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Vertical movements of a pelagic thresher shark (*Alopias pelagicus*): insights into the species’ physiological limitations and trophic ecology in the Red Sea

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ABSTRACT: The pelagic thresher shark *Alopias pelagicus* is an understudied elasmobranch harvested in commercial fisheries of the tropical Indo-Pacific. The species is endangered, overexploited throughout much of its range, and has a decreasing population trend. Relatively little is known about its movement ecology, precluding an informed recovery strategy. Here, we report the first results from an individual pelagic thresher shark outfitted with a pop-up satellite archival transmitting (PSAT) tag to assess its movement with respect to the species’ physiology and trophic ecology. A 19 d deployment in the Red Sea revealed that the shark conducted normal diel vertical migration, spending the majority of the day at 200–300 m in the mesopelagic zone and the majority of the night at 50–150 m in the epipelagic zone, with the extent of these movements seemingly not constrained by temperature. In contrast, the depth distribution of the shark relative to the vertical distribution of oxygen suggested that it was avoiding hypoxic conditions below 300 m even though that is where the daytime peak of acoustic backscattering occurs in the Red Sea. Telemetry data also indicated crepuscular and daytime overlap of the shark’s vertical habitat use with distinct scattering layers of small mesopelagic fishes and nighttime overlap with nearly all mesopelagic organisms in the Red Sea as these similarly undergo nightly ascents into epipelagic waters. We identify potential depths and diel periods in which pelagic thresher sharks may be most susceptible to fishery interactions, but more expansive research efforts are needed to inform effective management.

KEY WORDS: *Alopias pelagicus* · nDVM · Endangered · Hypoxia · Mesopelagic · Pelagic thresher shark · PSAT · Red Sea · Scattering layer

1. INTRODUCTION

Pelagic thresher sharks *Alopias pelagicus* occur in open-ocean areas of the tropical Indo-Pacific (Smith et al. 2008) where they are regularly taken in commercial fisheries (e.g. González-Pestana et al. 2019) and sold in the shark fin trade (Clarke et al. 2006). The pelagic thresher shark is listed as Endangered with a decreasing population trend by the International Union for the Conservation of Nature (Rigby...
et al. 2019) and is a member of one of the most threat-
ened elasmobranch families in the world (Alopiidae; Dulvy et al. 2008). The species is particularly suscep-
tible to overexploitation due to its low population
productivity (Liu et al. 2006, Drew et al. 2015). Mis-
identification of the pelagic thresher shark has pre-
cluded accurate assessment of its distribution and
behavior (Smith et al. 2008), and it is the least studied
of the 3 thresher shark species even though it is the
most imperiled.

In particular, there have been no studies of a pelagic
thresher shark outfitted with a pop-up satellite
archival transmitting (PSAT) tag, and the species’ ver-
tical movement patterns remain largely undescribed.
This precludes movement ecology comparisons with
the common A. vulpinus and bigeye A. superciliosus
thresher sharks (Sepulveda et al. 2005, Smith et al.
2008), or with other pelagic predators that have been
the focus of numerous satellite telemetry studies (e.g.
Cartamil et al. 2011, Coelho et al. 2015).

The purpose of this study was to provide the first
description of the movement ecology of a pelagic
thresher shark outfitted with a PSAT tag. Using a
high-resolution data set from a juvenile pelagic
thresher shark in the Red Sea, in conjunction with
concurrent hydrographic and oxygen observations
collected by an autonomous ocean glider and light-
based estimates of scattering layer distribution, we
identified a normal diel vertical migration pattern
and analyzed these movements with respect to the
species’ physiological constraints and trophic niche.

