Rapidly obtained ecosystem indicators from coral reef soundscapes

Lauren A. Freeman^{1,*}, Simon E. Freeman²

¹National Research Council Postdoctoral Fellow, Remote Sensing Division, Naval Research Laboratory, Washington, DC 20375, USA

²Underwater Acoustics Division, Naval Research Laboratory, Washington, DC 20375, USA

ABSTRACT: Present-day coral reef ecosystem monitoring techniques can be costly, labor-intensive point measurements that can potentially introduce intractable sampling bias and error. Here we report correlations between visually obtained ecological assessment metrics and concurrently recorded aspects of the underwater biological soundscape over coral reefs at 23 sites spanning the Hawaiian Islands archipelago. Sites from the ‘cool tropics’ oceanographic habitat grouped along a principal component defined by an acoustic sliding scale: from protected or more remote sites at which lower frequencies were more dominant, to degraded sites which produced soundscapes dominated by higher frequency sound. Positive correlations between ambient biological sounds below 2 kHz and the density of benthic invertebrates (Pearson's $\rho = 0.61\text{--}0.76$), their predators ($\rho = 0.65\text{--}0.8$), organism-scale bathymetric complexity ($\rho = 0.6\text{--}0.62$) and the quantity of crustose coralline algae ($\rho = 0.6\text{--}0.62$) suggest a connection between this part of the spectrum, habitat complexity and the density of benthic fauna. A positive correlation was also observed between the daytime soundscape in the 2 to 20 kHz band and the proportion of benthic fleshy macroalgal cover ($\rho = 0.63\text{--}0.7$), an indicator of reef degradation. This study indicates the possibility of rapid, inexpensive and spatially integrative remote sensing of the ecological state of coral reefs. Such quantitative methods could be used to ecologically assess vast areas of reef habitat autonomously in near real-time and could be important for remote *in situ* detection and characterization of subtle but significant ecological changes brought about by climate change and other more localized anthropogenic impacts.

KEY WORDS: Underwater acoustics · Ecological survey · Monitoring · Coral reef · Marine ecology · Hawaiian Islands

INTRODUCTION

Coral reefs are under threat from both climate change (Glynn 1996, Langdon et al. 2000, Hoegh-Guldberg 2011) and large-scale anthropogenic stressors that elicit complex ecosystem stress responses (Pastorok & Bilyard 1985, Hughes 1994, Sebens 1994, Jackson et al. 2001, Pandolfi et al. 2003, 2005). Evaluation and monitoring of the ecological state of coral reefs is required for both scientific understanding and reef conservation initiatives. Classical coral reef ecological monitoring methods utilizing SCUBA diver

surveys and substrate photography are both time and labor intensive. These techniques can introduce sampling error (due to the limited range of diver vision, optical sensors and diver endurance) and bias (due to the effect of the diver's presence on animal behavior). Furthermore, these surveys generally require a research vessel on station, and thus are not conducted frequently and cannot be conducted at night when benthic organisms are more active (Johnson et al. 1947, Freeman et al. 2014, Nedelec et al. 2015). The majority of faunal biomass on a coral reef may be small, cryptic and subterranean (Plaisance et al.

*Corresponding author: laurenava@gmail.com

2011). There is an urgent need for more quantitative, remote, less invasive and lower cost ecological data collection methods.

Passive acoustic monitoring of naturally occurring underwater sounds is a remote sensing method that may offer such ecosystem evaluation and monitoring capability. The underwater biophony, comprising sounds produced by biological processes (Pijanowski et al. 2011), contains the ecologically relevant information of interest. Some aspects of the biophony, such as marine mammal calls, are the subject of extensive study (Johnson et al. 2009, Richardson et al. 2013). However, the majority of acoustic energy in temperate and tropical shallow-water regions is created by a wide variety of other organisms including shrimp (Johnson et al. 1947, Au & Banks 1998), lobsters (Moulton 1957, Patek et al. 2009), sea urchins (Cummings et al. 1964, Radford et al. 2008), hermit crabs (Freeman et al. 2014), as well as many species of soniferous fishes (Tavolga 1964, Rountree 2008). Ecological processes such as spawning (Tavolga 1964), feeding (Amorim et al. 2004), schooling and predator avoidance (Moulton 1960) create acoustic emissions that may contain information regarding the number and size of the organisms present, or the rate of resource consumption in that area. Indeed, some sounds play a role in the attraction of pelagic larvae to settlement sites (Simpson et al. 2004, 2005, Montgomery et al. 2006, Radford et al. 2007, Vermeij et al. 2010), suggesting that the correct interpretation of the information contained in these sounds confers selective advantage. Interest in using passive sounds as ecological metrics is growing (Cotter 2008). With the advancement of battery and solid-state memory technology, modern battery-powered underwater acoustic recorders can be deployed for a year or more and can take quality recordings at high sample rates and bit depths. Such sample rates not only permit the spectral investigation of higher frequency sounds but also facilitate detailed waveform analysis in the time domain (Au & Banks 1998). While the sounds created by reef ecosystems contain a great deal of information, extracting useable ecological metrics from acoustic recordings remains a formidable challenge. Due to the complex nature of the acoustic environment in shallow water and the high degree of variability in sounds produced by organisms, careful interpretation and vetting of recordings with ecological data is necessary. Following work in terrestrial environments (Sueur et al. 2008, Depaetere et al. 2012), a number of recent studies (Kennedy et al. 2010, McWilliam & Hawkins 2013, Lillis et al. 2014, Piercy et al. 2014, Nedelec et al. 2015) have explored rela-

