Clam distribution and subsurface hydrothermal processes at Chowder Hill (Middle Valley), Juan de Fuca Ridge

Anthony J. Grehan*, S. Kim Juniper

ABSTRACT: This study used seafloor imaging, near-surface sampling and drilling results to examine hydrological constraints on vent organism distribution and productivity in a sedimented hydrothermal setting at Middle Valley, Juan de Fuca Ridge in the northeast Pacific, where venting is focused around seafloor mounds. A vesicomyid clam bed on one of these mounds (Chowder Hill) was reconstructed from imagery acquired by the remotely operated vehicle ROPOS, using a new image enhancement/mosaicking system. The mosaic was fitted to a Universal Trans-Mercator (UTM) coordinate grid and a contour map of clam density and local bathymetry was derived from visual counts within grid squares and ROPOS navigation logs. Highest clam density occurred on a slightly raised area of seafloor in the upper-central portion of the clam bed, where sediment temperatures suggested hydrothermal flux to be greater than further downslope. Results from Ocean Drilling Program (ODP), College Station, Texas, USA, Leg 139 suggested that a local hydrothermal reservoir exists within Chowder Hill and that erosion of low-permeability surface sediments may be critical to allowing fluids to escape. A 1-dimensional advection-diffusion model was used to derive an estimate for H$_2$S supply to the clam bed from a subsurface reservoir, based on sediment temperature profiles and pore-water H$_2$S concentrations. Estimated H$_2$S flux (250 mol m$^{-2}$ yr$^{-1}$) would support a maximum chemosynthetic CO$_2$ fixation rate of 8.3 gC m$^{-2}$ yr$^{-1}$. More detailed in situ data are required to study links between local fluid flow variations and clam density, and to resolve near-surface processes that laterally delimit the fluid conduit beneath the clam colony.

KEY WORDS: Hydrothermal vents · Calyptogena · Mosaicking · Fluid flux

INTRODUCTION

Hydrothermal vent sites are characterized by irregular topographical and physicochemical features and extreme patchiness of animal distribution (e.g. Hessler et al. 1985, Chevaldonné & Jollivet 1993). A high degree of accommodation to environmental controls appears to be a predominant feature of vent communities (Hessler et al. 1985, Fustec et al. 1987, Tunnicliffe & Juniper 1990), although significant influences of biotic interactions on community composition cannot yet be discounted (e.g. Hessler et al. 1988). Understanding mechanisms by which environment influences vent community pattern-
Photographs and video imagery are a primary source of data for reconstructing benthic organism distribution and surface geological features at vents and seeps (e.g. Juniper & Sibuet 1987, Hessler et al. 1986). Recent developments in video capture and image processing technology for personal computers greatly increase the speed and ease with which image mosaic ‘maps’ can be produced. The application of computer-assisted mosaicking by MacDonald et al. (1989, 1994) to document spatial distribution of organisms around gas seeps in the Gulf of Mexico illustrates the potential of this technology for vent ecological studies. Synoptic mapping of temperature and chemical conditions at hydrothermal vents will also soon benefit from a recent technological development. Submersible flow injection chemical scanners have been used to probe the microenvironment around some vent species (Johnson et al. 1986, 1988, Sarrazin et al. 1993), and to map hydrothermal plumes (Massoth et al. 1995), and are a promising tool for vent field scale chemical mapping.

Reconstruction of seafloor features from submersible gathered data provides a 2-dimensional view of what is essentially a 3-dimensional hydrological and ecological problem. Subsurface processes that control hydrothermal fluid emission are understood in a descriptive sense, but since they occur beneath the floor of the deep ocean, direct observation is difficult and real 3-dimensional information on vent field hydrology is rare. Recent and planned scientific drilling operations by the Ocean Drilling Program (ODP), College Station, Texas, USA at hydrothermal vent sites provide unique opportunities for ecologists to add this third dimension to their view of processes determining community patterning. This paper follows up on a predrilling study of hydrothermal communities at Middle Valley, on the Juan de Fuca Ridge in the Pacific Ocean off the US/Canadian coast (Juniper et al. 1992). Here, we developed an approach to reconstruct a vesicomyid clam bed and its local geological setting, using imagery and samples collected by the remotely operated vehicle ROPOS and published information from ODP Leg 139. Particular emphasis was placed on near-surface processes controlling fluid supply to the clams. The paper also describes a Macintosh-based image processing and mosaicking system that we developed for this work, and discusses problems associated with mosaicking and image analysis.

