm); the crustacean should be common (according to their abundance and overall presence in NE Atlantic coastal habitats); and the acoustics of the crustacean should not have been described previously. A list of 11 species that met these criteria was created: Anomura *Galathea squamifera*; Brachyura *Cancer pagurus*, *Carcinus maenas*, Necora *puber*, *Pachygrapsus marmoratus*, *Pilumnus hirtellus* and Lophozymus *incisus*; Caridea *Crangon crangon* and *Palaemon serratus*; and Cirripedia *Balanus perforatus* and *Pollicipes pollicipes*. Between 3 and 53 individuals of each species were sampled, depending on specimen availability.

The crustaceans were carefully caught by divers or by hand in the intertidal zone. After collection, the animals were transferred to a quiet laboratory (Chorus laboratory, Grenoble INP Foundation) at the Océanopolis public aquarium in Brest. This laboratory is equipped for long-term housing of crustaceans in 6 rectangular glass-sided tanks (60 × 50 cm and 40 cm water depth) that are continuously supplied with fresh UV- and sand-filtered seawater from the Bay of Brest (temperature: 17−17.3°C, salinity: 35.0−35.2). The crustaceans were distributed by species in 5 tanks (each tank contained 1, 2 or 3 species), and 1 tank was kept for acoustic recordings and was termed the experimental tank. The animals were fed every 2 d except during feeding experiments, as described in ‘Experimental procedures: Identification of sounds and behaviours’, with a variety of frozen organisms (shrimp, mussel and pieces of mackerel for Anomura and Brachyura, crushed mussels for Caridea and *Artemia* spp. for Cirripedia). They were maintained in an 11 h light:13 h dark cycle.

**Experimental procedures**

Sound measurements

The acoustic signals emitted by the crustaceans were recorded using a calibrated HTI-92-WB pre-amplified hydrophone (High Tech) that had a sensitivity of −155 dB re 1 V μPa⁻¹ and a flat frequency response from 2 to 50 kHz. The hydrophone was con-
Coquereau et al.: Acoustic behaviours of large temperate crustaceans

connected to an EA-SDA14 compact autonomous recorder set at 14.7 dB gain (RTSys®). Acoustic recordings were acquired with a sampling rate of 156 kHz with 24 bit resolution. The hydrophone was suspended at the centre of the tank and was positioned 11 cm above the tank bottom.

Identification of sounds and behaviours

The animals were acclimated to the laboratory conditions for at least 1 mo before the beginning of the experiments. A silicone plate (0.5 cm thick) was placed on the bottom of the experimental tank to prevent sound emissions caused by friction between their hard body parts and the glass. Sound recordings were performed separately for each species. Individuals of a given species were randomly collected from the tank where they were housed and released into the experimental tank. The number of individuals in the experimental tank was chosen to mimic the natural abundance as estimated over 2 decades in a coastal habitat long-term survey conducted in Brittany (Grall 2002; data obtained from the Observatory of the Institut Universitaire Européen de la Mer).

Two sets of observations and recordings of sounds were conducted: one set during the day (shorter recordings) to capture potential moving and feeding sounds and another set of longer observations (24 h), which included nights, to capture other potential acoustic behaviours and interactions among individuals. Sounds emitted when the individuals were moving or feeding were selected for analysis because these behaviours are frequently encountered in the natural environment, and they occur year-round. Moving behaviour was recorded in the presence of the substrate on which the species lives (i.e. rock or sand), and no stimulation was used to encourage moving behaviour. The silicone plate, left on the bottom of the tank, was covered by a layer of sand (about 4 cm) or by rocks. For the feeding behaviour experiments, the crustaceans were food-deprived for 7 d to ensure triggering of feeding behaviour during the recordings. All other sounds associated with behaviours that were observed in the tank were recorded and analysed. After being released into the experimental tank, the animals were allowed to adapt to the tank for 1 h before recording began. After an hour, the crustaceans appeared calm and exhibited normal behaviour. Each recording lasted from 1 to 2 h and was performed on at least 2 different days. The water flow system was turned off during the recording period to reduce background noise. Recordings were conducted during the day from 08:00 to 19:00 h, which corresponds to the natural daytime period when the study was performed.