tionships between spectral and temporally filtered aspects of the underwater soundscape and ecological data using a variety of statistical techniques. Night-time sound levels are observed to be generally higher in all studies, although attempts to quantify faunal activity through direct observation at night were problematic due to the need for divers to use illumination that (1) limited the observable area and (2) subsequently altered animal behavior (Nedelec et al. 2015). Nevertheless, it is generally accepted that nocturnal sound levels above several hundred Hertz are elevated due to invertebrate activity (Johnson et al. 1947, Freeman et al. 2014, Staaterman et al. 2013, 2014). While these levels have been linked in part to the activity of snapping shrimp (Johnson et al. 1947, Staaterman et al. 2013), evidence suggests that in some locations, a wide variety of organisms contribute to the general increase in level (Freeman et al. 2014, Radford et al. 2007, Kennedy et al. 2010). This paper aims to provide a holistic assessment of coral reef soundscapes in Hawaii, incorporating all of the biotic components without characterizing each individually.

MATERIALS AND METHODS

Data collection and processing

Data were collected in the Northwest Hawaiian Islands (NWHI) during NOAA Remote Areas Monitoring Program Cruise HA-12-04 on the R/V 'Hi'ialakai' during August 2012, and through shore-based operations throughout the main Hawaiian Islands (MHI) over the subsequent 8 wk (Fig. 1 and Fig. S1 in Supplement 1 at www.int-res.com/articles/suppl/m561p069_supp.pdf). Permits for conducting research within the MHI, including some parks and protected areas, were provided by the Hawaii Department of Land and Natural Resources (DLNR Special Activity Permit 2012-83). Permits for conducting research in the NWHI were provided by the Papahānaumokuākea Marine National Monument (PMNM permit PMNM-2012-029). A limited number of sites were visited per island in the NWHI (Fig. S1A–D in Supplement 1) due to weather constraints and cruise scheduling. Acoustic data were not collected at some sites due to timing limitations and hardware failure, although at least 1 recording was obtained from each island in the NWHI and at least 3 from each island in the MHI (Fig. S1E–H). NWHI sites were selected based on prevailing weather conditions and proximity to the station site

Fig. 1. Bathymetric chart of the study area in the Hawaiian Islands. The relative location of the Northwestern Hawaiian Islands (NWHI) and the Main Hawaiian Islands (MHI) is indicated by the white lines. The high latitude and cool tropics habitat regions (oceanographic habitats determined in Freeman et al. 2012) are indicated by the green and red ovals, respectively. Filled white circles indicate the locations of field sites where data were collected for this study. Land is denoted by the solid red color. The color bar indicates depth in meters. Smaller land-masses in the NWHI are too small to be visible at this scale

chosen by the captain of the R/V 'Hi'ialakai'. MHI site selection was based upon ease of accessibility from shore, weather conditions, and safety advice from knowledgeable locals. To mitigate for environmental noise, acoustic data were only collected in fair seas when Douglas Sea State remained between 0 and 4.

Time-lapse photography of benthic organisms

Time-lapse photographic (TLP) data were collected using Canon D10 (or similar) underwater cameras programmed using the Canon Hack Development Kit open-source software package in a manner similar to that described in Freeman et al. (2012). Cameras were programmed to collect one image every 5 min, using flash photography if light levels decreased below a software-determined threshold. Cameras were positioned above the substrate facing downward at a height of approximately 1 m, or so that the field of view encompassed a benthic area of approximately 1 m² (Fig. S2A in Supplement 1). To circumvent use of the autofocus light, which may have elicited a behavioral response from some organisms, each camera was manually focused *in situ*. Care was taken to ensure that cameras were deployed over substrate that was representative of the area. Four cameras were deployed at each site. TLP