**Site description**

At Middle Valley, a failed rift at the northeastern end of Juan de Fuca Ridge, venting occurs through several hundred meters of interbedded turbidite and hemipelagic sediment. The principal centre of present day hydrothermal activity in Middle Valley is the Dead Dog vent field (the ‘High Heat Flow Area’ in Juniper et al. 1992), where venting is concentrated around 5 to 18 m high sediment-covered mounds (Fig. 1). High temperature chimneys (up to 276°C) are restricted to mound summits. Diffuse low temperature flows (<40°C) that support microbial mats and symbiont-bearing bivalve communities (Calypogena spp., Solymya spp.) are found in basal and flank areas of active mounds (Juniper et al. 1992). The largest bivalve colony known is located on the lower northwestern slope of a 15 m high, 60 m diameter mound known as Chowder Hill (Fig. 1). The colony is dominated by a large symbiont-bearing vesicomyid clam designated Calypogena large (n. sp. 2) by Juniper et al. (1992). In the summer of 1991, Hole 858B of ODP Leg 139 was drilled to a depth of 32 m on the northeastern flank of Chowder Hill (Fig. 1), and several deeper holes were drilled nearby (Davis et al. 1992). Subsurface processes were investigated through analysis of physical and chemical properties of drill core material and downhole observations. Related piston coring, seismic and heat flow studies, and drilling at 3 other sites in Middle Valley provided vent field and regional scale information on the nature and consequences of hydrothermal circulation (Davis et al. 1992, 1994).

**MATERIALS AND METHODS**

**Image collection and navigation.** Images (both video and still photos) of the Chowder Hill site were collected by the ROPOS remotely operated vehicle during a 1992 joint Canada/US expedition to the Juan de Fuca Ridge aboard the NOAA ‘Discoverer’ (Embley & Franklin 1993). A total of 4 dives visited the clam bed on Chowder Hill (HYS-192, 193, 196 and 199), between June 27 and July 4. The bulk of the results discussed here are from detailed mapping carried out during dive HYS-199. During imaging transects in dive HYS-199, the ROPOS was flown laterally, facing the slope at a constant altitude with the Silicon Intensified Targetting (SIT) camera pointing vertically down. Lateral movement minimized resuspension of sediments over the target area, permitting repetition of imaging swaths without visibility loss.

Video imagery from the ROPOS black and white SIT and Osprey colour cameras was recorded in the industrial chrominance/luminance (Y/C) format (S-video). Colour still photos were taken on Kodak negative transfer film, using a Photosea 35 mm camera. Definition of the boundaries of the clam bed study area within a Universal Trans-Mercator (UTM) coordinate system was based on acoustic transponder navigation of the ROPOS, relative to differential Global Positioning System (GPS) positioning of the surface support vessel.
Image analysis and treatment. The sea-going image analysis system included a Macintosh IIc upgraded to a 100 MHz Power PC (48 MB RAM, 240 MB HD) with an onboard 24-bit, S-video capable colour image capture card (RasterOps 24TVX) with compatible software: Adobe Photoshop 3.0 (image capture and enhancement) and IPLab Spectrum 2.5.7 (image enhancement, sizing, rotation and mosaicking and on-screen measurement; Signal Analytics Corporation). Peripherals included a Dynatec RMD88 removable hard drive for storage of captured video images (up to 2 or 3 MB for 24-bit colour images) and an Apple CD-ROM 300 for viewing digitized still photos. On-line image capture from the ROPOS cameras was possible during dives, but most mosaicking work was done from recorded video. Recordings were initially reviewed using a paired Panasonic AG-5700 S-VHS VCR and high resolution monitor system enabling synchronized viewing of SIT and colour video. Selection and control of video sequences for image capture was facilitated by using a Panasonic AC-A570 editing board. Photographs (slides) were digitized commercially using the Kodak proprietary PhotoCD process.