To determine the association of acoustic signal production with a particular behavioural event, visual observations and/or video recordings were conducted using a GoPro® HERO3 and were synchronised with the acoustic recordings. We assigned behavioural names to sounds that were produced in clear behavioural contexts (e.g. sounds produced while the animal was feeding or while it was moving on a rock). To avoid anthropomorphic interpretations of sounds that overlap in acoustic features (similar shape, similar acoustic features values) within the species but which lacked a clear behavioural context, we used the terms Type 1, Type 2, etc. We used ‘unidentified behaviour’ for species-specific sounds when we were not able to establish a clear relationship between the sound and a particular behaviour.

Because many decapod crustaceans are nocturnal and therefore active during dim or twilight hours (Strauss & Dircksen 2010), each species was recorded over a 24 h cycle in addition to the shorter recording sessions. Recordings were performed as in the short-time experiments (density, silicone plate, sound measurements) except that the crustaceans were acclimated in the recording tank for 24 h before the recording began. A camera was placed on a tripod outside and in front of the experimental tank containing the silicone plate. A neutral red light, to which crustaceans are known to have low sensitivity (Johnson et al. 2002), was mounted overhead so we could determine the association of sound production with behaviours. The acoustic recordings were analysed for 16 h (12 h of the night phase plus 2 h before and after the night phase) by scanning for 10 min every 30 min. When acoustic signals were detected, the video footage was viewed.

Data analysis

Acoustic features of crustaceans

The sound data (.wav files) were bandpass filtered between 2 and 78 kHz (sampling rate divided by 2) and were analysed using Raven®, and specific signal processing routines were developed in Matlab®. Sounds either were emitted as a short single transient broadband signal or consisted of a series of pulses. To characterise and quantify the features of
the acoustic signatures, the signals of each sound type were selected manually. The sound analyses were performed and the acoustic features were processed according to the methods described by Coquereau et al. (2016). Because of reflections from the water surface and from the walls and bottom of the tank, the acoustic parameters are subjected to distortion (Parvulescu 1964, 1967, Akamatsu et al. 2002). Specifically, the duration of the sound is distorted because of the relatively small size of the tanks (<2 m in length). Therefore, there could have been reverberation, with the sound persisting in the enclosed space. To limit errors resulting from reverberation of the tank walls, the acoustic measurements were performed on the initial part (the direct path before the echoes arrived, following methods described in Coquereau et al. 2016) of the signals, which are poorly affected by tank artefacts (Fig. 1). Simulations of transient signal emissions were performed previously to evaluate the effects of reverberation on signal features, and these simulations revealed that tank-induced errors do not significantly affect the peak frequency ($f_p$) estimations of the initial part of transient signals in experimental tanks (Coquereau et al. 2016). We measured 2 features of the initial part of the signals: (1) the received level (RL, in dB re 1 μPa peak to peak [pp]) calculated in the time window equal to signal selection; and (2) the $f_p$ (in Hz), which was defined as the frequency at which the power spectral density (dB re 1 μPa² Hz⁻¹) was maximal within the selection. The mean, standard deviation (SD) and minimum and maximum values were determined for the acoustic features of each sound type. Median acoustic spectra (dB re 1 μPa² Hz⁻¹; the temporal distribution of frequency spectra across the duration of a sound event) between 2 and 50 kHz were determined for each sound type (128-point fast Fourier transform, rectangular window, overlap 50%). In addition, to get an idea of the in situ detectability of the sounds that were recorded, in situ estimated detection distances (EDDs) were determined for each sound type, assuming spherical spreading transmission loss. The EDD was calculated using the formula:

$$EDD = R_0 \frac{RL-(NL+8)}{20}$$

(1)

