Filter-net structure and pumping activity in the polychaete *Nereis diversicolor*: effects of temperature and pump-modelling

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ABSTRACT: Electron micrographs of the filter-net structure in the facultatively suspension-feeding polychaete *Nereis diversicolor* O. F. Müller showed that the net is composed of an irregular meshwork made up of long, relatively thick filaments (up to 300 nm) interconnected with a variety of shorter and thinner filaments. The thinner filaments range in diameter from 5 to >25 nm. The average size of the meshes, measured directly on the micrographs, lies between 0.5 and 1.0 μm, but due to shrinkage the values represent only about 75% of the actual dimension of the intact net. The effects of temperature on water processing were measured as clearance of suspended algal cells or measured directly. Pumping activity (undulating body movements of worms kept in glass tubes) was monitored using an infrared phototransducer technique. In the temperature interval from 5 to about 15 °C there was a linear increase in clearance, and a doubling of the temperature was followed by a doubling in clearance. Direct measurements of pumping rate showed that high stroke frequency was correlated with high pumping rate. A doubling of temperature from 13 to 23–29 °C led to a doubling of the stroke frequency and a halving of the net cycle length. At low temperatures a tendency towards an extended pause between pumping periods was noticed. The *N. diversicolor* pump was modelled as a positive displacement unit, and earlier data on back pressure characteristics were examined in light of the proposed model. The pump model prediction of temperature dependence showed reasonably good agreement with experimental data. The consequences of leaving out the effect of viscosity or stroke frequency in the pump model were evaluated. Clearly, the temperature effect as related to viscosity is negligibly small in the *N. diversicolor* muscular positive displacement pump (unlike for viscous ciliary pumps).

INTRODUCTION

The facultatively suspension-feeding polychaete *Nereis diversicolor* has recently been suggested to be an undervalued, key organism in the control of phytoplankton production in shallow brackish-water areas, its population filtration rates being on the order of 10 m³ m⁻² d⁻¹ (Riisgård 1991). *N. diversicolor* lives in U-shaped tubes in soft sediment. In the presence of suspended algal cells, the worm spins a net-bag in the tube. By vigorously undulating body movements water is driven through the trapping-net. The net with the retained food particles is eaten after pumping periods of 5 to 10 min. A new spinning and pumping cycle follows immediately thereafter (Harley 1950, Goerke 1966, Riisgård 1991). This presumably evolutionary late adaptation to a facultative life as a filter-feeder is not only interesting in an ecological context, but also in comparison with obligately suspension-feeding polychaetes, such as *Chaetopterus variopedatus* (Riisgård 1989) and *Sabella penicillus* (Riisgård & Ivarsson 1990).

The aim of the present work was to undertake a more detailed study, including modelling, of the filter-pump system of *Nereis diversicolor*. The results serve both to aid our understanding of the filtration biology of *N.
**RESULTS AND DISCUSSION**

Food-trapping net

Although the chemical composition of the food-trapping net of *Nereis diversicolor* has not yet been studied, the filaments of the net probably consist of highly polymerised macromolecules resembling components of mucus. Such structures are thoroughly hydrated, and drying them, as done in the present work, would most likely cause them to shrink lengthwise and round structures to appear flat. Since the filaments appeared to be well-attached to the carbon-film on the EM grid, one would have expected any shrinkage to cause creases in the carbon film and ruptures in both filaments and film in places where the film was firmly fixed. Neither phenomenon was observed, and the few ruptures of the net that could be seen appeared to have taken place during the attempts to pick up the net on the EM grid, since the carbon film underneath was intact. Lacking indications of noticeable shrinkage, the dimensions reported below are considered representative of the intact net. Net length was reduced by ca 25% relative to the working size, with minimal width reduction. The 25% reduction in net length was determined by measuring the net length before and after injection of the glutaraldehyde/formaldehyde solution into the inhalant end of the tube containing the worm.

Filament dimensions (Fig. 1)

Keeping in mind that the filaments were probably flattened to some degree, measurements showed that the long, relatively thick filaments of the net had diameters up to 300 nm. Some of these thick filaments appeared to consist of several strands fused together. A variety of shorter and thinner filaments interconnected with the long thicker filaments to form an irregular mesh-work. The thinner filaments varied in diameter from 5 nm to more than 25 nm, and often they seemed to fuse with the thicker filaments. The thinnest filaments were often observed forming the longest side of a triangle, spanning the corner where thinner filaments joined with thicker ones. Even at a magnification of more than 100,000× no obvious internal structures could be seen in the filaments.