![Image Analysis and Treatment](image)

Fig. 1. Adaptation of SeaMARC 1A sidescan sonar image of the Dead Dog vent field at Middle Valley, Juan de Fuca Ridge, illustrating locations of Chowder Hill and ODP Holes 858A-D. Acoustic reflectivity is generated by hydrothermal alteration and sedimentation. Hydrothermal mounds are marked by dark acoustic shadows on their eastern side. A re-entry cone is situated at Hole 858G. Original SeaMARC 1A image courtesy of J. Franklin, Geological Survey of Canada. Inserts: Top right: *Calyptogena* spp. in the Chowder Hill clam bed; attached anemones are more common on empty clam shells than on the living clam shown here. Image from grabbed video frame enhanced in Adobe Photoshop. Bottom right: location of Middle Valley on the Juan de Fuca Ridge.
Digitized video frames were reviewed after appropriate enhancement (brightness, contrast, sharpness) using Adobe Photoshop or IPLab Spectrum. Repetitive enhancement tasks were usually scripted with Spectrum, greatly speeding up image processing. Automated edge finding and object recognition, both based on pre-determined brightness criteria, could also be scripted in Spectrum.

**Mosaicking.** IPLab Spectrum was used to create a composite black & white image of the clam bed from SIT video frames selected from east-west transects (HYS-199). Beginning with a single pair of overlapping images, a mosaic was built up by fitting successive daughter images to the expanding parent image. For each pairing, at least 2 common objects in each image were selected on-screen using the registration tool in Spectrum. From these registration marks, Spectrum automatically calculated and performed the necessary scaling and rotation to fit the daughter image to the mosaic. While overlapping images taken from a constant altitude should theoretically fit together seamlessly, sizing and rotation was inevitably necessary to correct for minor altitude variations and vehicle yaw between successive images. The final merging of parent and daughter images was then performed in Spectrum with the mosaic function, using the same registration marks, or by exporting prepared daughter images to Photoshop where temporary lowering of opacity eased positioning onto the mosaic. Illumination and contrast in the completed mosaic were optimized in Photoshop, and the final image was reproduced on a Linotronic printer at 2400 dpi (dots per inch).

**Grid positioning.** Two navigational reference points were established at opposite ends of the clam bed during dive HYS-199. Each point corresponded to the mean UTM $X$, $Y$ position of the ROPOS vehicle during 5 min holds at the start and finish of an east-west video transect. Video imagery was then used to identify these 2 points on the final mosaic, where they were fixed as registration marks. Next, a 50 cm mesh UTM navigational grid was drawn using Aldus Freehand and imported into Spectrum where registration marks were placed on the $X$, $Y$ positions of the 2 reference points. The mosaic was then scaled and rotated to fit the navigational grid and the paired images were exported to Adobe Photoshop where the grid was overlaid on the mosaic.

**Density measurements.** Uneven illumination in our images prevented any meaningful experimentation with brightness-based automated object recognition for counting clams. Instead, counts were made directly by eye from high resolution photo and colour video images correctly scaled and positioned within the clam bed. This was accomplished by using the mosaic as a template to scale high resolution images and locate them within the UTM grid. A copy of the grid was then overlaid on the high resolution image and used to count clams. Count and position data were contoured with MacGridzo, using the $X$, $Y$ position of the centre of each counted image as the location of the data point.

**Geological observations and sampling.** Local geology around the clam bed was studied by reviewing video sequences from all dives on Chowder Hill. Temperature profiles were taken at 2 sites in the clam bed during dives HYS-192 (2 replicate profiles in upper clam bed) and HYS-199 (single profile in lower clam bed). Profiles were taken by first measuring temperature next to the sediment surface using a high temperature probe, and then inserting the probe vertically into the sediment, stopping at 7, 19 and 29 cm depth for readings. During dive HYS-192, the submersible collected 4 live clams at the site of the replicate temperature profiles. A push-core was taken next to the temperature profile site during dive HYS-199, where a PVC tripod marker was also deployed.

Local bathymetry for a 20 x 15 m area around the clam bed was determined from $X$, $Y$, $Z$ data in ROPOS dive logs, using only data points where ROPOS was sitting on the bottom for at least 2 min. Average $X$, $Y$ position for each time interval was used to place each depth point in space for contouring with MacGridzo.