In this equation, $R_0$ is the mean distance (m) between the sound source and the hydrophone, RL (dB re 1 μPa) is the mean received level of a species’ sound type, 8 (in dB) corresponds to the minimum signal-to-noise ratio needed to detect the noise and NL is the noise level in dB re 1 μPa. The NL was a mean in situ ambient noise level (ANL = 85.6 dB) or standard theoretical noise levels computed for open water (Wenz reference curves, Wenz [1962]) for various meteorological conditions: wind speed at 1 knot (kn) (NL = 77) and at 5 kn (NL = 83). The in situ ANL was based on the value calculated by Coquereau et al. (2016) from field recordings in a biogenic habitat in the Bay of Brest. The crustacean species recorded in this study are found in this habitat, and the values are consistent (day and night recordings and replicates at different sites). These calculations are described in detail in Coquereau et al. (2016). For signals composed of a series of pulses, defined as at least 2 pulses that occurred within 10 ms of each other, we also measured the number of pulses per train, the pulse-to-pulse time intervals, the duration of the entire train and the pulse rate (pulses s⁻¹: number of pulses per train divided by the duration of the entire train) (Fig. 2). The duration of the entire train of pulses was measured to compare signal production in different species, but care should be taken when extrapolating these values to a natural context (Parvulescu 1964, 1967, Akamatsu et al. 2002). Data from Maja brachy-dactyla (Brachyura) and Athanas nitescens (Caridea), the acoustics of which were previously described in the same laboratory setting and using the same acoustic calculations (Coquereau et al. 2016), were added into the figures for comparison with the crustaceans recorded in this study.
Statistical analysis

The similarities between species for the presence/absence of acoustic behaviours were compared with a hierarchical method (spherical) of cluster analysis using the Jacquard index (Anderberg 1973). The acoustic features were compared statistically according to species and behaviours. Because the data were not normally distributed (Shapiro-Wilk test, p < 0.05), the non-parametric Kruskal-Wallis test with Dunn's test was used to assess differences between the acoustic features ($f_p$ and RL) of signals emitted by the crustaceans (Hollander et al. 2014). The Mann-Whitney U-test was used to compare the characteristics of pulse train sounds (the number of pulses per train, the pulse-to-pulse time intervals, the duration of the entire train and the pulse rate) shared between 2 species. Statistical tests were performed using R Studio 3.0.2© software.

RESULTS

General characteristics of the crustacean sounds

Analysis of approximately 130 h of audio/video recordings showed that of the 11 crustacean species investigated in the laboratory settings, 9 produced detectable sounds (Table 1). The 2 species for which no acoustic signals were detected were Balanus perforatus and Pilumnus hirtellus. Overall, 34 different sound types were detected during the recording sessions.

Acoustic behaviours

Crustacean sounds were produced in different behavioural contexts, including when the animals were moving on rock, moving on sand, swimming, feeding and rubbing their mandibles (Table 1, Fig. 3, see sound library in Supplement 1 at www.int-res.com/articles/b025p151_supp/). Similar pulse train sounds were produced by several species without clear-cut identification of the associated behaviour; we termed this Type 1 sound. The recorded crustaceans also produced species-specific sounds that were associated with specific behaviours (Table 1). These sounds included antennae rubbing for Galathea squamifera, antennule rubbing and an unidentified

Table 1. Recorded crustaceans living in NE Atlantic coastal habitats. x: signals were detected during the recording sessions; ND: no detected signal