2. MATERIALS AND METHODS

2.1. Satellite tagging

One male pelagic thresher shark was tagged with a
PSAT tag (miniPAT; Wildlife Computers) 23 km off
the coast of Thuwal, Saudi Arabia, in the eastern Red
Sea on 11 January 2020. The shark measured 1.25 m
fork length, which equates to 1.14 m precaudal
length, 2.44 m total length, and 31.4 kg total weight
based on established regressions for the species
(White 2007), and suggests that this individual was a
sexually immature juvenile (Tsai et al. 2010). The
shark took a baited hook at ~300 m depth during the
daytime and, after a 28 min fight on electric rod-and-
reel, was tagged alongside the vessel. The tag was
applied into the musculature near the base of the dor-
sal fin using a titanium dart as an anchor. The fishing
line was cut at the corner of the mouth and the hook
left in the posterior of the shark’s buccal cavity at the
time of release because the hook could not safely be
removed. The tag was programmed for a 3 mo de-
ployment and logged pressure (depth), temperature,
and light level every 5 s to onboard memory. Data
were summarized into 75 s resolution time series that
were transmitted via Argos satellites after tag release.

2.2. Geolocation methods

The most probable track of the pelagic thresher
shark was constructed using the HMMOCE package
(Braun et al. 2018). This approach combines tag-based
measurements of light levels, sea surface temperature,
and depth–temperature profiles with bathymetry and
oceanographic observations and model outputs to
construct likelihoods of the tagged individual’s move-
ments. Likelihoods from each of the aforementioned
inputs are convolved (i.e. combined via integral trans-
form) in a gridded hidden Markov model that com-
putes an output of posterior probability distributions
in a grid-based hidden Markov model that com-
putes an output of posterior probability distributions
to estimate the most likely state (position) of the ani-
mal at each time point (see the Supplement at www.

2.3. Autonomous ocean glider

Oceanographic data (potential temperature and
dissolved oxygen) were collected concurrent with
and spatially proximate to the most probable track of
the pelagic thresher shark by the King Abdullah Uni-
versity of Science and Technology (KAUST) sus-
tained glider line at 22.2° N (see the Supplement).
The glider transect extends from a point ~20 km west
of the coast (beyond the coastal reefs) to approxi-
mately 100 km offshore, within Saudi Arabia’s exclu-
sive economic zone (see Fig. 1).

2.4. Time-at-depth, -temperature, and -oxygen

Time-at-depth (TAD), time-at-temperature (TAT),
and time-at-oxygen (TAO, based on concurrent oxy-
gen observations collected by the glider) were calcu-
lated with the proportion of time spent in each depth,
temperature, and dissolved oxygen bin. The 75 s res-
olution time series data were classified into daytime
(sunrise to sunset) and nighttime (sunset to sunrise)
categories to assess diel changes in depth distri-
bution. Proportions were calculated for each 24 h period
and then averaged to determine the mean daily and
nightly TAD, TAT, and TAO profiles. TAD and TAT
were calculated using tag data; TAO was estimated using the most proximate glider data (see the Supplement). These calculations excluded data from the days in which the shark exhibited irregular, post-release behavior due to tagging effects (11–13 January), as well as from the day preceding and the day of its inferred mortality (29–30 January).

2.5. Occupation of hypoxic waters in the mesopelagic zone

The inclusion of in situ contemporaneous dissolved oxygen data from an autonomous ocean glider is rare in telemetry studies; most do not include oxygen data and those that do typically use climatological model outputs or ship-based CTD-O2 profiles from a limited number of sites (Coffey & Holland 2015). With the glider-recorded dissolved oxygen measurements aligned to the most probable track, we compared the shark’s occupation of low oxygen conditions relative to their prevalence in the water column. We used the 3 categories of hypoxia defined by Hofmann et al. (2011) (upper thresholds in ml O2 l⁻¹: A: mild hypoxia: 2.4; B: hypoxia: 1.4; C: severe hypoxia: 0.5), as well as a fourth category for non-hypoxic waters. We analyzed data exclusively from the mesopelagic zone (>200 m depth), which is where low oxygen conditions occur in the Red Sea.

2.6. Light comfort zones of acoustic scattering layers

The Red Sea exhibits 3 mesopelagic acoustic scattering layers that occupy distinct light comfort zones (Røstad et al. 2016), and thus adjust their depth distribution in response to changes in downwelling irradiance (Kaartvedt et al. 2017). To estimate the depth distribution of these scattering layers during the study period, we used above-surface light measurements in concert with an empirically derived light attenuation equation to predict the depths of the isolumens that define the light comfort zone boundaries of each layer (see the Supplement).