Mesh dimensions (Fig. 1)

The largest dimension of any of the meshes, measured directly on the micrographs, varied from <0.1 μm in the triangular structures to 1.5 μm for the biggest meshes. Very few meshes were near-circular or near-

**MATERIALS AND METHODS**

Ragworms *Nereis diversicolor* O. F. Müller were collected in October 1990 from mud flats (<0.5 m water depth; ca 10% S) at Kærby Fed, Odense Fjord, Denmark. In the laboratory the worms were transferred to glass tubes (16 cm length; 4.0 mm internal diameter) and kept in aquaria (14 to 16 °C, 18 to 20% S) until preparation of net-samples and experiments could be performed.

**Preparation of net-samples for electron microscopy (EM).** Hydrophilic carbon films (about 10 nm thick) were prepared on mica in a Balzers BAF 301 with turbopump used as a vacuum evaporator. The carbon film was picked up on copper grids and used for adsorbing filter-nets without further treatment. When a worm had completed a net, it was forced to abandon it by injection of a solution of 2.5% glutaraldehyde, 1% formaldehyde, and 0.05 M sodium cacodylate in 60% seawater (filtered) into the inhalant end of the glass tube (Flyd & Fiala-Medioni 1982). The glass tube had been scored with a glass-cutter, so that one could easily break off the part into which the worm had retracted. The EM grid was placed inside the net and then withdrawn, with the net adhering to it. After a cautious blotting, the grid was air-dried. The grids were then examined in an electron microscope (Jeol 100CX) without further treatment. Staining with uranylacetate in aqueous solution did not notably enhance the contrast of the filaments, and the detrimental effects of rewetting the grids were therefore avoided.

**Water pumping activity.** Experimental procedures for measurement of water processing, by means of either the ‘clearance method’ (volume of water cleared of algal cells per unit time) or the ‘direct technique’, were the same as those adopted by Rüsgård (1991). Pumping activity (undulating body movements of worms kept in glass tubes) was monitored using the ‘infrared phototransducer technique’ of Rüsgård (1991).

The effects of temperature on clearance, pumping rate and stroke frequency (undulating body movements) were determined 1 to 12 h after a temperature change of 3 to 6 °C controlled by a thermostated water bath in which the aquarium with the worm(s) was placed.

When no literature references are given for fluid mechanical formulas or concepts these matters may be found in general textbooks (e.g. Leyton 1975, Vogel 1981). General principles and characteristics of pumps are explained in many standard engineering handbooks, e.g. Marks (1941).

diversicolor, and to further elucidate temperature effects on biological pumps, as initially reported by Jørgensen et al. (1990).
quadratic, so the average size of a hole lay between 0.5 and 1.0 μm. However, it should be remembered that these figures represent only about 75% of the actual dimensions of the intact net. Small particles (of <0.1 μm diameter) were occasionally picked up by the net, apparently by the small holes. If the filaments are just slightly flexible and elastic, the triangular structures may be able to catch very small particles that get wedged into the triangles.

**Effects of temperature**

Temperature effects on pumping activity were measured by means of various methods: clearance (Fig. 2); direct determination of pumping rate and stroke frequency (Fig. 3); and the infrared phototransducer technique (Figs. 4 & 5).