<table>
<thead>
<tr>
<th>Recorded species</th>
<th>No. ind. recorded</th>
<th>Total no. of analysed signals</th>
<th>Moving on rock</th>
<th>Moving on sand</th>
<th>Swimming</th>
<th>Feeding</th>
<th>Mandibles rubbing</th>
<th>Type 1</th>
<th>Species-specific behaviour</th>
</tr>
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<tbody>
<tr>
<td><strong>Anomura</strong></td>
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<tr>
<td>Galathea squamifera</td>
<td>5</td>
<td>284</td>
<td>x</td>
<td>ND</td>
<td>ND</td>
<td>x</td>
<td>ND</td>
<td>ND</td>
<td>x</td>
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<td><strong>Brachyura</strong></td>
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<tr>
<td>Cancer pagurus</td>
<td>6</td>
<td>748</td>
<td>x</td>
<td>x</td>
<td>ND</td>
<td>x</td>
<td>x</td>
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<td>x</td>
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<td>x</td>
<td>x</td>
<td>ND</td>
<td>x</td>
<td>x</td>
<td>x</td>
<td>ND</td>
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<tr>
<td>Lophozozymus incisus</td>
<td>6</td>
<td>296</td>
<td>x</td>
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<td>x</td>
<td>x</td>
<td>x</td>
<td>ND</td>
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<td>Necora puber</td>
<td>4</td>
<td>204</td>
<td>x</td>
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<td>ND</td>
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<td>439</td>
<td>x</td>
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<td>ND</td>
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<td>ND</td>
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<td>Pilumnus hirtellus</td>
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<td>Crangon crangon</td>
<td>35</td>
<td>103</td>
<td>ND</td>
<td>ND</td>
<td>x</td>
<td>ND</td>
<td>ND</td>
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<td>ND</td>
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<tr>
<td>Palaemon serratus</td>
<td>15</td>
<td>252</td>
<td>ND</td>
<td>ND</td>
<td>x</td>
<td>x</td>
<td>ND</td>
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<tr>
<td><strong>Cirripedia</strong></td>
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<tr>
<td>Balanus perforatus</td>
<td>-50</td>
<td>0</td>
<td>ND</td>
<td>ND</td>
<td>ND</td>
<td>ND</td>
<td>ND</td>
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<td>ND</td>
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<tr>
<td>Pollicipes pollicipes</td>
<td>53</td>
<td>111</td>
<td>ND</td>
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<td>ND</td>
<td>ND</td>
<td>ND</td>
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</table>
behaviour that produced a regular broadband pulse train signal for Cancer pagurus, cheliped rubbing and rubbing of mandibles with chelipeds for Necora puber and physical contact between individuals for Pollicipes pollicipes.

The sound types that were identified during the night in the 24 h acoustic recordings were mostly the same as those identified during the short daytime recordings. The night recordings also showed 3 new sound types: Type 1 sounds for both C. pagurus and Lophozozymus incisus and a sound associated with an unidentified behaviour for C. pagurus that consisted of irregular broadband pulses. These 3 sound types were also found in the daytime portion of the 24 h recordings, so they were not specific to the night.

Brachyura produced the most different sound types (4 per species on average), followed by Anomura (3 sound types for G. squamifera) and Caridea and Cirripedia (1 per species) (Table 1). Feeding was the most shared acoustic behaviour among the species (recorded for 7 of the 9 soniferous crustaceans). Cluster analysis identified 2 groups with similar acoustic type profiles (Fig. 4): one group comprised Brachyura and Anomura, and a second group comprised Cirripedia and Caridea.

Acoustic features

The 34 sound types covered a broad spectrum of peak frequencies that ranged from 2.5 to 41 kHz and that had a mean $f_p$ of 19 ± 9 kHz (Fig. 5). The distribution of the peak frequencies was bimodal (modes of 2.5 to 7.5 kHz and 27.5 to 37.5 kHz). RLs ranged from 93 to 142 dB re 1 μPa (pp) with a mean of 107 ± 5 dB re 1 μPa (pp). RL data were shifted towards a unimodal distribution (mode of 95 to 105 dB re 1 μPa [pp]). The feeding sounds were mostly composed of low mean peak frequencies (from 4 to 10 kHz), but they were more or less loud depending on the species (Fig. 5). Acoustic spectra were calculated for the stack of all signal selections for each sound type. Fig. 6 shows examples of the acoustic spectra associated with feeding for 7 species: N. puber, G.
Coquereau et al.: Acoustic behaviours of large temperate crustaceans

Fig. 4. Cluster analysis comparing the species for presence/absence of acoustic behaviour using the Jacquard index (black = presence; white = absence). See Table 1 for full species names.

