



FEATURE ARTICLE

Tracking the marine migration routes of South Pacific silver eels

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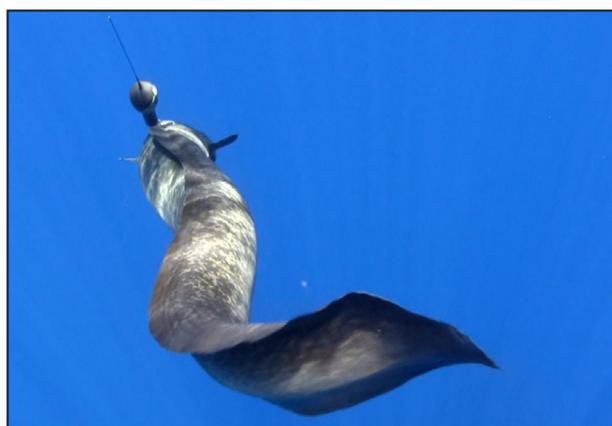
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ABSTRACT: It is still a mystery how catadromous eels find their way through the seemingly featureless open ocean to their spawning areas. Three catadromous Pacific eels (2 *Anguilla marmorata*, 1 *A. megastoma*) from the Archipelago of Vanuatu were tagged with pop-up satellite archival transmitters, and their migration tracks towards their presumed spawning area approximately 870 km northeast of the point of release were reconstructed in order to evaluate their movements in relation to oceanographic conditions. We used the timing of diel vertical migrations to derive the eels’ positions. The 2 *A. marmorata* exhibited steep-angled turns resulting in a zig-zag migration path along the east–west axis, while the *A. megastoma* took a relatively straight course towards the presumed spawning area. They migrated with a speed over ground of 21–23 km d⁻¹. In this region, the eastward flow of the South Equatorial Counter Current (SECC, ~5°–10°S) separates the westward flowing South Equatorial Current (SEC; ~0°–5°S and 10°–18°S) into 2 branches. During shallower nighttime migration depths around 150 m, eels crossed a variable flow field through the southern branch of the westward SEC with westward propagating mesoscale eddies and the eastward SECC, but stayed south of the stronger northern branch of the SEC, possibly increasing retention time of larvae within this area. The eels headed towards a tongue of high-salinity Subtropical Underwater (STUW). The eels did not move beyond a salinity front of 35.9–36.0 at a depth of 100–200 m, which may have provided cues for orientation towards the spawning area.

KEY WORDS: *Anguilla* · Migration routes · Diel vertical migration · Satellite telemetry · Spawning



Tagged eel released off Gaua Island, Vanuatu.

Photo: Robert Schabetsberger

1. INTRODUCTION

Since the epic spawning migrations of European eels *Anguilla anguilla* were reported during the 1920s, biologists have marveled at this more than 5000 km journey across the Atlantic Ocean to the Sargasso Sea (Schmidt 1922). Inspired by this landmark discovery, oceanic spawning areas for other anguillid species were found or narrowed down (Ege 1939, Jespersen 1942, Tsukamoto 1992, Kuroki et al. 2008, Miller et al. 2015), but even a century later the mystery remains about how eels orient and navigate through the seemingly featureless open ocean (Tsukamoto 2009, Righton et al. 2012, Westerberg 2014, Schabetsberger et al. 2016). Likely, they integrate information from various sensory systems such as vision, hearing, mechanoreception,

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pressure detection, and chemo-, electro-, and magnetoreception (McCleave et al. 1987, Tesch 2003, Tsukamoto 2009, Tsukamoto et al. 2011, Hunt et al. 2013), but the relative importance for orientation is unknown. The energetic constraints of this long-distance migration have been discussed as one possible cause for the drastic decline of temperate eel stocks, as mature silver eels are weakened by introduced parasites, toxic chemicals, and dams in their freshwater habitats and may not reach their spawning areas (Righton et al. 2012 and references therein).

For a better understanding of their orientation in the ocean, the migration routes of eels need to be tracked. The development of satellite pop-up archival transmitters (PSATs) provided first insights into the remarkable diel vertical migration behavior of eels, quickly descending from 100–300 m nighttime depth down to >600 m during the day (Aarestrup et al. 2009, Jellyman & Tsukamoto 2010, Béguyer-Pon et al. 2017, Higuchi et al. 2018 and references therein). However, global positioning does not work when the tags are submerged. Even though the PSATs are equipped with light sensors, the ambient light levels at these depths are too low to estimate light-based geolocation. Hence, the diel vertical migration behavior is used to estimate times of sunrise and sunset in order to estimate longitude and latitude. Temperature and depths may additionally be used to refine potential latitude, if strong enough temperature gradients are present (Béguyer-Pon et al. 2015a, Chow et al. 2015, Righton et al. 2016). Moreover, the migration routes of virtual eels have been simulated using numerical models (Béguyer-Pon et al. 2015b, 2016, Chang et al. 2016). Data collected for European eels suggested that they may not necessarily minimize the distance to reach the Sargasso Sea, but rather follow the reverse direction of the subtropical gyre that may have carried them as larvae towards Europe, potentially navigating along olfactory cues originating in the spawning area or oceanic cues imprinted during larval migration (Righton et al. 2016).

Comparatively little is known about the migrations of tropical and temperate eels in the Indopacific region (Aoyama et al. 2003, Kuroki et al. 2014). Six species (*Anguilla marmorata*, *A. megastoma*, *A. reinhardtii*, *A. obscura*,

A. australis, and *A. dieffenbachii*) live in the western South Pacific. During 2012 and 2013, 3 tropical anguillid species (*A. marmorata*, *A. megastoma*, *A. obscura*) departing from Gaua Island in Vanuatu were tagged with long-term pop-up satellite transmitters to follow their migrations (Schabetsberger et al. 2013, 2015). Up to 23% of caught eels were found to be putatively admixed individuals between *A. marmorata* and *A. megastoma* (Schabetsberger et al. 2015, Barth et al. 2020). Particularly, 3 eels (2 *A. marmorata* and 1 *A. megastoma*) out of 15 tagged fish exhibited long-distance migrations, with their tags surfacing more than 800 km away from release locations, popping up northeast of Gaua after 3–5 mo (Schabetsberger et al. 2015). While the 2 *A. marmorata* kept their tags until the pre-programmed release, the *A. megastoma* may have been eaten by a predator or it was weakened and died within the spawning area (Schabetsberger et al. 2015; Table 1). *Leptocephalus* larvae of both species (>25 d old) had been collected close to the pop-up location of our tags (Kuroki et al. 2008, 2020). These lines of evidence suggest that both species may spawn across this area.