Clearance as a function of acute change in temperature (2 to 6 °C within 15 to 30 min) was measured in 3 worms aclimatized to 6 °C during several weeks (Fig. 2). In the temperature interval from 5 to ca 15 °C there was a linear increase in clearance, as indicated by the regression lines. In Worms #8 and #9 a doubling of temperature was followed by a doubling in clearance. At higher temperatures up to about 25 °C clearance decreased. In the temperature range from 5 to 25 °C the stroke frequency (i.e., undulating body movements) was seen to increase (from 25 strokes to 100 strokes min⁻¹ in #8, Fig. 3). Direct measurements of the pumping rate in #9 at 19 to 22 °C (Fig. 2) and in #10 at temperatures up to 26 °C (Fig. 3) showed that high stroke frequency was correlated with high pumping rate, and thus, the low clearance might have been due to a leaky food-trapping net caused by high flow rates, or the mucous secretion may have been disturbed by the acute temperature increase. This interpretation is supported by the measurements of retention efficiency (Fig. 6). Particles down to at least 2 to 3 μm were efficiently cleared from the water at
Fig. 2. Nereis diversicolor. Algal clearance as a function of temperature in experiments with 3 worms. Regression lines and their equations have been shown for temperature intervals where linear relationships are suggested (Worm #8: 5.5 to 13°C; #11: 5 to 16°C; #9: 6 to 17°C). Frequency of water-pumping, undulatory body movements (strokes min⁻¹) counted by eye and using a stop-watch are indicated at a number of sampling times. Dashed lines, fitted by eye, show the pattern of decrease in clearance rate at higher temperatures. Pumping rate in the temperature range 20 to 22°C was measured in Worm #9 using the direct technique immediately after the clearance experiment (closed symbols). Body dry weights: #8 = 40 mg; #9 = 41 mg; #11 = 47 mg

Fig. 3. Nereis diversicolor. Stroke frequency, pumping rate and length of net cycle (spinning-pumping-eating) as a function of temperature. Regression lines (Worm #9: 6 to 17.4°C; #10: 8 to 26.2°C; #8: 5.5 to 25°C) and means ± SD (#8) are shown. Body dry weights: #8 = 40 mg; #9 = 41 mg; #10 = 35 mg

Temperatures of 17°C and less, but at higher temperatures clearance was reduced. At 19°C the net became ineffective in retaining particles smaller than ca 9 μm, and almost no particles up to this size were retained at 24°C. The low retention efficiency of particles smaller than ca 7 μm, previously found by Røisgård (1991), may be explained by a temperature effect similar to that demonstrated in the present work.

Fig. 6 indicates that the mesh dimensions in the intact net may be somewhat larger than shown by the micrographs (Fig. 1). More clearance measurements of small particles (0.5 to 3 μm) are, however, needed in order to identify more precisely the effective mesh size of the net.

Temperature also influenced the duration of net cycling, i.e. the time spent on net spinning, water pumping and net eating. An approximate doubling of the temperature from 13°C to 23–28°C lead to a doubling of the stroke frequency and a halving of the net cycle length (Fig. 3). At low temperatures a tendency towards an extended pause between pumping periods was noticed.

Extended pauses between pumping periods were also seen at low algal concentrations (i.e. 2500 cells ml⁻¹; see Fig. 5A). During a pause the worm often turned around or went to the tube entrances to examine the outside surroundings. When no algae were present in the water no net was spun, and pumping activity was low and sporadic (only to ventilate the tube). Addition of algae stimulated the worm to spin a net and to pump at a constant high rate usually within 10 min. Algal concentration did not influence pumping period, stroke frequency, spinning time, net eating time or net length in the range between 0.25 and 5 × 10⁴ cells ml⁻¹ (Table 1).

**Pump model**

Any attempt to interpret the effect of temperature change on worm pumping rate requires a plausible model of the pumping system under isothermal conditions. In *Nereis diversicolor* the pumping action is a result of the wavy motion of the body in the confining
Fig. 4. *Nereis diversicolor*. Pumping activity (undulating body movements) in Worms #8 and #9 recorded at different temperatures using a phototransducer fastened to the glass tube holding the worm.

Fig. 5. *Nereis diversicolor*. Pumping activity of Worm #2 at different algal (*Rhodomonas* sp.) concentrations: (A) $2.5 \times 10^3$ cells ml$^{-1}$; (B) $3 \times 10^3$; (C) $10^4$; (D) $1.5 \times 10^4$; (E) $2.6 \times 10^4$. 
tube (Figs. 7 & 8). Observations indicate 3 posteriorly propagating waves in different phase, one of which creates an effective stroke responsible for the pumping action. The effective wave peaks make firm contact with the tube wall on the dorsal and ventral sides, suggesting good seals. On the lateral sides, the parapodia make contact with the sidewalls of the tube, creating an effective stroke responsible for the pumping action.