**squamifera** and *Carcinus maenas* had distinct feeding spectral characteristics, whereas *Cancer pagurus* and *Pachygrapsus marmoratus* had similar feeding acoustic spectral shapes, as did *Palaemon serratus* and *L. incisus*.

The EDDs were greater for Anomura and Brachyura than for Caridea and Cirripedia, which presented EDDs <1 m in all 3 conditions, i.e. Wenz 1 kn, Wenz 5 kn and in situ ANL. The majority of the acoustic behaviours of *C. pagurus* and *N. puber* showed high EDDs at low wind regimes. Sounds associated with feeding for Brachyura and with moving on sand and Type 1 behaviour for *C. pagurus*, *N. puber* and *L. incisus* all showed high EDD values (up to 39.0 m in high wind conditions and up to 28.9 m with in situ ANL). In contrast, sounds associated with moving on rock, mandible rubbing, swimming and the majority of species-specific behaviours had lower EDD values.

Fig. 5. (a) Peak frequencies and (b) received levels of sound types recorded from crustacean species living in NE Atlantic coastal habitats. The sounds were produced during feeding behaviour and during non-feeding behaviours that included moving, swimming, mandible rubbing, Type 1 and species-specific behaviours. pp: peak to peak.

Fig. 6. Average acoustic spectra (1 μPa² Hz⁻¹ at 1 m) of the stack of all signal selections for feeding sound types emitted by crustacean species living in NE Atlantic coastal habitats (128-point fast Fourier transform, rectangular window with 50% overlap). Numbers in parentheses correspond to the peak frequencies of the sounds (in kHz). Species: Anomura *Galathea squamifera* (G. s); Brachyura *Cancer pagurus* (C. p), *Carcinus maenas* (C. m), *Necora puber* (N. p), *Pachygrapsus marmoratus* (P. m) and *Lophozozymus incisus* (L. i); Caridea *Palaemon serratus* (P. s).
in the 5 kn wind and in situ ANL settings. Tables S1 & S2 in Supplement 2 at www.int-res.com/articles/suppl/b025p151_supp/ lists the acoustic feature values (RL, \( f_p \), bandwidth, in situ EDD) of each soniferous crustacean and the associated behaviours recorded in this study.

**Comparison of sound characteristics**

The sound types were compared between species and according to the behaviours. The sounds could be categorised into 2 groups based on their acoustic features, especially the \( f_p \) value (Fig. 7). The first group was composed mainly of sounds associated with moving on rock, feeding (for the Brachyura), Type 1 and moving on sand. This group was characterised by a low \( f_p \) (from 2 to 20 kHz), and the majority of sounds had high RL values (up to 142 dB re 1 \( \mu \)Pa [pp]). The second group was composed of sounds generated by body parts rubbing together, including sounds associated with swimming, mandible rubbing and species-specific behaviours. This group was characterised by high \( f_p \) (from 25 to 45 kHz) and low RL values (up to 116 dB re 1 \( \mu \)Pa [pp]).

Fig. 7. Acoustic features of sounds recorded by (a) behaviour types and (b) taxa. The median peak frequencies are indicated by circles along with the bandwidths for the species: *Galathea squamifiera* (G. s), *Cancer pagurus* (C. p), *Carcinus maenas* (C. m), *Necora puber* (N. p), *Pachygrapsus marmoratus* (P. m), *Lophozozymus incisus* (L. i), *Crangon crangon* (C. c), *Palaemon serratus* (P. s) and *Pollicipes pollicipes* (P. p). The circle size varies according to the classes of the received levels. The dotted boxes indicate species that did not differ significantly from each other in terms of peak frequency, received level or pulse sequence features (Kruskal-Wallis multiple comparison test). Data from *Maja brachydactyla* (M. b) and *Athanas nitescens* (A. n) originated from Coquerneau et al. (2016). pp: peak to peak.
The *Maja brachydactyla* feeding sound had acoustic features that were similar to the feeding sounds recorded in this study for the Brachyura, as did the sound associated with Type 1 behaviour (Fig. 7a). The snapping sound made by *Athanas nitescens* matched the louder sounds recorded in this study and with sounds in the group that had high $f_p$ values.