3. RESULTS

The most likely track estimate identified movement towards the southwest in waters <1000 m bottom depth (Fig. 1, see the Supplement). The depth–time series data from the shark suggested a period of irregular post-release behavior during the first 1.5 d after release, followed by a regular pattern of normal diel vertical migration for 15 d (Fig. 2). Eighteen days into the deployment, the shark exhibited erratic but vertically less extensive movements prior to an inferred mortality event the following day in which the fish approached the surface prior to sinking to 649 m depth, where the tag remained for 17 h before initiating a mortality related pop-off and ascending to the surface (Fig. 2). During the 15 d period of normal diel vertical migration behavior, the shark vertically migrated from mesopelagic to epipelagic waters at dusk and did the reverse at dawn (Fig. 2). Migrations among these 2 zones were largely direct and uninterrupted, whereas movements within these zones consisted of repeated descents and ascents over a comparatively limited depth range (individual displacements were typically <40 m; Fig. 2). The pelagic thresher shark occupied significantly deeper...
waters during the day (mean: 257 m) than at night (mean: 106 m) (Welch’s 2-sample t-test: $t = 139.2$, $p < 0.0001$). On average, the shark spent 85% of the day at 200−300 m and 84% of the night at 50−150 m (Fig. 3A). While largely restricting its overall depth distribution to 50−300 m, the shark was recorded conducting a single descent to 632 m which represented the maximum depth observed during this deployment.

Correspondingly, the mean temperature experienced by the pelagic thresher shark during the daytime (22.1°C) was significantly colder than during the nighttime (24.2°C) ($t = −187.6$, $p < 0.0001$). On average, the shark spent 97% of the day in waters $\leq$22.5°C and 89% of the night in waters $>22.5°C$ (Fig. 3B). Maximum changes in temperature experienced by the shark in each 24 h period were $\leq$4.2°C (mean ± SE: 3.4 ± 0.2°C). The pelagic thresher shark occupied an overall temperature range of 21.6−26.1°C during the deployment.

Fig. 3. Mean (±1 SE) (A) time-at-depth, (B) time-at-temperature, and (C) time-at-(glider-recorded)-oxygen by diel period. White: daytime; black: nighttime. Depth and temperature data come from the pop-up satellite archival transmitting tag; oxygen data were obtained by matching the pelagic thresher shark’s horizontal track and vertical movements to corresponding measurements from the autonomous ocean glider.
Parallel to the aforementioned diel patterns, the mean glider-recorded dissolved oxygen potentially experienced by the pelagic thresher shark during the daytime (1.4 ml O$_2$/l$^{-1}$) was significantly lower than during the nighttime (4.1 ml O$_2$/l$^{-1}$) ($t = -219.5$, $p < 0.0001$). The shark was estimated, on average, to have spent 86% of the day in waters with 0.8–2.5 ml O$_2$/l$^{-1}$ and 94% of the night in waters with $>2.5$ ml O$_2$/l$^{-1}$ (Fig. 3C). In the mesopelagic zone, the proportion of time the pelagic thresher shark occupied non-hypoxic, mildly hypoxic, hypoxic, and severely hypoxic waters was significantly different from their relative prevalence (Pearson’s $\chi^2$ test: $\chi^2 = 1803.6$, $p < 0.0001$). In particular, the shark appeared to occupy mildly hypoxic conditions more frequently (44.6% occupation vs. 9.1% prevalence) and hypoxic conditions less often (54.9% occupation vs. 86.5% prevalence), with the greatest disparity seemingly occurring in waters with $\leq$0.8 but $>0.5$ ml O$_2$/l$^{-1}$ (11.0% occupation vs. 57.6% prevalence) (Fig. 4). Negligible occupation of non-hypoxic and severely hypoxic conditions in the mesopelagic zone paralleled their minimal prevalence.