Table 1. *Nereis diversicolor*. Pumping period, stroke frequency, net-spinning time, net-eating time, and length of net bag for 5 worms at different algal (*Rhodomonas* sp.) concentrations. Means ± SD; number of observations are shown in parentheses. Temperature = 17 °C

<table>
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<tr>
<th>Worm</th>
<th>Body dry weight (mg)</th>
<th>Algal conc. (×10^3 cells ml^-1)</th>
<th>Pumping period (s)</th>
<th>Stroke frequency (strokes min^-1)</th>
<th>Spinning time (s)</th>
<th>Eating time (s)</th>
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<td>34 ± 0 (1)</td>
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forming less perfect seals that may leak with increasing back pressure. A pump design such as this has features in common with mechanical positive displacement pumps, such as the gear pump and the screw pump, even though in the present case the motion is not rotating but linearly undulating. These morphologically based suggestions of a positive displacement pump that leaks more and more as back pressure is increased seem to agree with the general form of experimental back pressure characteristics (Fig. 9 in Riisgård 1991 and present Fig. 9). A non-leaking positive displacement pump would have a vertical characteristic, showing constant flow at all values of back pressure. Clearly, this is not the case for the data in Fig. 9, except at vanishing values of back pressure. As the back pressure is increased, the flow data show a progressive decrease, yielding a curve which implies internal leakage in the pump. This leakage is more pronounced at low stroke frequencies ('low gear') around 70 strokes min\(^{-1}\) (see Worms #6 and #13 in Fig. 9 of Riisgård 1991, or #6 in present Fig. 9) than at high stroke frequencies ('high gear') around 80 to 90 strokes min\(^{-1}\) (see Worms #4 and #17 in Fig. 9 of Riisgård 1991, or #4 in present Fig. 9).

Based on the foregoing considerations, the pump was modelled as a positive displacement leaking unit, as shown in Fig. 7. The pumping rate is the difference between the volume flow \(V_p\) of a leak-free pump and the volume flow \(V_L\) of leakage,

\[
V = V_p - V_L, \quad (1)
\]

where

\[
V_p = A_p L f \quad \text{and} \quad V_L = C_L A_L \Delta H_p/v \quad (2)
\]

Here, \(A_p\), \(L\) and \(f\) denote area, stroke length and frequency of the pumping action, respectively. \(A_L\) denotes the slit area through which viscous leakage flow is driven by excess pressure (\(\Delta H_p\)), \(v\) denotes the kinematic viscosity, and \(C_L\) is a constant.

The available area for leakage flow, \(A_L\), may not be constant but increases with increasing excess pressure.

This is true for a spring-loaded valve under static conditions, which for example may represent a crude model of the seals provided by the parapodia. Furthermore, under dynamic conditions the opening of the valve may be retarded at increasing stroke frequency. The resulting reduction in amplitude of valve opening may be modelled as a mechanical system for which the amplitude depends on the ratio \(f/f_o\), where \(f_o\) denotes a characteristic frequency. For lack of further information we assume a simple second-order system. Such a system is the simplest one that models the motion of a mass subject to some restoring elastic (spring) force. Therefore, for a simple model, if valve area depends linearly on excess pressure and inversely on frequency, as

\[
A_p = \Delta H_p/[1 + (f/f_o)^2],
\]

and if the stroke length \(L\) and area \(A_p\) of the pump are taken to be constants, then Eqs. (1) \& (2) give the following characteristic for the pumping unit:

\[
V = V_{p0} (f/f_0) - C_L (\Delta H_p)^2 (v/v_o)^{-1} [1 + (f/f_o)^2]^{-1}, \quad (3)
\]

where subscript 0 refers to a reference state, e.g. the normal operating point, at volume flow \(V_{p0}\) and frequency \(f_0\). The characteristic frequency \(f_o\), which models a purely mechanical feature, is taken to be a constant throughout (≈ 50 strokes min\(^{-1}\)).

Next, the pressure distribution through the tube containing an organism should be considered, as shown schematically in Fig. 7. The pressure rise over the pump, \(\Delta H_p\), must equal the sum of contributions for
viscous losses at the inlet and in the net and tube $\Delta H_v$; kinetic energy at the exit, $\Delta H_{ex}$; and the imposed back pressure $\Delta H_{f2}$:

$$\Delta H_p = \Delta H_l + \Delta H_{ex} + \Delta H_{f2}. \quad (4)$$

Here, the sum of all viscous losses is of the form $\Delta H_l = V$ for laminar flow, while $\Delta H_{ex} = V^2$. However, this kinetic term can be safely ignored compared to other terms in Eq. (4) (see Table 2), since exit velocity does not exceed 10 mm s$^{-1}$, yielding only $\Delta H_{ex} = V^2/2g = 0.005$ mm H$_2$O, where $g$ is acceleration due to gravity.