Ocean current, salinity, and temperature fields may provide signposts for migrating eels. A distinct salinity maximum at about 150 m depth at the pop-up locations corresponding to the thermocline and the upper nighttime eel migration depths may act as a landmark for this spawning area (Schabetsberger et al. 2015). Data from Japanese eels *A. japonica* sug-

Table 1. Fish number (number in Schabetsberger et al. 2015), tag number, year, species, status of injury, total length (TL), body weight (BW), deployment duration, tag release, total distance covered, mean speed over ground, and pop-up position of 3 eels caught on Gaua Island and equipped with satellite tags

	Eel number		
	1 (1)	2 (6)	3 (8)
Tag	113291	128005	128006
Year	2012	2013	2013
Species	<i>Anguilla marmorata</i>	<i>A. marmorata</i>	<i>A. megastoma</i>
Capture	Hooking mark	Unhurt	Unhurt
TL (cm)	129.6	121.5	118.0
BW (kg)	5.7	4.8	3.8
Duration (mo)	3	5	3
Tag release	On time	On time	Premature (2 mo early)
Distance covered (km)	1952	3257	1717
Mean speed (km d ⁻¹)	23.2	21.0	22.9
Pop-up location	8.770°S, 173.016°E	9.233°S, 170.462°E	10.322°S, 174.614°E

gest multiple spawning during consecutive new moon periods at around this depth (Tsukamoto et al. 2011). The aim of the present study was to reconstruct the migration paths of 3 tropical eels and to understand their migration in relation to oceanographic conditions.

2. MATERIALS AND METHODS

Catching and tagging procedures have been described in detail by Schabetsberger et al. (2013, 2015). Briefly, the large female eels were caught by local fishermen snorkeling in the outflow of Lake Letas, Gaua Island, Vanuatu, in 2012 and 2013 (Decimal degree coordinates: 14.261°S, 167.604°E, Fig. 1). During the first year, the eels were hooked at their tails and pushed into handnets, while in the following year, the local fishermen had learned to catch the eels unharmed. The eels were first kept in a net within the river for several days, and later released 4 km offshore tagged with PSATs.

Eels avoided depths at which light was measurable by the tag sensors during their vertical migrations (Schabetsberger et al. 2013, 2015). As a consequence, no measurements were available from the light sensors to estimate the eels' geolocations. To overcome this limitation, we used the timings of the diel vertical migrations to estimate the times of sunrise and sunset to further derive longitude and latitude. In other words, we took advantage of the eels' eyes as light sensors that they use to avoid visual predators (Béguet-Pon et

al. 2015a, Chow et al. 2015, Righton et al. 2016). The proportions of data recovered from the 3 tags were 85, 49, and 92% for eels 1, 2, and 3, respectively (Fig. 2).

The next step was to estimate the sunrise and sunset times from the diel vertical migrations. The composite of diel vertical migration and the mean sunrise and sunset times indicated that the eels started to ascend to shallow water upon sunset but had started to descend to the deep layer before sunrise (Fig. 3). At sunrise, the eels were about halfway down on their descent. During the ascending and descending periods, depth changes in time were much greater than during daytime and nighttime when eels tended to undergo less distinct vertical movements. Therefore, the depth gradients were then used to estimate the ascending and descending periods. The composite depth gradient showed that eels nevertheless continued up and down movements during both daytime and nighttime (Fig. 4). Due to restricted battery life and size limitations of transmitted data packets, temperature and depth readings are compressed before they are transmitted to Argos satellites. If a fish dives more than 166.8 m or ascends more than 172.1 m in a 1 h period, then the minimum and maximum depth delta limits are transmitted. The same holds true if the temperature readings differ beyond a predetermined but variable threshold. Delta-limited depth and temperature records may not capture the actual extent of steep vertical movements and rapid temperature variations.

In order to judge the depth gradient more accurately, the 45 min (3 time step) running mean was calculated first (Fig. 4B). Sunrise and sunset fell into the 2 steep gradient periods (Fig. 4B). They were defined as Sunset: the beginning of the steep positive gradient and Sunrise: median of the steep negative gradient (Fig. 4B).

The periods of steep positive and negative gradients for sunset and sunrise were defined as the periods when the gradient was greater than the gradient before sunset (13:00–15:00 h Local Solar Time, LST, averaged) and before sunrise (01:00–03:00 h LST averaged), respectively. Using the depth gradients was intuitive, as they directly reflected the ascending and descending movements. The next step was to estimate local midnight time based on derived sunrise and sunset times, which then could be used to further estimate longitude following Hill & Braun (2001). The

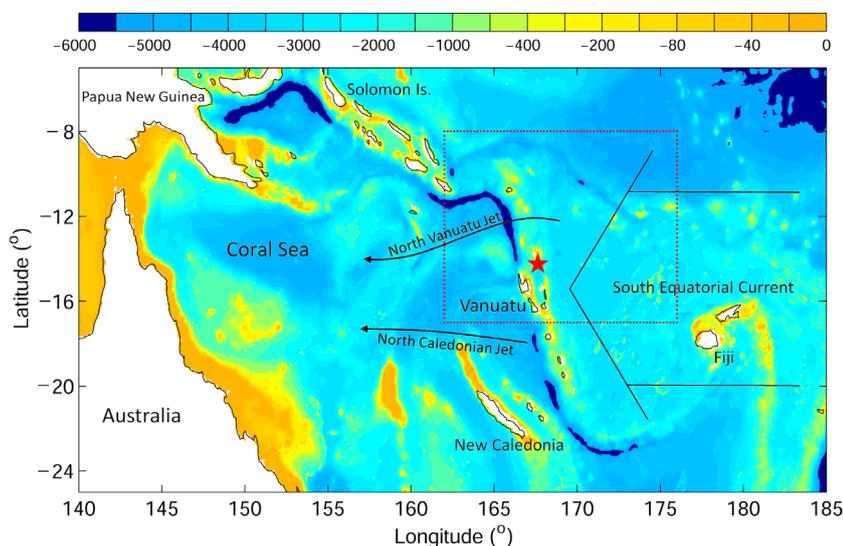


Fig. 1. Bathymetry (color, m) in the western South Pacific. The dotted box shows the study region, and the red star marks the release location. Arrows indicate the major ocean currents