The acoustic features $f_p$, RL or both differed significantly within and across behaviours (Kruskal-Wallis multiple comparison tests, $p < 0.05$) (Figs. 7a & 8). Only the following did not show significant differences between species in terms of $f_p$ and RL values (Kruskal-Wallis multiple comparison test, $p > 0.05$): moving on rock for *N. puber*, *G. squamifera* and *L. incisus*, species-specific behaviours for *N. puber* and *C. pagurus*, and Type 1 behaviour for *C. maenas* and *C. pagurus*. However, for the sound associated with Type 1 behaviour, which was a pulse train sound, the duration of the entire signal and the pulse-to-pulse time interval were significantly different between *C. maenas* and *C. pagurus* (Mann-Whitney U-test, $p < 0.05$ for the duration of
The acoustic features varied substantially both within and across the species (Figs. 7b & 8). The majority of the species (6 of the 9 soniferous species) had singular acoustic signatures for each of its behaviours in terms of $f_p$, RL or both (Kruskal-Wallis multiple comparison test, $p < 0.05$) (Fig. 7b). However, 3 species had behaviours for which some of the sounds overlapped. *N. puber* showed 3 groups of sounds associated with behaviours; these sounds were not significantly different in terms of $f_p$, RL or both (Kruskal-Wallis multiple comparison test, $p < 0.05$). The first group included sounds associated with feeding and Type 1 behaviour, the second group included sounds associated with mandible rubbing and species-specific behaviours and the third group included sounds associated with moving on rock behaviour. However, the sounds associated with feeding and Type 1 behaviour in the first group could be differentiated, as the pulse-to-pulse time intervals differed significantly (Mann-Whitney $U$-test, $p < 0.001$). For *L. incisus* and *C. pagurus*, the sounds associated with feeding, moving on rock and Type 1 behaviours did not differ significantly from each other (Kruskal-Wallis multiple comparison test, $p > 0.05$). Sounds associated with moving on rock could be distinguished from the other 2 sounds by the acoustical shape (single pulse vs. pulse train signal). The sounds associated with feeding and Type 1 behaviours could be differentiated by the pulse-to-pulse time interval, the duration of the entire signal and the pulse rate for both species *L. incisus* and *C. pagurus* (Mann-Whitney $U$-test, $p < 0.01$) (Fig. 8).

**DISCUSSION**

Because reverberation influences the acoustic features of sounds, the effects of tank reverberation on sound characteristics have been addressed (Pavulcescu 1964, 1967, Akamatsu et al. 2002). In their tank-based experimental study, Coquereau et al. (2016) used simulations to show that tank-induced errors do not significantly affect $f_p$ estimations of the initial part of transient signals. Using this methodology, the data obtained in the present study are consistent with the results of that study regarding the acoustic features. The sounds from the 2 soniferous crustacean species *Athanas nitescens* and *Maja brachydactyla* as reported by Coquereau et al. (2016) were in accordance with those recorded in our study in terms of $f_p$, RL, bandwidth, general signal shape and spectra. In addition, *M. brachydactyla* (Brachyura), shared sound types with the Brachyura recorded in our study (i.e. sounds associated with feeding and Type 1 behaviour) and had similar acoustic feature values.

This study, which recorded 11 crustacean species, is the most comprehensive acoustic study of crustaceans in temperate coastal habitats to date. Overall, 34 sound types from 9 species were detected. The recorded sounds were produced during common behaviours, such as moving, feeding and mandible rubbing, which occur year-round in the natural environment. Our study represents an approximate 40% increase in the total number of acoustic crustacean species found in NE Atlantic habitats (Buscaino et al. 2011, de Vincenzi et al. 2015, Coquereau et al. 2016).