Substituting Eq. (4) into Eq. (3), employing the foregoing reference state, we obtain the back pressure model:

$$V = V_0 \left( \frac{f_0}{f} \right) - C_L \left[ \frac{\Delta H_{f2}}{(V/V_0)}(v/v_0) + \Delta H_{f2} \right] \left[ \frac{v/v_0}{1 + (f/f_0)^2} \right]^{-1}. \quad (5)$$

In effect, Eq. (5) gives $V(\Delta H_{f2})$, or $\Delta H_{f2}(V)$, including the effects of changing pump frequency and fluid viscosity. To use Eq. (5) we determine the total frictional pressure drop $\Delta H_p$ at the operating point from theoretical calculations based on known geometry and volume flow $V_0$. Constants $C_L$ and $V_0$ are determined from two measurements. One is at the normal operating point, where Eq. (5) gives

$$V_0 = V_0 - C_L [\Delta H_{f2}^2] \left[ 1 + (f_0/f)^2 \right]^{-1}. \quad (6)$$

For the other, at zero flow, Eq. (5) reduces to

$$0 = V_0 [f(0)/f_0] - C_L [\Delta H_{f2}^2] \left[ 1 + (f(0)/f_0)^2 \right]^{-1}, \quad (7)$$

where $\Delta H_{f2}$ and $f(0)$ are measured at (or obtained by extrapolation of data to) $V = 0$.

To complete the model and extend it to include the effect of changing temperature, $t$, we first need to know the temperature dependence of kinematic viscosity, $v(t) = 1.83 - 0.06t + 0.00133t^2 - 0.00000133t^3$ (Rawson & Tupper 1968). Also, we need to know how stroke frequency depends on both temperature and resistance to the pumping action, expressed by the pumping pressure $\Delta H_p$. The former dependence is expected to be biological in nature. It has been studied experimentally at zero back pressure (Figs. 2 & 3) and may be approximated by a linear relation:

$$f = a + bt \quad \text{(zero back pressure).} \quad (8)$$

The dependence on $\Delta H_p$, on the other hand, is expected to be both mechanical and biological, and it is not directly amenable to experimental study. However, isothermal experiments (Fig. 9 in Riisgård 1991) show decreasing frequency with increasing back pressure, hence with increasing pumping pressure. The difference between these pressures is the frictional pressure drop, which is a small fraction of either pressure, given a large back pressure. Therefore, the above-mentioned data suggest the general behavior of the relation

$$f(\Delta H_p), \text{ which proved to be well approximated by the relation}$$

$$f = f_0 - c(\Delta H_p)^2 \quad \text{(isothermal)}, \quad (9)$$

where constants $f_0$ and $c$ are as given in Table 2.

According to Eq. (9), the stroke frequency asymptotically approaches a maximum value, $f_0$, at low resistance, a limit that is probably determined biologically.

### Table 2. *Nereis diversicolor*. Pump model parameters of 'standard' worms at 15 °C

<table>
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<tr>
<th>Parameter</th>
<th>'Low gear'</th>
<th>'High gear'</th>
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<tbody>
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<td>Worm #6</td>
<td>Worm #4</td>
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<tr>
<td>$V_0$ (µl s$^{-1}$)</td>
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<td>140</td>
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<tr>
<td>$\bar{u}$ (mm s$^{-1}$)</td>
<td>0.221</td>
<td>0.269</td>
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<tr>
<td>$t_0$ (strokes min$^{-1}$)</td>
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<td>90</td>
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<tr>
<td>$f(0)$ (strokes min$^{-1}$)</td>
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<td>70</td>
</tr>
<tr>
<td>$\Delta H_{f2}$ (mm H$_2$O)</td>
<td>8</td>
<td>10</td>
</tr>
</tbody>
</table>

Predicted frictional pressure drop at normal conditions:

- $\Delta H_p$ (mm H$_2$O) 0.278 0.330
- $\Delta H_v$ (mm H$_2$O) 0.336 0.409
- $\Delta H$ (mm H$_2$O) 0.088 0.108
- $\Delta H_H$ (total) (mm H$_2$O) 1.228 1.467