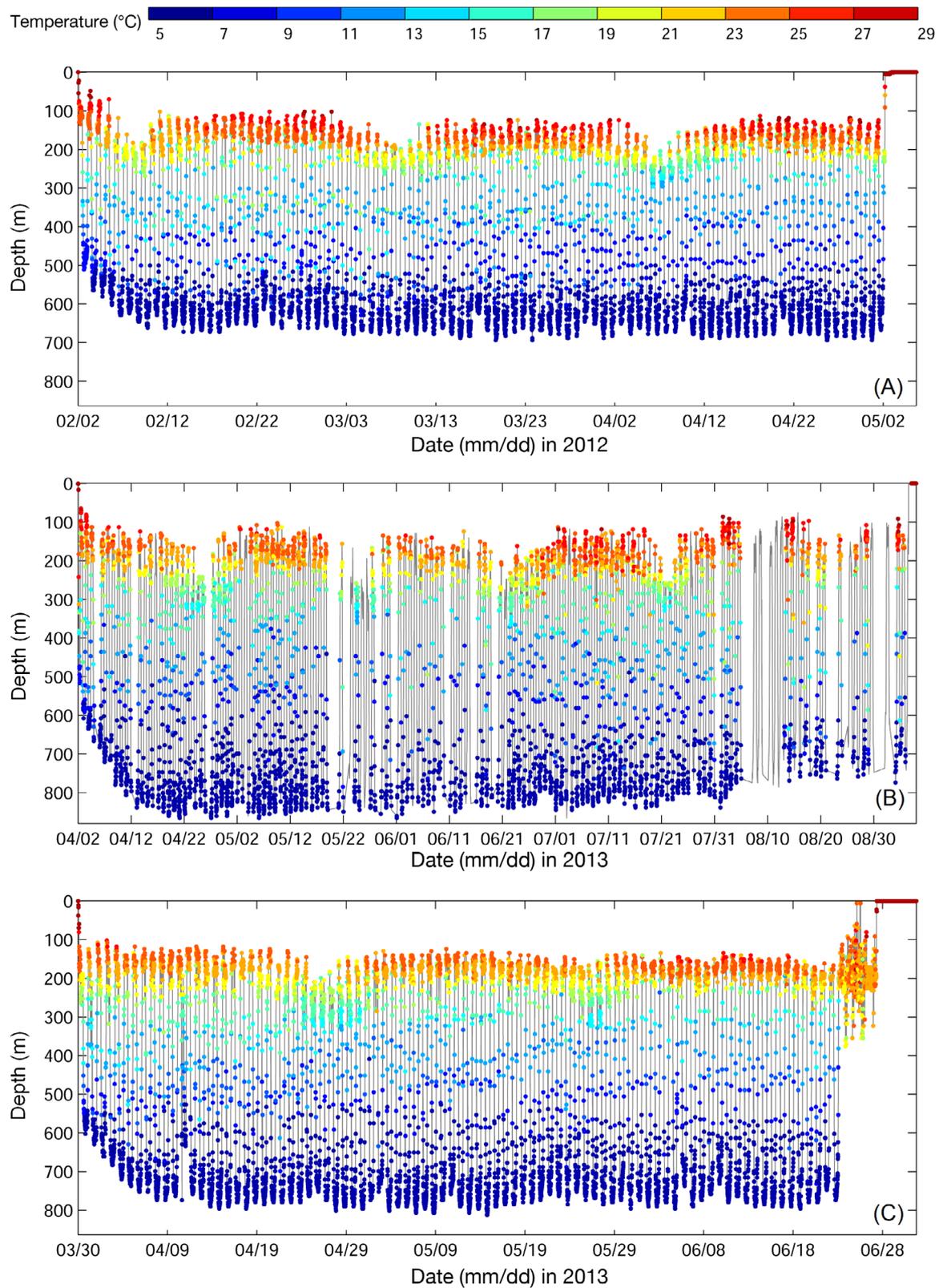


Fig. 2. Vertical migration of Eels (A) 1 (*Anguilla marmorata*), (B) 2 (*A. marmorata*), and (C) 3 (*A. megastoma*) with the temperatures (°C) experienced by the eels shown on the color bar

local midnight time (Eq. 1) and the longitude (Eq. 2) were estimated as:

$$\text{Midnight (h)} = \text{Sunset (h)} + \frac{(\text{Sunrise (h)} + 24 - \text{Sunset (h)})}{2} \quad (1)$$

$$\text{Longitude} (^{\circ}\text{E}) = 360 - 15 (\text{Midnight (h)}) - \frac{\text{equation of time (min)}}{4} \quad (2)$$

in which midnight time used for estimating longitude followed UTC hours, and equation of time (Hughes