**RESULTS**

**Clam bed map**

The final image composite with the overlaid navigational grid is shown in Fig. 2a. Image resolution was reduced by over-illumination in the centre of the clam bed where reflection from shell debris and bacterial mat saturated the SIT camera. Some recovery of detail was achieved through enhancement, but much textural information was masked by the high reflectivity. Overall image quality was still sufficient for the intended purposes of outlining the clam bed and acting as a base map to locate high definition images of the clams. The clam bed was situated on the northeastern corner of Chowder Hill between 2414 and 2415 m and generally ran along slope, covering a surface area of approximately 28 m$^2$. The locations of the 2414 and 2415 m depth contours within the clam bed are shown in Fig. 2b.

**Density measurements**

Clam density distribution over the entire bed is contoured in Fig. 2b. Highest densities were encountered in the central and upslope areas. Downslope, clam densities gradually fell off as one approached the
of the mound. The platform was strewn with boulders and cobble-sized chunks of indurated mud rich in pyrite and hydrocarbons. The cobble-sized pieces may have been fragments of a surface crust broken up by clam movement. The presence of the platform appeared to be reflected in the northward extension of the 2415 m depth contour in the central area of the clam bed (Fig. 2b). The zone of highest clam density overlaid this locally upraised area of seafloor (Fig. 2b).

Temperature profiles are illustrated in Fig. 3. Although all profiles were very crudely constrained, it is worth pointing out that the 2 profiles taken in the upper portion of the slope suggested greater fluid flow rates, compared to the downslope site. This corresponded to the greater estimated density of clams in the upslope portion of the field. The temperature gradient suggested by these profiles (ca 18°C m⁻¹) was roughly twice the background value in the vent field away from the mounds and similar to the highest conductive values observed by Davis & Villinger (1992). The more rapid temperature drop in the upper few cm of the HYS-197 profiles may have reflected the entrainment of seawater in the rubbly surface layers in this area of the mound.

The push-core taken by ROPOS at the downslope site was analyzed for pore water chemistry. Pore fluids were extracted by centrifugation of pooled sediments from 0 to 4 and 4 to 8 cm depth intervals. Pore fluid H₂S values from Butterfield et al. (1994) are given in Fig. 4.

**DISCUSSION**

**Clam colonies and sulfide supply**

Vesicomyid clam colonies are found in both vent and seep environments in the deep sea, wherever the supply of H₂S is sufficient to support chemosynthesis by their endosymbionts, and where there is a suitable substratum (Kennish & Lutz 1992). Sediments receiving a diffuse supply of reducing fluids are the most common substratum colonized by these clams (Kennicutt et al. 1985, Sibuet et al. 1988, Juniper et al. 1992), although hemipelagic mud of the seafloor surrounding Chowder Hill. There were an estimated 200 clams in the bed, of which an estimated 150 were in the upright 'living' position, as determined from examination of still photos. Highest densities encountered in quadrats were 20 ind. m⁻². Distribution was discontinuous, giving average densities of about 5 ind. m⁻². Shell length of sampled clams ranged from 7.0 to 18.1 cm and maximum shell width was 3.8 to 7.3 cm, yielding respective means of 14.5 and 6.3 cm (n = 4).

**Local geology**

Relative to the slope and the surrounding seafloor, the clam colony appeared to be situated on and around a platform produced by slumping or localized inflation.
Fig. 3. Temperature profiles in Chowder Hill clam bed from data collected with high-temperature probe on ROPOS remotely operated vehicle.

certain basalt terrains can also be exploited (Hessler et al. 1985). Colony size and relative abundances of living and dead clams appear to be linked to site longevity and constancy of fluid supply (Juniper & Sibuet 1987).

Adequate supply of sulphide is obviously of critical importance to the clams, although low ambient levels can be compensated by an ability to concentrate sulphide (Arp et al. 1984). The upper limits to clam colonization may be set by the animals' ability to detoxify H₂S. Fiala-Médioni et al. (1993) indicate that vesicomyid clams do not colonize sites where pore-water H₂S concentrations exceed 1 mM. Species-specific limits in terms of ambient H₂S levels and resupply rates are poorly understood, although there is some recent evidence for environmental control of composition and density of clams within colonies and the overall 2-dimensional shape of the colony, as discussed below.