Based on ambient light levels, the 3 mesopelagic scattering layers were estimated to descend and progressively widen from dawn to noon, achieve maximum and widest depth distributions at noon, and ascend and progressively narrow from noon to dusk. The estimated depth distributions (at local noon) of the 3 mesopelagic scattering layers were 200–270, 400–580, and 580–800 m (assuming no bathymetric constraint) (Fig. 2A). During the daytime, the shark primarily occupied depths close to or within the estimated distribution of scattering layer 1 (Fig. 2A). In contrast, daytime overlap with the estimated distribution of scattering layers 2 and 3 was almost exclusively around crepuscular periods; the shark appeared to occasionally track these layers downwards in the mornings until encountering more hypoxic waters and sometimes descended around dusk to intercept them during their upwards migration (Fig. 2A,C). Furthermore, the shark’s only potential midday overlap with scattering layers 2 and 3 occurred outside of the most hypoxic waters at the bottom of layer 2’s and top of layer 3’s estimated distributions around 600 m (Fig. 2A,C).

4. DISCUSSION

The observed behavior of the pelagic thresher shark switching from a deeper daytime to shallower nighttime distribution (Fig. 2) is consistent with the normal diel vertical migration behavior observed in the common thresher shark (e.g. Cartamil et al. 2011) and bigeye thresher shark (e.g. Weng & Block 2004). Among juveniles of these 3 congeners, the daytime distribution of the pelagic thresher shark we tagged (predominantly $>200$ m; Fig. 3A) was more similar to that of the bigeye thresher shark (which almost exclusively occupies mesopelagic waters during the day; Coelho et al. 2015) than to that of the common thresher shark (which remains in epipelagic waters; Cartamil et al. 2011, 2016). While this intrageneric comparison is confounded by the disparate oceanographic conditions of the underlying studies (which were conducted in the Red Sea, tropical eastern North Atlantic, and subtropical eastern North Pacific, respectively), the patterns align with the physiological differences among the alopiid species. The pelagic and bigeye thresher sharks both likely exhibit cranial endothermy because they each contain orbital retia mirabilia (vascular structures akin to a counter-current heat exchanger; Weng & Block 2004), whereas the common thresher shark is the only alopiid that exhibits endothermy within centrally positioned red myotomal muscle (Sepulveda et al. 2005, Patterson et al. 2011). Thus, the potential warming of the eyes and brain of pelagic and bigeye thresher sharks may expand their depth niche further into the mesopelagic zone (Weng & Block 2004), while the centralized warming of the common thresher shark may expand its regional niche into cold-temperate latitudes (Patterson et al. 2011).

The extent of normal diel vertical migration by the individual in this study was seemingly not constrained by temperature in the Red Sea (Fig. 2A,B).
Daily changes in temperature experienced by the pelagic thresher shark from the surface to its deepest descent were always ≤4.2°C, consistent with the atypical oceanographic conditions of the Red Sea in which the water is at or near the notably warm minimum temperature of 21.6°C from ~200 m down to the deepest point of the basin (Yasuhara & Danovaro 2016, Zarokanellos et al. 2017). This relatively small vertical gradient in temperature during normal diel vertical migration of the pelagic thresher shark strongly contrasts with those exceeding 10, 15, or even 20°C experienced by different pelagic shark and fish species in other ocean basins (e.g. bigeye thresher shark, Coelho et al. 2015; black marlin and fish species in other ocean basins (e.g. bigeye tuna Thunnus obesus (Moteki et al. 2001, Varghese et al. 2014). The Red Sea exhibits 3 stratified mesopelagic scattering layers during the daytime; scattering layer 1 — the shallowest layer — occurs above the oxygen minimum zone and is separated by an acoustic void from the deeper scattering layers 2 and 3, which are adjacent to each other and occur within and below the oxygen minimum zone, respectively (Klevjer et al. 2012, Dypvik & Kaartvedt 2013). The pelagic thresher shark tagged in this study primarily remained above the oxygen minimum zone during the daytime where it overlapped with scattering layer 1 (Fig. 2A), which largely contains sternopytychid fishes (Dalpadado & Gjosaeter 1987, Klevjer et al. 2012). The shark possibly interacted with scattering layers 2 and 3, however, by tracking them downward during their dawn descent or descending to intercept them during their dusk ascent, with the vertical extent of these crepuscular interactions mostly restricted to waters above or near the upper boundary of the oxygen minimum zone. Although rare, daytime forays below the oxygen minimum zone may enable the shark to further overlap with these deeper scattering layers containing phosichthyid and myctophid fishes (Dalpadado & Gjosaeter 1987, Dypvik & Kaartvedt 2013) but possibly also demersal fishes when in neritic waters (Rosas-Luis et al. 2017).