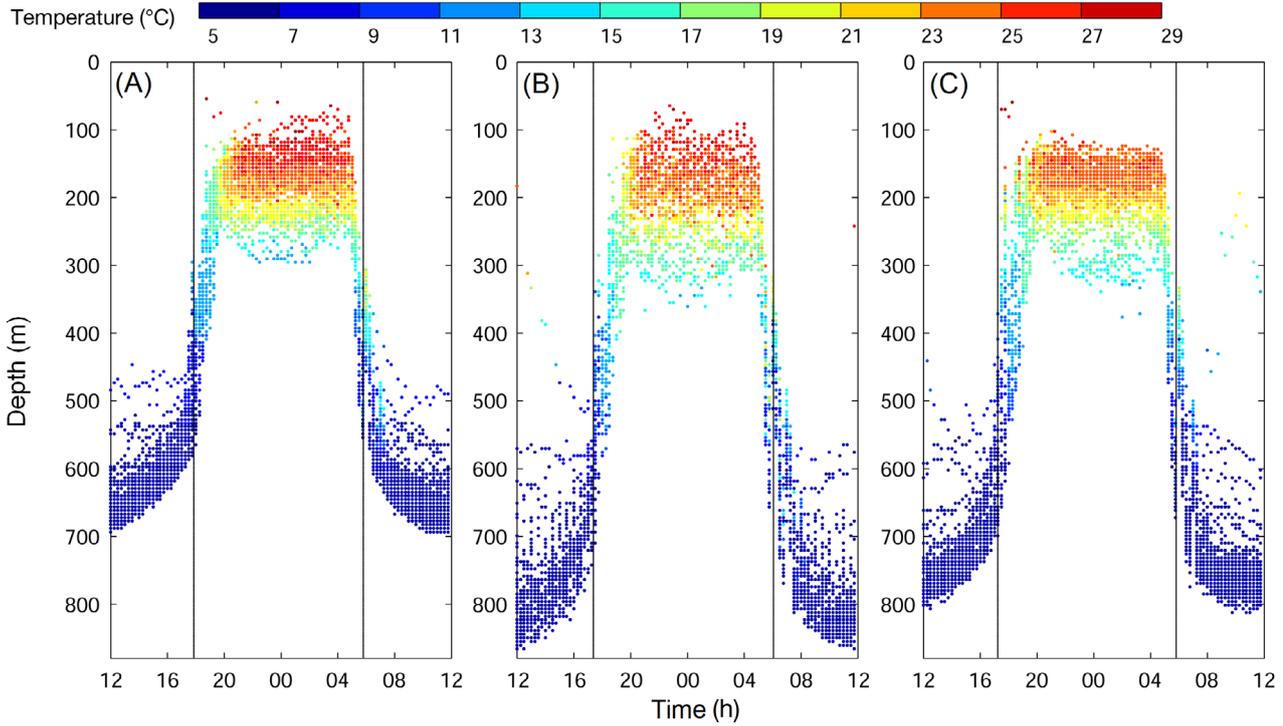


Fig. 3. Diel vertical migrations and the along-path temperature (color, °C) for Eels (A) 1 (*Anguilla marmorata*), (B) 2 (*A. marmorata*), and (C) 3 (*A. megastoma*). Vertical lines show the averaged sunset and sunrise over the migration period

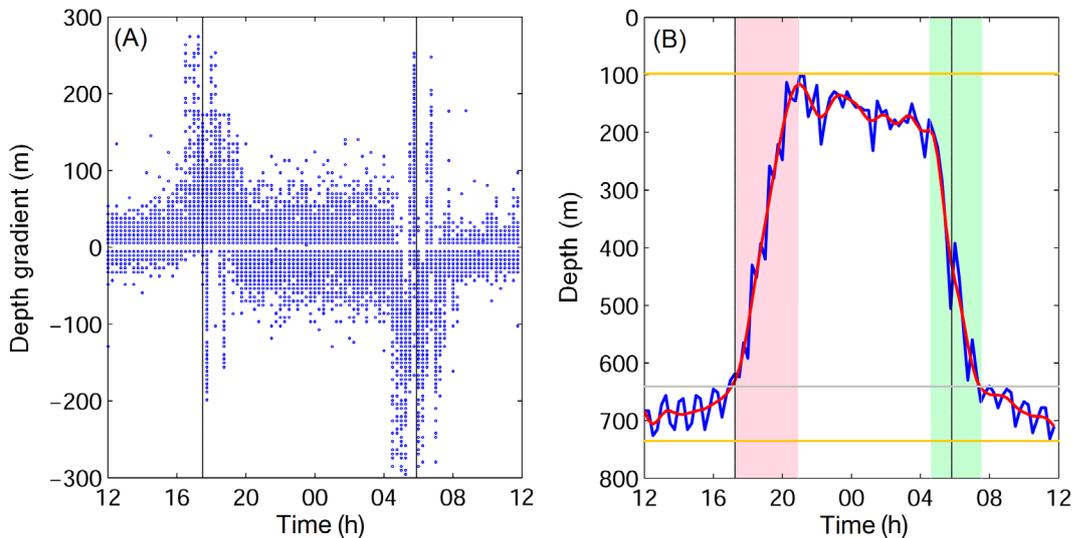


Fig. 4. (A) Depth gradient and (B) example of daily vertical migration from Eel 3 (*Anguilla megastoma*) on 4 April 2013. Positive and negative gradient represents ascending and descending, respectively. The red curve in (B) is the 45 min (3 time steps) running average. Pink and green shading indicates increased positive (ascending) and negative (descending) gradients, respectively. The 2 vertical lines show sunrise and sunset. The grey horizontal line marks the daytime minimum depth; the 2 yellow lines are the daily maximum and minimum depths

et al. 1989) was derived using Matlab toolbox (www.mathworks.com/matlabcentral/fileexchange/32793-equation-of-time).

Temperature gradient fitting with reanalysis model data was applied to estimate the latitude of American eels departing from east of Nova Scotia, Canada (Béguer-Pon et al. 2015a). However, the temperature gradient was much greater in this mid-latitude region ($0.7\text{--}1.0^\circ\text{C } 100 \text{ km}^{-1}$), whereas the tropical ocean is generally warmer and exhibits a relatively small temperature gradient ($<0.1^\circ\text{C } 100 \text{ km}^{-1}$). Our observation also revealed little change in temperature during daytime or nighttime throughout the tracking period (Fig. 2). Therefore, the temperature gradient could not be used to estimate latitude for migrating tropical eels. We also tried to derive latitude from day lengths (Hill & Braun 2001) but failed due to large variations ($>10^\circ$). Hence, we assumed that latitude decreased linearly with time, or, in other words, that the eels constantly swam northward from release to pop-up location. Since most data points were available in 15 min intervals, we used ± 7.5 min to estimate the error for sunrise and sunset times. This led to $\pm 1.875^\circ$ error deviation when substituted into Eqs. (1) and (2). In a few cases, the time interval increased to 30 or even 45 min. Due to uncertainties of estimated sunrise and sunset times, we applied smoothing over a 15 d period, after which swimming speeds and trajectories approached stable values (rate changes $<1\%$ after 12–15 d smoothing).