Some workers have classified cold seep clam colonies based on colony morphology, clam size and clam density (e.g. Sibuet et al. 1988, Henry et al. 1992) and related these characteristics to environmental variables. Relevant to this study is the relationship between clam size and density and fluid flow velocity and flow pattern determined by Henry et al. (1992), whose classification scheme described a 'Type C' colony as being composed of large half-buried clams at low density (30 ind. m⁻²) that co-occur with white bacterial mats, supported by slow seepage (<10 m yr⁻¹) of H₂S rich fluid. The Chowder Hill clam bed shared similarities with the 'Type C' colony, both in clam size and density. The thermal gradient at Chowder Hill was, of course, much steeper than that observed by Henry et al. (1992) in a subduction zone setting, as a result of both conductive and advective heat flow from a shallow, high-temperature reservoir, as discussed below. The Chowder Hill clams generally appeared to be half-inserted in the sediments, and with an average shell length of 14.5 cm, most should have been in direct contact with pore fluids in the sampled 4 to 8 cm layer (see Fig. 4 inset). Levels of H₂S in pore waters in this layer were high (near 500 µmol kg⁻¹), relative to the 1 mmol kg⁻¹ upper limit for vesicomyid clams proposed by Fiala-Médioni et al. (1993). White bacterial mats were present within the Chowder Hill clam bed, although their significance as indicators of flow regime in a sedimented hydrothermal situation is not clear. Henry et al. (1992) described 2 distinct types of flow regime, distinguished by differences in flow rate and in dilution of original pore fluids by seawater in the upper layers of sediment. Their analyses showed dilution to be controlled by 2 factors: the lateral permeability of the fluid conduit and the relationship between volume flow and conduit diameter. In the following section, we examine results from the drilling program in Middle Valley, in order to develop a conceptual model of the processes that create a 'Type C' venting situation at the Chowder Hill clam bed.

Subsurface processes in the Dead Dog field

Seismic profiles across the Dead Dog vent field in Middle Valley indicated the presence of a prominent basement fault, approximately 2 km to the east of the vent field (Rohr & Schmidt 1994). Fluids presently venting at the Dead Dog field showed chemical signatures of interaction with both basaltic and sedimentary rock (Butterfield et al. 1994, Goodfellow & Peter 1994) and were believed to originate within a sill-sediment complex that formed the transition to oceanic crust in the area of the fault block (Davis et al. 1992). The sill-sediment reaction zone was buried by 450 m of hemipelagic sediment. A volcanic edifice located immediately beneath the Dead Dog field reached to within 250 m of the seafloor and has been proposed to act as a chimney to direct hydrothermal fluid flow.
Fig. 4. The northern face of Chowder Hill (looking south). Schema (not to scale) summarizes observations and hypotheses regarding local hydrothermal circulation (main figure), and fluid supply to the clam colony (enlargement).
by hydrothermal alteration permits the mounds to progressively 'grow' as thermal dewatering of sediments causes subsidence of the surrounding seafloor.

Subsurface processes at Chowder Hill

We considered how fluids might be expelled at the clam bed at Chowder Hill, within the above context of hydrothermal alteration of sediments and related permeability changes. The irregular distribution of venting on Chowder Hill indicated that permeability properties are not homogeneous over the entire structure. Clues to one aspect of local permeability control may be found in 2 observations. Hole 858B penetrated the northeast flank of Chowder Hill to a depth of 32 m. When observed by submersible the following year, Hole 858B was venting high temperature fluids from a chimney that had formed on the side of the hole, at 1 to 2 m below the seafloor surface (K. Becker pers. comm.). This observation suggested that a locally shallow reservoir of high temperature fluids resided within the mound and that widespread venting was prevented by a low permeability surface layer. The localization of the clam bed on a slump scar, where indurated sediments were exposed, can be seen as further evidence of a local reservoir within the mound. In the case of the clam bed, we suggest that erosion has brought more permeable sediments close enough to the seafloor to supply the clams with H2S through slow diffusion into the soupy surface layer (Fig. 4).