Because our recordings were conducted in tanks, we could associate sound emissions with specific movements when the sounds were produced in an obvious behavioural context, such as when the animals rubbed calcareous parts together (for example, antenna rubbing for *Galathea squamifera* and cheliped rubbing for *Necora puber*). However, when
some sounds were produced, we did not observe any movement before, during or after the sound emission, and the individuals were mostly immobile. These sounds may result from very small rubbing movements of 2 body parts of an individual, as found for other crustacean species, which is difficult to observe (Guinot-Dumortier & Dumortier 1960, Boon et al. 2009). Buscaino et al. (2015) described the acoustic behaviour of the paddle crab *Ovalipes trimaculatus*. They showed that this species emitted pulse train signals similar in shape and acoustic behaviour of the California spiny lobster *Panulirus interruptus* in a tank vs. in the field. There was a more physically active behavioural response in the field than in the tank, but there were no differences in the sounds that were produced. They also found that lobsters in tanks responded more actively to intrusion during the day compared to the night, but their rasping behaviour did not change depending on the time of day. Another study showed that the Japanese spiny lobster *P. japonicus* did not produce different sounds at night than during the day, although the frequency of its stridulating sounds tended to increase at night (Kikuchi et al. 2015). Our results from the night parts of the recordings were consistent with these studies, and we think that the species we studied also make the same sounds at night as during the day. It would be interesting to perform additional night recordings for several 24 h cycles to see if the crustaceans we recorded would also increase their sound production frequency.

Using a combination of several acoustic features, such as $f_p$, RL, general signal shape, spectra and pulse train features, our study showed that the majority of crustacean sounds were likely to be differentiable according to species or behaviour. These results would be useful for the study of crustacean ecology, since sounds can provide information on presence and behaviours. This was an exploratory study, and it seems important in the future to record several species simultaneously to see if they can be differentiated based on an analysis of the sounds they produce. In future efforts, it would be interesting to use other approaches to better characterise and quantify the differences between the sounds, such as spectral entropy, spectral dissimilarity or waveform decompositions.

Among the sound types recorded in this study, a significant portion presented low EDDs ($\leq 1$ m): 44% in low wind conditions, 64% in high wind conditions and 73% using *in situ* ANL. This implies that a majority of the sounds recorded have low potential of detection in field recordings. Nevertheless, by looking at high EDD values and by combining
acoustic features, 8 of the 34 sounds recorded in this study have properties consistent with detectability and identification for in situ acoustic studies: the feeding sound of C. pagurus, Cancer pagurus, N. puber and Pachygrapsus marmoratus; the species-specific sound of C. pagurus and G. squamifera; and the sounds associated with Type 1 behaviour of Lophozozymus incisus and N. puber. It should be also pointed out that the in situ ANL used in this study was calculated in a temperate coastal habitat with very high diversity (up to 200 species m⁻²) (Barbera et al. 2003), which is therefore a noisy habitat. The species recorded in this study also live in other coastal habitats, such as soft-sediment habitats, that are less diverse and therefore probably less noisy. Consequently, the EDDs obtained using in situ ANL might be smaller than what would be found in other habitats. These data help approximate the detectability of species and acoustic behaviours in field recordings.

The sound library that was created in this study contributes to the documentation of crustacean acoustic behaviour. The ability to distinguish sounds at a precise taxon level and to associate sounds with behaviour suggests the potential value of acoustic monitoring of crustacean activities and ecology. For example, sounds produced during feeding behaviour could be used to demonstrate a correlation between rates of sound production and daily rhythms. On a broader scale, it may useful to monitor crustacean sound production over long periods of time to assess periodic population behaviour and migrations. Although specific experiments in the field are required to confirm the acoustic and behavioural findings presented here, this work demonstrates that crustaceans are substantial participants in the soundscape in NE Atlantic coastal habitats.

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