The ocean circulation model uses the operational Mercator global ocean analysis and forecast system from Copernicus Marine Environment Monitoring Service (CMEMS). It provides the 3-dimensional currents and hydrological fields that were used in showing the oceanic condition in the present study. The CMEMS is a global model, with a horizontal resolution of $1/12^\circ$ and 50 vertical layers and was constructed based on Nucleus for European Modelling of the Ocean (NEMO). CMEMS covers the period from 2007 to the present, and the data during the tracking period for the 3 eels in 2012 and 2013 were used in this study.

3. RESULTS

3.1. Migration routes and swimming behavior

The 3 female eels generally took a northeastward direction and headed towards the final pop-up locations (Fig. 5). However, both *Anguilla marmorata* (Eels 1 and 2) exhibited 4–5 steep angled turns

resulting in a zig-zag migration path along the east–west axis. Eel 1 showed this behavior during the first half of its journey, while Eel 2 started this 435–455 km east–west movement 805 km from the presumed spawning area. In contrast, the only *A. megastoma* (Eel 3) migrated for about 190 km away from the postulated target direction before it reversed its course and headed on a comparatively straight course for the presumed spawning area. The tag popped up prematurely after 3 mo and likely drifted westward during the end of the eel's journey (Fig. 2). The mean estimated distance covered was 1952 (Eel 1), 3257 (Eel 2), and 1717 km (Eel 3), which led to mean \pm SD traveling speeds over ground of 23.2 ± 17.3 , 21.0 ± 15.3 , and $22.9 \pm 11.8 \text{ km d}^{-1}$.

3.2. Oceanographic conditions

The 3 eels experienced different ocean conditions depending on the highly dynamic interannual changes in flow patterns in this region. They were exposed to a higher variability in temperature, salinity, and current fields during the night, compared to more stable conditions at greater depths during the day (Figs. 6 & 7).

Temperatures increased northward as the eels moved towards the potential spawning area. During nighttime (~ 180 m), they seemed to prefer temperatures around $22\text{--}25^\circ\text{C}$ (Fig. 6A–C; see Anims. S1–S3A in the Supplement at www.int-res.com/articles/suppl/m646p001_suppl/). During daytime ($\sim 650\text{--}800$ m), eels traversed a flat temperature gradient slightly increasing towards the potential spawning area traveling to $\sim 6.2^\circ\text{C}$ and $5.2\text{--}5.8^\circ\text{C}$ in 2012 and 2013, respectively (Fig. 7A–C; Anims. S4–S6A).

Eels headed towards the high-salinity core of the Subtropical Underwater (STUW) that propagates westward at their upper nighttime migration depth. In the potential spawning area, all 3 individuals seemed to prefer salinities around $35.9\text{--}36.0$ (Fig. 6D–F; Anims. S1–S3B). At the daytime migration depths, eels crossed a salinity gradient ascending south to north and did not move beyond a salinity of 34.5 (Fig. 7D–F; Anims. S4–S6B).

At their upper nighttime migration depth, the eels departed between 2 strong westward jets, the North Vanuatu and North Caledonia Jets (also see Fig. 1). After leaving these westward currents, they were exposed to a variable flow field of weak east- to westward currents ($< 0.1 \text{ m s}^{-1}$). Once they got to the potential spawning area at the border of the South

Equatorial Counter Current (SECC) and northern branch of the South Equatorial Current (SEC), the eels did not migrate into the stronger flow of

the westward SEC that reaches down to the eels' upper migration depths (Fig. 7G–I; Anims. S1–S3C). At their deep daytime residence, they experienced even weaker currents flowing either east- or westward (Anims. S4–S6C). During the last new moon period before pop-up, the eels experienced nighttime temperatures and salinities from 23.2–24.2°C and 35.9–36.0, respectively. They were exposed to weak east- and westward currents of $<0.05 \text{ m s}^{-1}$ (Table 2).