The absence of detectable temperature anomalies at the sediment surface within the clam bed and the modest temperatures measured down to near 30 cm were evidence of the relatively low intensity of venting at this site. The sediment layer supplying the clam bed may have been less permeable to fluid flow than the conduit exposed at nearby Hole 858B or the conduit feeding the high temperature (276°C) vents further up the hill. As discussed above, the relatively low density of clams within the Chowder Hill field was also indicative of low velocity venting, although predation effects on clam density by the locally abundant octopus population (Juniper et al. 1992) are unknown.

The same fracture-enhanced permeability that opened sediments to the movement of hydrothermal fluid also permitted entrainment of seawater into the conduit system. Magnesium enrichment of hydrothermally altered sediments recovered from cores on Chowder Hill indicated that seawater entrainment does occur (Goodfellow & Peter 1994, Leybourne & Goodfellow 1994). We do not have sufficient data to model the level of seawater entrainment into the conduit system, as performed by Henry et al. (1992) for clam colonies at subduction zone seeps. Comparison of sulfide and Si concentrations from Butterfield et al. (1994) for pore waters from the 4 to 8 cm layer in the clam bed (0.489 and 1.243 mmol kg⁻¹, respectively) with the 276°C fluids sampled from the top of Chowder Hill (1.82 and 9.61 mmol kg⁻¹, respectively) indicated that the fluid source feeding the clam bed was formed by mixing of high temperature fluids and entrained seawater. Modeling of seawater entrainment requires more extensive pore-water and temperature profile data for the clam bed and surrounding sediments. In Fig. 4, we present a simplified scheme for fluid supply to the clam bed on Chowder Hill that summarizes the observations discussed above.

Fluid and sulfide flow to the clam colony

Measured sediment temperature profiles (Fig. 3) and pore-water sulfide concentrations (Fig. 4 inset) can be used to constrain flow characteristics for the clam bed, and to derive an estimate of sulfide supply to the colony from a subsurface source. For this purpose, we first estimated fluid flow velocity from the temperature gradient using the equations of Bredehoeft & Papadopulos (1965) for a 1-dimensional advection-diffusion model. This steady-state model assumes vertical uniform flow of fluid and heat through a homogeneous and fully saturated semiconfining layer from a source at depth L. Thermal conductivity for the sediments was taken from data from the 858B drill core (average value of 1.0 W m⁻¹ K⁻¹; Davis et al. 1992). Because temperature was measured to a shallow depth only (z = 29 cm), it was not possible to fit the temperature profiles to theoretical exponential profiles for advection such as given in Bredehoeft & Papadopulos (1965). Instead, we expanded their solution for shallow depth intervals (βz/L < 1.0) over which the temperature gradient can be assumed to be linear. Given this boundary condition, for an average temperature gradient of 18°C m⁻¹ (Fig. 3), the calculation of fluid velocity was reduced to the following equation

\[ V_z = \frac{18^\circ K}{c\rho(T_L - T_0)} 3 \times 10^7 \text{s} \]

where \( V_z \) = fluid velocity (m yr⁻¹); \( k \) = thermal conductivity (1.0 W m⁻¹ K⁻¹); \( c \) = specific heat of fluids (4000 J kg⁻¹); \( \rho \) = density of fluids (10³ kg m⁻³); \( T_L \) = source fluid temperature at depth L; \( T_0 \) = temperature at sediment-seawater interface (2°C).

Estimates of \( V_z \) by this method are sensitive to the choice of source temperature (\( T_L \)), which could not be measured directly. The maximum source fluid temperature was assumed to be 280°C, corresponding to a high temperature reservoir at 30 m depth (Davis & Fisher 1994). For a 280°C source a 1-dimensional
Darcy velocity of 0.50 m yr⁻¹ would account for the observed temperature gradient. Lower source fluid temperatures would result in higher fluid velocity estimates (e.g. 1.38 m yr⁻¹ for a 100°C source).

Implicit in this approach was the assumption that no heat is lost through the sides of the conduit bringing fluid to the clam colony. According to Henry et al. (1992) this is acceptable if the depth to \( T_L \) (fluid source) is small with respect to colony diameter. As this is not the case (colony diameter \( \approx 3.5 \) m, vs source depth of 10 to 30 m), the amount of fluid flowing through the colony is underestimated. Fluid flux would be overestimated in the case where the measured thermal gradient was primarily due to vertical conduction above a very shallow aquifer or lateral conduction away from a vertical conduit.