Larger squid have also been documented in numerous studies as being an important part, or even the majority, of the diet of pelagic thresher sharks (Rosas-Luis et al. 2017, González-Pestana et al. 2019). In the Red Sea, patches of what are thought to be squid Sthenoteuthis spp. occur primarily at 1100−1300 m during the day (Kaartvedt et al. 2020) — far outside of the observed depth range of the pelagic thresher shark in this study. Trophic interactions between this pelagic thresher shark and squid may have occurred at night when both underwent normal diel vertical migration into epipelagic waters (Kaartvedt et al. 2020, this study) but it is unclear what prey species the shark targeted during this time because nearly all mesopelagic biomass in the Red Sea ascends to <200 m depth at night (Klevjer et al. 2012).

While seemingly curtailed by more hypoxic conditions, the deep movements of the tagged pelagic thresher shark are in accordance with the species’ trophic niche similarity to other predators foraging on small mesopelagic fishes, such as swordfish and bigeye tuna Thunnus obesus (Moteki et al. 2001, Varghese et al. 2014). The Red Sea exhibits 3 stratified mesopelagic scattering layers during the daytime; scattering layer 1 — the shallowest layer — occurs above the oxygen minimum zone and is separated by an acoustic void from the deeper scattering layers 2 and 3, which are adjacent to each other and occur within and below the oxygen minimum zone, respectively (Klevjer et al. 2012, Dypvik & Kaartvedt 2013). The pelagic thresher shark tagged in this study primarily remained above the oxygen minimum zone during the daytime where it overlapped with scattering layer 1 (Fig. 2A), which largely contains sternopytychid fishes (Dalpadado & Gjosaeter 1987, Klevjer et al. 2012). The shark possibly interacted with scattering layers 2 and 3, however, by tracking them downward during their dawn descent or descending to intercept them during their dusk ascent, with the vertical extent of these crepuscular interactions mostly restricted to waters above or near the upper boundary of the oxygen minimum zone. Although rare, daytime forays below the oxygen minimum zone may enable the shark to further overlap with these deeper scattering layers containing phosichthyid and myctophid fishes (Dalpadado & Gjosaeter 1987, Dypvik & Kaartvedt 2013) but possibly also demersal fishes when in neritic waters (Rosas-Luis et al. 2017).

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Our findings, based on an opportunistic, short deployment of a single individual, provide one of the first high-resolution views into the ecology of the pelagic thresher shark; however, more data is needed to determine if the behaviors we documented are...
representative of the species, particularly in different oceanic regimes and across other size classes. We have identified potential depths and diel periods in which pelagic thresher sharks may be most susceptible to fishery interactions (deep in the day and shallow at night), but more expansive tagging efforts are needed to confirm this pattern and inform regulations aimed at reducing interactions with this endangered species. Such research is especially important in the Arabian Sea and adjacent waters, where thresher sharks constitute some of the most common by-catch species encountered by commercial fishing fleets (Jabado et al. 2018), and is further highlighted by the high mortality rate of these sharks captured in such fisheries (e.g. Coelho et al. 2012). Effective fisheries management in the region could further be informed by long-term telemetry deployments (e.g. Oliver et al. 2019) that elucidate the species’ migration patterns and aggregation sites, as well as by genetic sampling (e.g. Cardeñosa et al. 2014) that determines population structure within the Indian Ocean and across the Indo-Pacific divide.

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