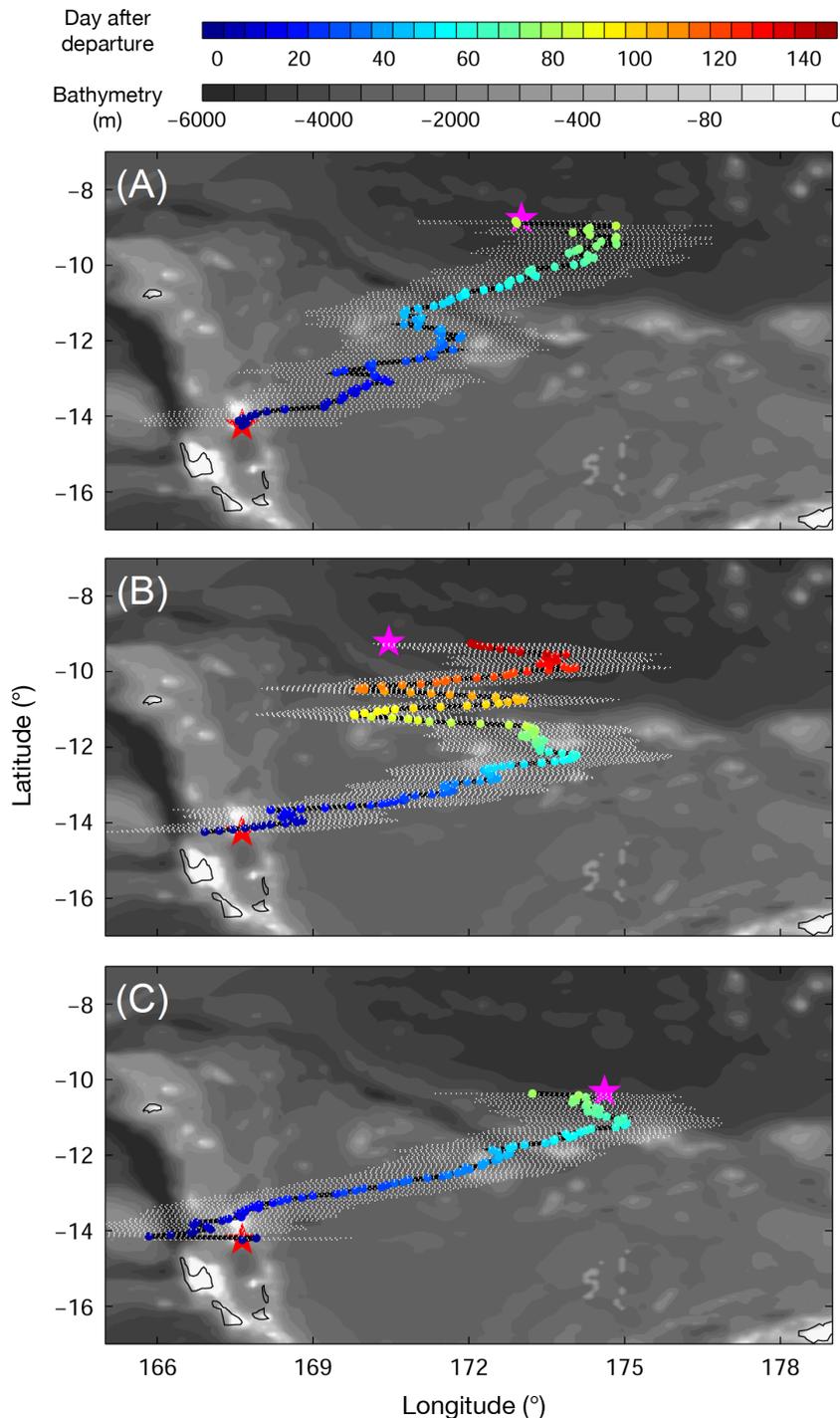


Fig. 5. Estimated migration path for Eels (A) 1 (*Anguilla marmorata*), (B) 2 (*A. marmorata*), and (C) 3 (*A. megastoma*). The color corresponds to days after departure from release locations. The red and magenta stars represent release and pop-up location, respectively. Grey shading shows the bathymetry (m). Black curves represent the estimated path of eels. White dots show the error of $\pm 1.875^\circ$

4. DISCUSSION

The 3 individual South Pacific eels likely were the first ever that carried satellite tags from near their freshwater habitat all the way towards their hypothetical spawning area located about 870 km northeast from the point of release. Although the final proof by catching ripe spawners, eggs, or preleptocephali is missing, several lines of evidence suggest that eels spawn in this region. Tags from both species popped up in within a mean \pm SD radius of about $167 \pm 49 \text{ km}$, irrespective of being attached for either 3 or 5 mo during consecutive years. Additionally, leptocephali of *Anguilla marmorata* (25–155 d old), *A. megastoma* (71–117 d), *A. obscura* (37 d), and *A. australis* (25 d) were caught in this region northwest of Fiji (Kuroki et al. 2008, 2020). By exploiting the distinct diel vertical migration behavior of the eels, we were able to coarsely reconstruct their migration paths towards this spawning area. The eels predictably descended before sunrise and ascended upon sunset, potentially avoiding predators hunting in shallower water during dawn and dusk (Chow et al. 2015, Hammerschlag et al. 2017).

The zig-zag movements of Eels 1 and 2 could have resulted from the uncertainty of our longitude estimates. The sampling interval of 15 min leads to a minimum error of 1.875° . Additionally, the timing of DVM may, to an