Constants computed from Eqs. (6) & (7) (cases for $f_0 = 50$ strokes min$^{-1}$ and $\Delta H = 0$) in Table 2:

| $\Delta H_{f2}$ (mm H$_2$O) | 2.609 | 3.274 |

Relationship between stroke frequency ($f$, strokes min$^{-1}$) and temperature ($t$, °C), based on Eq. (8) and Fig. 3 (Worm #9; $b = 3.53$):

$$f = 17.04 + 3.53t \quad f = 37.05 + 3.53t$$

Relationship between stroke frequency ($f$, strokes min$^{-1}$) and pumping pressure ($\Delta H_p$, mm H$_2$O), based on Eq. (9) and Fig. 8:

$$f = 70 - 0.3(\Delta H_p)^2 \quad f = 90 - 0.2(\Delta H_p)^2$$

As resistance increases, the mechanical work load on the pump increases as $f\Delta H_p$. Assuming constant pump power would give $f = 1/\Delta H_p$, which does not fit the data. Apparently, *Nereis diversicolor*—like other biological pumps—can deliver increasing power with increasing pumping pressure until some maximum value is reached, according to Fig. 9 near zero net flow. Note that use of Eq. (9) in Eq. (5) complicates calculations which require iteration. Also, it must be stressed that the combined simultaneous effects of temperature and pumping pressure on stroke frequency have not been resolved.

### Parameters of 'standard' *Nereis diversicolor*

Earlier data (Riisgård 1991) were examined in light of the proposed pump model and 2 'standard' individuals
that seem to be representative of *Nereis diversicolor* were examined. One was denoted the 'low gear' individual (Worm #6; Fig. 9 in Riisgård 1991) with frequency decreasing from a maximum of 70 to about 50 strokes min\(^{-1}\) at increasing back pressure. The other was a 'high gear' individual (Worm #4; Fig. 9 in Riisgård 1991), with frequency decreasing from a maximum of 90 to about 70 strokes min\(^{-1}\).

Geometry, net bag, and tube were the same for both individuals, while volume flow \(V_0\) under standard conditions (15°C) was 115 and 140 \(\mu\)l s\(^{-1}\), respectively, as shown in Table 2. First, the total frictional pressure drop was estimated and then characteristic parameters from experiments were identified.

Following Silvester (1983), using the modified Tamada-Fujikawa equation, the pressure drop over a uniform mucus net of rectangular mesh is expressed as

\[
\Delta H = 8\pi \mu / g_{\mu} \lambda = \alpha \bar{u},
\]  

which defines the constant \(\alpha\) being the mean velocity upstream of the net; \(h_{\mu} = h_1 h_2 / (h_1 + h_2)\); \(h_1\) = width of mesh; \(h_2\) = length of mesh; \(\lambda = 1 - 21r + \pi^2/6\); \(r = \pi d/h_0\); \(h_0 = h_1 h_2 / \sqrt{(h_1 + h_2)}\); \(d\) = diameter of a cylindrical fibre.

Suppose the net of total area \(A = \sum A_j\) is composed of regions \(A_j\), \(j = 1, 2, \ldots, n\) of different mesh sizes, representing parallel flow paths of different resistances \(\alpha_j\) but subjected to the same pressure drop \(\Delta H_j = \alpha_j \bar{u}_j = \Delta H_0\). Then, from the continuity of total volume flow \(V = A \bar{u}\) the pressure drop may be estimated from

\[
\Delta H_n = \alpha_n \bar{u} = \alpha V/A; \alpha_n = \sum_{j=1}^{n} (\alpha_j/a_j).
\]

Clearly, Fig. 1 does not show a regular net with rectangular meshes, but rather triangular meshes for which no formula appears to be available. For an estimate, however, net mesh size may be approximated by 3 uniform, rectangular areas:

<table>
<thead>
<tr>
<th>Area no.</th>
<th>Area fraction (%)</th>
<th>(h_1) (μm)</th>
<th>(h_2) (μm)</th>
<th>(d) (μm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>25</td>
<td>1.2</td>
<td>1.4</td>
<td>0.030</td>
</tr>
<tr>
<td>2</td>
<td>50</td>
<td>0.6</td>
<td>1.0</td>
<td>0.025</td>
</tr>
<tr>
<td>3</td>
<td>25</td>
<td>0.28</td>
<td>0.42</td>
<td>0.010</td>
</tr>
</tbody>
</table>