The estimated value was comparable to the minimum velocity of \( \approx 0.5 \) m yr⁻¹ required to maintain the average temperature profile for the Dead Dog field (Davis & Fisher 1994) and the \( <10 \) m yr⁻¹ value estimated for the 'Type C' colonies by Henry et al. (1992). Assuming that fluids feeding the clam colony at a rate of 0.50 m yr⁻¹ have a \( \text{H}_2\text{S} \) concentration of 500 mmol kg⁻¹ (see Fig. 4) and a density of 1000 kg m⁻³, the supply rate would be 250 mol \( \text{H}_2\text{S} \) m⁻³ yr⁻¹. If all sulfide were used by chemosynthetic bacteria for \( \text{CO}_2 \) fixation, at a molar consumption ratio of 0.35 to 0.40 mol \( \text{CO}_2 \) fixed per mole \( \text{H}_2\text{S} \) consumed (Tuttle & Jannasch 1979, Nelson & Hagen 1995), the potential \( \text{CO}_2 \) fixation rate would be \( 8.3 \) gC m⁻² yr⁻¹. There are no data in the literature that would enable us to estimate the relative importance of the different mechanisms of sulfide oxidation likely to occur in a clam bed (clam symbionts vs free-living bacteria and chemical oxidation). By way of comparison, Juniper et al. (1995) report \( \text{CO}_2 \) fixation rates of up to \( 6.1 \) gC m⁻² yr⁻¹, for bacterial mats at diffuse vents on the CoAxial Segment of the Juan de Fuca Ridge.

**CONCLUSION**

**Mosaicking**

Although relatively expensive, custom-designed image mosaicking Geographic Information Systems (GIS) can be developed to carry out small-scale benthic mapping, e.g. the Small Area Benthic Imaging System (SABIS) described by MacDonald et al. (1992), no attempt has previously been made to design a system that exploits the vast potential for application of commercial art and machine vision software and hardware to the particular problems of deep-sea ecology and geology. The system configured here was relatively inexpensive, albeit less sophisticated than dedicated systems. By making use of the intuitive Macintosh GUI (Graphic User Interface) it permits first-time users to gain a basic working familiarity with the mosaicking and image enhancement software, while leaving considerable room for program customization (scripting) by more experienced users. While the mosaicking work can be performed with off-the-shelf personal computers, additional random access memory (RAM) is required to assemble large image mosaics and perform enhancements. The 48 MB of RAM in the system described here is adequate for most tasks involving mosaics of up to 100 images. Use of virtual memory on the computer hard disk considerably slows processing operations.

Systematically repeated and overlapping imaging swaths, controlled viewing angle (preferably 90°) and correct illumination are essential if mosaicking is to be used for site reconstruction and quantitative study of vent communities. Here we used natural objects as references for overlapping image pairs and assembling mosaics, and results were satisfactory. While greater accuracy can theoretically be obtained by referencing deployed markers of a constant size and shape (preferably round), it is not always practical or desirable to saturate an area with enough markers to have several appear in every image.

**Application of drilling results to ecological studies**

The vast amount of information now available for Middle Valley, and a scheduled second drilling leg for 1996, effectively make this site a de facto ridge crest observatory. A recent RIDGE/USSAC workshop developed plans for coordinated geophysical, geochemical and ecological observations to be carried out in conjunction with the second drilling leg (Zierenberg et al. 1994). Combining results from ODP Leg 139 with submersible observations certainly provided a clearer overall understanding of the processes controlling hydrothermal fluid supply to the clam colony on Chowder Hill. Complementary vent discharge and organism abundance data will also be important to future determinations of energy flow in this hydrothermal ecosystem. Nevertheless, the scale at which hydrological processes are considered in the context of the drilling program does not always correspond to the interests of ecological studies of individual colonies of vent animals. In the latter case, more detailed in situ data gathering is required, in order to better resolve fine-scale, near-surface processes and to fit them into the general hydrological scheme derived from drilling results. Evaluating the influence of hydrothermal flux on vent community composition in the Dead Dog field will obviously require information from many contrasting sites. It was the intention of this study to develop a methodological approach that will permit acquisition of the necessary comparative data in subsequent studies.
Acknowledgements. This work was funded by NSERC Canada, the Department of Natural Resources Canada and the Universitè du Québec à Montréal. A.J.G. was supported by a post-doctoral fellowship from the Université du Québec. The NOAA Vents program contributed significantly to our field effort. We thank the ROPOS team and the crew of the NOAA 'Discoverer' for their collaboration at sea. Discussions with J.-C. Maé, fc. and E. Davies were of great aid in the development of the fluid flow estimate. Three anonymous reviewers contributed to improving an earlier version of this manuscript. Graphics are by Enriette Cagnon.