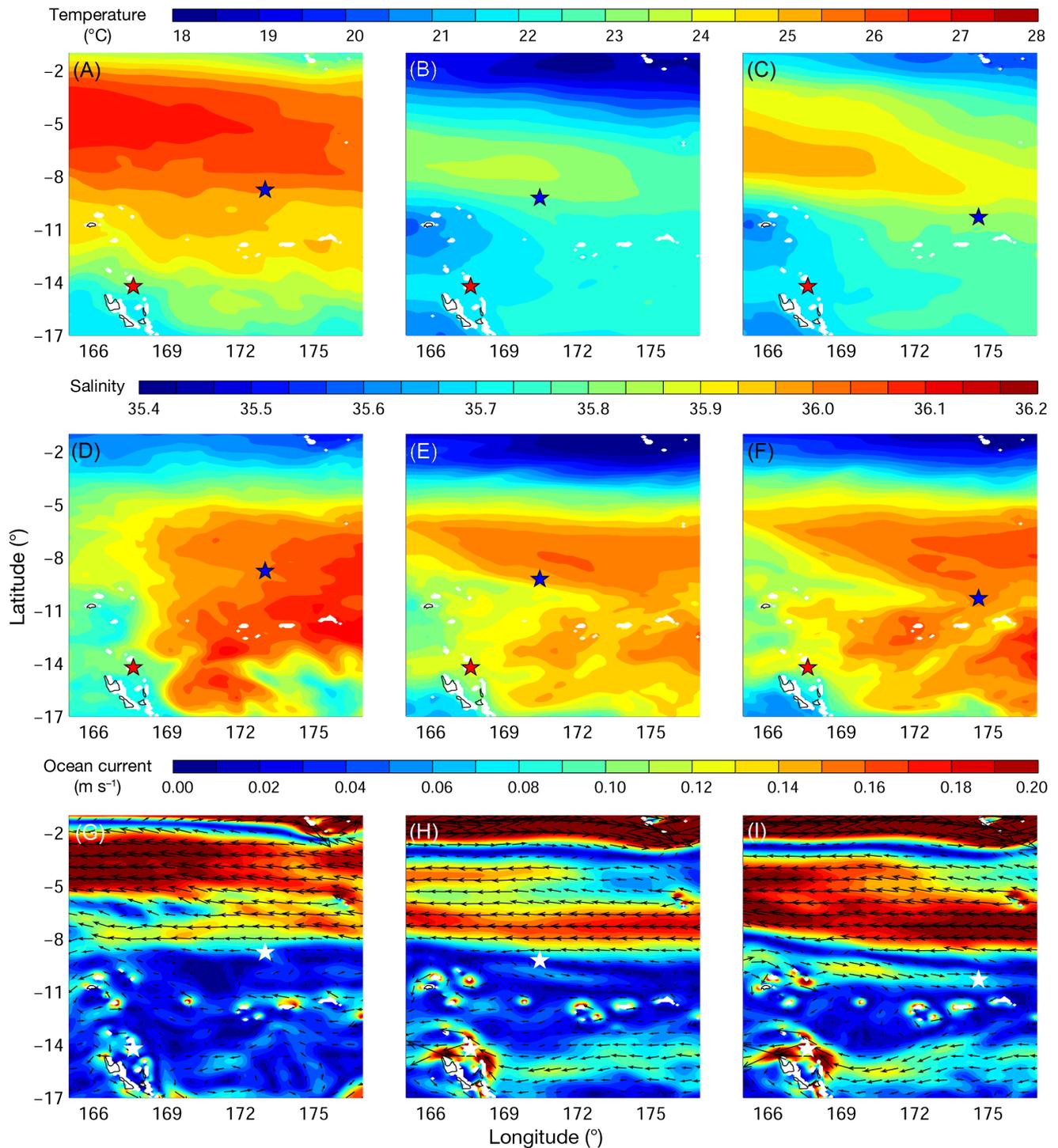


Fig. 6. Average (A–C) temperature ($^{\circ}\text{C}$), (D–F) salinity, and (G–I) ocean current fields (m s^{-1}) at median nighttime migration depths of eels experienced during their migration (\pm robust standard deviation, Hyslop & White 2009); left: Eel 1, *Anguilla marmorata*, 174 ± 30 m; middle: Eel 2, *A. marmorata*, 188 ± 45 m; right: Eel 3, *A. megastoma*, 177 ± 21 m). Red and blue (or white) stars represent release and pop-up location, respectively

unknown extent, shift with cloud cover, and our assumption of a constant northward movement is improbable, yet we were unable to solve these prob-

lems. Migrating silver eels could have been deflected by ocean currents, although they seem to be able to swim out against even stronger flow than seen in this

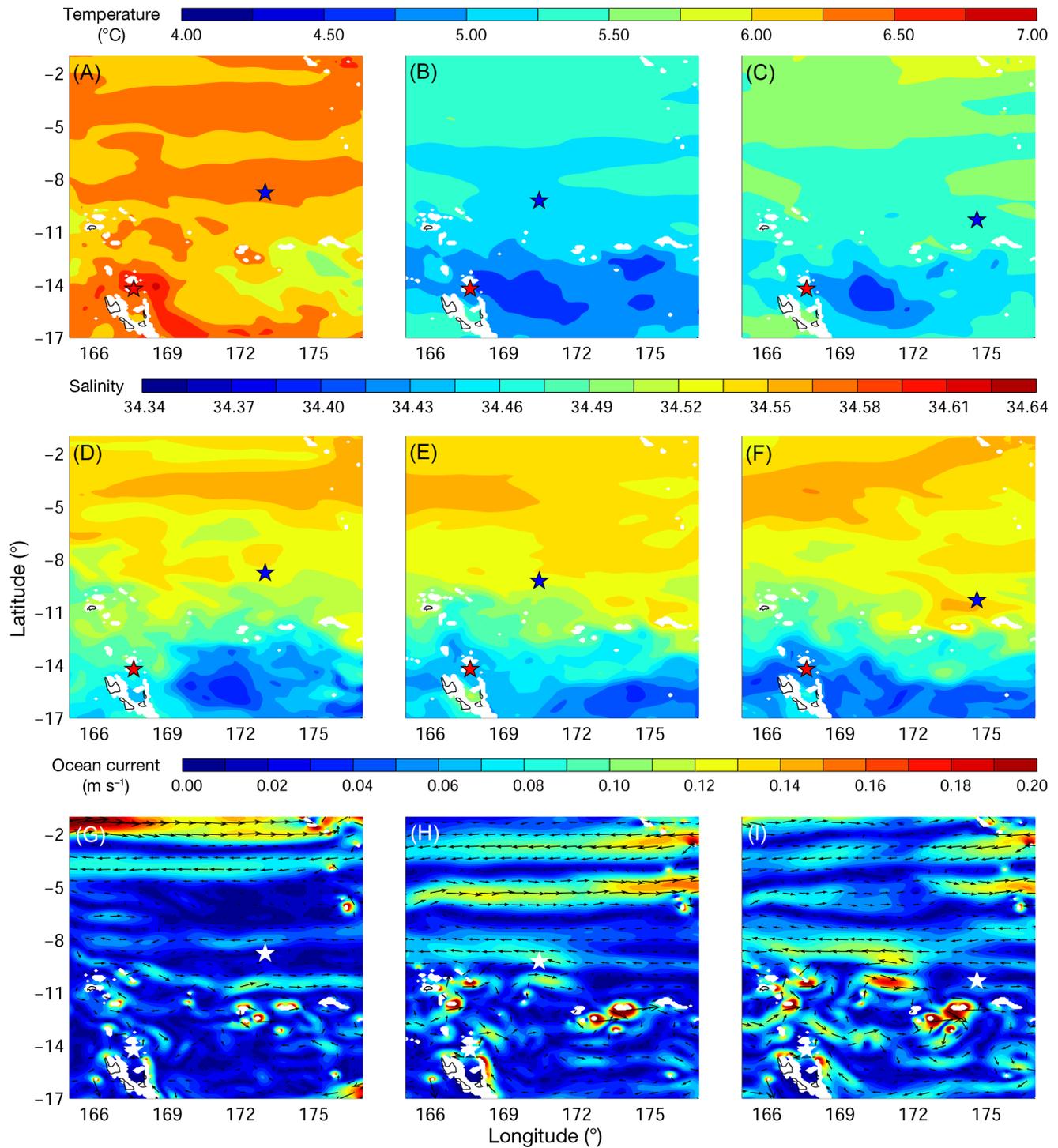


Fig. 7. Average (A–C) temperature ($^{\circ}\text{C}$), (D–F) salinity, and (G–I) ocean current fields (m s^{-1}) at median daytime migration depths of eels during their migration (\pm robust standard deviation; left: Eel 1, *Anguilla marmorata*, 653 ± 21 m; middle: Eel 2, *A. marmorata*, 806 ± 30 m; right: Eel 3, *A. megastoma*, 758 ± 21 m). Red and blue (or white) stars represent release and pop-up location, respectively

study (see Béguyer-Pon et al. 2016, Righton et al. 2016). Alternatively, the tracks may indeed reflect an active zig-zag searching behavior of eels for cues to

guide them along a pathway to a specific destination. The eels may take the risk of a prolonged journey in order to locate mates (see also Béguyer-Pon et al. 2017