At 15°C (\(v_0 = 1.184 \times 10^{-6} \text{ m}^2 \text{ s}^{-1}\)), use of Eqs. (10) & (11) gives \(\alpha_0 = 1.518 \text{ mm H}_2\text{O} \times (\text{ mm s}^{-1})^{-1}\), hence \(\Delta H = 0.336\) and 0.409 mm H\(_2\)O respectively for low gear and high gear individuals, as shown in Table 2.

Additional contributions to the frictional pressure drop are derived from flow in the tube, through the annular space between body and tube, and from flows parallel to the net, both inside and outside the net bag.

For the tube (40 mm length × 4 mm diameter; Fig. 7), assuming a fully developed Poiseuille flow, the frictional pressure drop is calculated from

\[
\Delta H_f = 8\pi v \ell / 2\pi R^4,
\]

where \(r\) = body radius and \(R\) = tube radius; this equation gives 0.088 and 0.108 mm H\(_2\)O, respectively, for the 2 cases.

For the annular space, using the expression for fully developed flow between coaxial cylinders (see e.g. Yuan 1967, p. 270)

\[
\Delta H_a = 8\pi v \ell / 2\pi R^4, \quad n^2 \frac{n-1}{n^2} = \frac{n-1}{n^2}, \quad \frac{\ln(R/\ell)}{\ln(R/\ell)}\]

we obtain 0.526 and 0.640 mm H\(_2\)O, respectively, for the 2 cases.

One approach is to assume a no-slip condition for axial flow along the net and to assume quasi-developed flow. Because Eqs. (12) & (13) are linear in velocity and length, the frictional pressure drop for a flow rate that varies linearly between zero and maximum is the same as for half the flow over the full length. For the low gear individual, the frictional pressure drop is estimated accordingly: from Eq. (12) for the flow inside the net bag, giving 0.390 mm H\(_2\)O (\(r = 1.3\) mm, \(L = 63/2 = 31.5\) mm), and from Eq. (13) for the external annular flow, 1.471 mm H\(_2\)O (\(R = 2\) mm, \(n = 2/1.3, L = 31.5\) mm).

Clearly, these results appear to be unrealistic, and they contradict the assumption of constant pressure drop over all parts of the net. In reality the net bag is somewhat conical, probably making the mean axial velocity inside and outside the net nearly the same, ca 9 to 10 mm s\(^{-1}\). Also, in view of the high porosity of the net and the low Reynolds numbers based on fiber diameters, a slip rather than no-slip condition for axial flow would be appropriate. In this second simplified approach twice the frictional pressure drop obtained from Eq. (12) (\(R = 2\) mm, \(L = 63\) mm) is used, i.e. \(\Delta H_\text{a} = 0.278\) and 0.330 mm H\(_2\)O, respectively, for the 2 individuals.

Ignoring the frictional pressure drop at the inlet, \(\Delta H_\text{in}\), as being negligible, the total frictional pressure drop becomes \(\Delta H = 1.228\) and 1.487 mm H\(_2\)O, respectively. These values, as well as other parameters \((\beta_0, f(0)\) and \(\alpha\ell/\alpha)\) of standard worms #6 and #4 obtained from Riisgård (1991: Fig. 9), and Figs. 3 & 8 in the present work, are given in Table 2 along with the resulting constants \(V_0\) and \(C_L\) computed from Eqs. (6) & (7).
Evaluation of pump model and temperature effects

Before studying temperature effects, the ability of the model in Eq. (5) to predict the back pressure characteristics of 'standard' Nereis diversicolor under isothermal conditions (15°C) was examined. Fig. 9 shows experimental data for Worms #6 and #4 and model predictions from Eq. (5). The predictions are based on model parameters listed in Table 2 and a chosen value of \( f_o = 50 \) strokes min\(^{-1}\). The agreement between model and data is encouraging in view of the many unknown details in both positive displacement pump parameters and the leakage model.