LITERATURE CITED


Becker K, Morin RH, Davis EE (1994) Permeabilities in the Middle Valley hydrothermal system measured with packer and flow meter experiments. In: Davis EE, Mott MJ, Fisher AT et al. (eds) Proceedings of the Ocean Drilling Program (ODP), College Station, TX, Scientific Results 139:613–626

Bredgoettet JD, Papadopoulos IS (1965) Rates of vertical groundwater movement from the earth's thermal profile. Water Res 1:325–328

Butterfield DA, McDuff RE, Franklin JM, Wheat CG (1994) Geochemistry of hydrothermal vent fluids from Middle Valley, Juan de Fuca Ridge. In: Davis EE, Mott MJ, Fisher AT et al. (eds) Proceedings of the Ocean Drilling Program (ODP), College Station, TX, Scientific Results 139:399–410


Davis EE, Fisher AT (1994) On the nature and consequences of hydrothermal circulation in the Middle Valley sedimented rift: inferences from geophysical and geochemical observations. In: Davis EE, Mott MJ, Fisher AT et al. (eds) Proceedings of the Ocean Drilling Program (ODP), College Station, TX, Scientific Results 139:695–717

Davis EE, Mott MJ, Fisher AT et al. (1992) Proceedings of the Ocean Drilling Program (ODP), College Station, TX, Initial Report Leg 139

Davis EE, Mott MJ, Fisher AT et al. (1994) Proceedings of the Ocean Drilling Program (ODP), College Station, TX, Scientific Results Leg 139

Davis EE, Villinger H (1992) Tectonic and thermal structure of the Middle Valley sedimented rift, northern Juan de Fuca Ridge. In: Davis EE, Mott MJ, Fisher AT et al. (eds) Proceedings of the Ocean Drilling Program (ODP), College Station, TX, Initial Report 139:9–41


Goodfellow WD, Peter JM (1994) Geochemistry of hydrothermally altered sediment, Middle Valley, northern Juan de Fuca Ridge. In: Davis EE, Mott MJ, Fisher AT et al. (eds) Proceedings of the Ocean Drilling Program (ODP), College Station, TX, Scientific Results 139:207–289


Leybourne MJ, Goodfellow WD (1994) Mineralogy and chemical studies of hydrothermally altered sediment, Middle Valley, Juan de Fuca Ridge In: Davis EE, Mott MJ, Fisher AT et al. (eds) Proceedings of the Ocean Drilling Program (ODP), College Station, TX, Scientific Results 139:15–206

Rohr KM, Gröschel-Becker H (1994) Correlation of well logs, physical properties, and seismic reflection data, Middle Valley, Juan de Fuca Ridge. In: Davis EE, Mottl MJ, Fisher AT et al. (eds) Proceedings of the Ocean Drilling Program (ODP), College Station, TX, Scientific Results 139:585–596
Rohr KM, Schmidt U (1994) Seismic structure of Middle Valley near sites 855–858, Leg 139, Juan de Fuca Ridge. In: Davis EE, Mottl MJ, Fisher AT et al. (eds) Proceedings of the Ocean Drilling Program (ODP) College Station, TX, Scientific Results 139:3–17
Sarrazin J, Juniper SK, Massoth GJ (1993) Using the ROPOS remote vehicle to study biological and physico-chemical zonation on hydrothermal chimneys. EOS 74(43) Suppl. (abstr #T21A-01)

This article was submitted to the editor

Manuscript first received: December 14, 1994
Revised version accepted: May 16, 1995