Table 2. Oceanographic conditions experienced by the eels during nighttime (21:00–03:00 h) of the last new moon periods near the spawning area recorded by the tags. Salinity (S) and zonal (U) and meridional (V) velocities were extracted from the model. Numbers represent mean (SD) values. Temperature data are from the tags

	Eel number		
	1 (<i>Anguilla marmorata</i>)	2 (<i>A. marmorata</i>)	3 (<i>A. megastoma</i>)
Time (days since release)	78–83	123–128	73–77
Eel depth (m)	164.8 (18.6)	148.6 (25.5)	169.9 (14.6)
T (°C)	23.2 (2.7)	24.2 (2.0)	23.6 (1.8)
S	36.04 (0.003)	35.91 (0.040)	35.97 (0.019)
U (m s ⁻¹)	0.015 (0.016)	0.038 (0.021)	0.020 (0.019)
V (m s ⁻¹)	0.054 (0.003)	-0.040 (0.027)	-0.034 (0.020)

for changes in direction). Eel 2 seemed to follow the bathymetry along the Vitiaz Trench Lineament/Melanesian Border Plateau (Pelletier & Auzende 1996). As it could not reach the bottom (>2000 m), it may have tracked obvious magnetic anomalies along these features (World Digital Magnetic Anomaly Map; Dymont et al. 2020).

The animations (Anims.) show that the eels crossed a variable flow field towards the border of the eastward SECC and the westward northern branch of the SEC, but they did not seem to enter into the stronger flow of the SEC. The region where tags popped up may provide good conditions for larval growth and dispersal; several eddies were observed along the estimated migration routes (see Anims. S1–S3). The rotating and westward propagating features could trap and transport eel larvae, affecting their migration speed and direction (Chang et al. 2017). Thereby they could potentially also increase the retention time within the region. Depending on their residence depths, larvae growing in this area could drift westward or eastward. Genetic data collected throughout the western South Pacific suggest panmixia of both species (Gubili et al. 2019) and support the hypothesis that leptocephali hatched in this area could reach different archipelagos west or east of it.

The eels migrated across a high-salinity core of the STUW around 100–200 m depth that is formed by saltier water being subducted from the surface into the lower thermocline (Price 2001). This tongue of high-salinity water may provide stable water mass signatures or olfactory cues for orientation (Schabetsberger et al. 2015, Kuroki et al. 2020). The 3 tags popped up within latitudinal salinity and temperature gradients forming between the 2 opposite current systems of 35.9–36.0 and 23–25°C, respectively. Optimum salinities and temperatures for egg development in tropical eels have not been deter-

mined under laboratory conditions, but the values above roughly correspond to the most favorable conditions observed in temperate eels (salinity ~35; 20–25°C; Dou et al. 2008, Okamoto et al. 2009, Ahn et al. 2012, Unuma et al. 2012, Sørensen et al. 2016).

The eels reached the area with estimated migration speeds over ground (21–23 km d⁻¹) that were similar to estimates from temperate species (*A. rostrata*: 35–54 km d⁻¹, *A. dieffenbachii*: 15–31 km d⁻¹, *A. anguilla*: 2–51 km d⁻¹; Béguier-Pon et al. 2017 and references therein). All 3 eels exhib-

ited very regular and distinct diel vertical migrations and seemed unaffected by tagging, so they likely were in good physical condition and the speeds were likely natural. The negative effects of externally attached tags observed in smaller European eels may be reduced in these comparatively large and well-nourished tropical eels (Burgerhout et al. 2011, Methling et al. 2011). It also remains to be determined if more invasive tagging techniques applied during earlier studies could actually have caused accelerated escape movements >50 km d⁻¹.

Even though the magnetic sense would be sufficient to reach their destination (Durif et al. 2013), eels likely use a set of senses to first locate their general spawning area and then to find their mates within optimal conditions for reproduction. Since eels likely spawn at their nighttime migration depths in the shallower water (Tsukamoto et al. 2011), the oceanographic features there are likely to have greater importance for orientation and navigation than those during the day at deeper depths beyond 600 m where the eels may hide from predators and approach their physiological limits for movement. In these layers of the STUW, ripe eels may have to actively search for odor trails of individual conspecifics to find mates by following smell wafted down by the currents (Sillar et al. 2016). Some tropical eels seem to spawn throughout the year (Aoyama et al. 2003, Arai & Abdul Kadir 2017), and the numbers of spawners aggregating at one time may be small compared to temperate eels (estimated to be <500 spawners per spawning event; Pujolar & Maes 2016). Finding suitable mates in the vast ocean may require a risky and strenuous prolongation of the eels' spawning migration when they are nearing or have reached maturity.

In summary, the 3 eels exhibited regular diel vertical migrations and at least the 2 *A. marmorata*

seemed to swerve east or west while moving towards their final destination. They likely stopped before reaching the faster-flowing northern branch of the SEC and remained within salinity and temperature fronts. Shorter time intervals between measurements (larger data volume transmitted to Argos) would increase the accuracy of the position estimates from diel vertical migrations. Obviously, large tagging campaigns are needed to monitor movement patterns within the spawning area. In the future, tags with higher transmission rates and/or superior light sensitivity would provide more accurate estimates. With expected miniaturization and price reduction of tags, many eels could be equipped with pop-up satellite transmitters as well as acoustic tags and then potentially guide ship-based oceanographers to spawning events (see also Wysujack et al. 2014).

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