Next, to examine the temperature dependence at zero back pressure, note that Worms #9 and #8 (Fig. 3) show nearly the same change in frequency per degree temperature change. Selecting #9 as representative,

\[
f = 10.87 + 3.53t
\]

where \( f \) is in strokes min\(^{-1}\) and \( t \) is in °C; this corresponds to about 64 strokes min\(^{-1}\) at 15°C. Scaling this relation to 70 and 90 strokes min\(^{-1}\), respectively, for Worms #6 and #4, \( f(t) \)-relations at zero back pressure may be proposed.

\[
f = 17.04 + 3.53t \quad \text{(Worm #6)} \tag{14a}
\]

\[
f = 37.05 + 3.53t \quad \text{(Worm #4)} \tag{14b}
\]

Using Eqs. (14a) & (14b) for these individuals, the parameters \( V_{po} \) and \( C_L \) given in Table 2, and the \( v(t) \) for seawater in Eq. (5), we obtain the pump model prediction of temperature dependence. For zero back pressure, the results are shown in Fig. 10. Volume flow (ml min\(^{-1}\)) as a function of temperature for low gear and high gear respectively (see Table 2) is for Worm #6

\[
V = 1.67 + 0.35t \tag{15a}
\]

and for Worm #4

\[
V = 3.42 + 0.33t \tag{15b}
\]

which is reasonably close to the \( V(t) \) of Worm #10 (Fig. 3):

\[
V = 1.41 + 0.44t \tag{16}
\]

Also shown in Fig. 10 are the consequences of leaving out the effect of viscosity or stroke frequency in Eq. (5). Clearly, the temperature effect related to viscosity is negligibly small, which is not surprising since we are dealing with a positive displacement pump with limited viscosity-dependent leakage and friction. This is unlike viscous pumps, such as the ciliary gill pump of the blue mussel Mytilus edulis (Jørgensen et al. 1990) and possibly the ciliary crown-filament pump of the suspension-feeding polychaete Sabella penicillus (Risgård & Ivarsson 1990).

Energetic costs of pumping

The normal pump pressure or operating point \( O_p \) of the Nereis diversicolor pump may be found by adding the kinetic loss \( \Delta H_{kin} \) to \( \Delta H_{fo} \) (see Table 2). The exit loss is given by \( v^2/2g \), where \( v \) is water velocity. For 'standard' N. diversicolor #4 it was found that \( \Delta H_{ex} = 0.140/n_0.27/(2.7g) = 0.0057 \) mm H\(_2\)O, and \( O_p = 1.493 \) mm H\(_2\)O. The power output \( P_p \) from the pump can be calculated as pumping pressure \( \Delta P = \rho g O_p \), where \( \rho = \) density of seawater) times pumping rate \( V \), resulting in 2.10 \( \mu \)W for Worm #4 and 1.42 \( \mu \)W for Worm #6. With a metabolic rate \( R = 12.6 \) \( \mu \)l O\(_2\) h\(^{-1}\) (Risgård 1991), equivalent to 70 \( \mu \)W, the 'pump work' \( P_p/R = 2.10/70 = 0.03 \). This value may be compared to the 'pump work' of 4 % in the exclusively suspension-feeding polychaete Chaetopterus variopedatus (Risgård 1988), which has a mucous trapping-net and a muscular piston pump comparable to that of Nereis diversicolor. The very similar value of pump work supports the earlier statement (Risgård 1991) that N. diversicolor fulfills conditions for subsisting exclusively as a suspension feeder. It is interesting to note that the pump and filter system of N. diversicolor apparently is well 'optimized' in spite of the presumably late adaptation of this polychaete to a facultative mode of life as a suspension feeder. According to both data and model, N. diversicolor may apparently pump against a rela-
tively high resistance over a prolonged time and thus deliver a pump effect that is 5 to 10 times the pump effect at zero back pressure. The possible biological significance of this property of the muscular positive displacement pump in *N. diversicolor* remains obscure.

It is of considerable ecological importance to determine the extent to which *Nereis diversicolor* actually uses its ability to filter the water column, and thus possibly limit phytoplankton productivity, particularly in shallow brackish-water areas where this polychaete is often abundant. The system used in the present work for monitoring stroke frequency (Fig. 4) may also be applied in field investigations. Such pumping activity studies, combined with simultaneous phytoplankton biomass recordings during extended periods, are now in progress.

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**LITERATURE CITED**


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