data that were limited by a hardware malfunction (fewer than 30 photos or out of focus) were discarded. In many cases, only 2 successful datasets were recorded per site. For sites with 3 or 4 series, only 2 were randomly selected for analysis to ensure consistency. Reef organisms were identified by eye, frame by frame, by trained observers. As the orientation of organisms, image quality, illumination and occluding material increased uncertainty when identifying organisms to the species level, counts of the photographed organisms were divided into the following, clearly identifiable groups: sea urchins (Echinoidea and Cidaroida), crabs (Brachyura), hermit crabs (Paguroidea), brittle stars (Ophiuroidea), starfish (Asteroidea), sea cucumbers (Holothuroidea), fish (Osteichthyes), worms (Annelida and Polychaeta), eels (Muraenidae) and molluscs (Mollusca). These groups were selected based on the ability of

the observers to identify organisms in the photographs, frequency of occurrence, and previous work that linked some of these groups to underwater sounds (Moulton 1957, 1960, Cummings et al. 1964, Tavolga 1964, Amorim et al. 2004, Radford et al. 2008, Patek et al. 2009, Freeman et al. 2014). An example of typical data from a crepuscular period recorded at Kahekili, Maui, is shown in Fig. 2. For each site, the average number of animals per frame was calculated for each group counted (Fig. S3A in Supplement 1). This average is the metric utilized in subsequent statistical analyses.

Stationary point counts of fish

Stationary point count (SPC) methods were based on NOAA Coral Reef Ecosystem Division (CRED) protocols for rapid ecosystem assessment (REA). All surveys were conducted at 10 m depth as fish assemblages at 10 m have been found to be equivalent to those at depths from 1 to 15 m (Friedlander et al. 2003). The observer remained in a stationary position 20 m away from TLP cameras and transect equipment. Fish longer than approximately 250 mm total length that entered a 20 m radius around the SPC diver were recorded during a timed 5 min count. Care was taken to avoid over-counting large transient or schooling

Fig. 2. Example time series of organism counts from time-lapse images taken at Kahekili, Maui. The horizontal axis indicates local time with sunset at 18:36 h, indicated by the vertical black line. Each color indicates a different organism type, stacked to indicate the total number of animals counted per photograph. Individual vertical bars represent one image in the time-lapse image series

fishes that left and subsequently re-entered the area. Observed fishes were identified to the following sub-groups: surgeonfishes (Acanthuridae), parrotfishes (Scaridae), drummers (Kyphosidae), squirrelfishes (Holocentrinae), wrasses (Labridae), jacks (*Caranx ignobilis* and *C. melampygus*), snappers (Lutjanidae), trumpetfishes (*Aulostomus* spp.), sharks (*Carcharhinus galapagensis* and *Triaenodon obesus*), pufferfishes (Tetraodontidae), groupers (*Cephalopholis argus*), scorpionfishes (Scorpaenidae), triggerfishes (Balistidae) and lizardfishes (Synodontidae) (Fig. S3B in Supplement 1). Per NOAA REA protocols, 2 replicate counts were conducted at each site, from which a mean was calculated for subsequent analyses. Group richness and Shannon diversity, an estimate of ecosystem entropy (Pielou 1966), were calculated from both the TLP and the SPC data sets.

Benthic cover from photoquadrats

Photoquadrat transects for the estimation of benthic cover were performed using REA methods utilized by NOAA CRED (Preskitt et al. 2004). Two 25 m transects were laid at a constant 10 m depth across the reef, passing directly under the hydrophone halfway along their length. Photographs were taken using a photoquadrat built to frame an area of 1 m². Photographs were taken every meter, yielding 50 images per site. Ten randomly selected images were then processed using Photogrid photoquadrat image processing software. Due to permitting restrictions, verification of algal species was not conducted as no

samples of algae or other substrate materials could be collected. Five hundred randomly distributed points were evaluated from the 10 images and an overall mean value for the following variables was established: percent cover of live coral, dead coral/rubble, crustose coralline algae (CCA), and fleshy/turf algae, and echinoderms, fish, sponges, reef cavities ('holes' in the reef) and sand/silt.

Passive acoustic data

A Loggerhead Instruments DSG Ocean single-channel, battery-powered acoustic recorder was deployed by divers at each field site for a minimum of 48 h, during which directly observed data collection also took place. The device was secured to the sea floor using a sand anchor in 10 m depth, with the recorder positioned 2 m above the sea floor (8 m depth). The hydrophone employed by the recorder (High Tech, HTI-96-MIN) is largely omnidirectional in the radial direction over the frequency range of interest. The recorder was oriented vertically along a polypropylene line, held upright by a subsurface float (Fig. S2B in Supplement 1) in order to minimize the effects of the hydrophone's directionality and the air-filled battery compartment on the received field. It was assumed that most sound sources were positioned either on or close to the sea floor and that due to the shallow depth, direct and multipath arrivals from these sources arrived predominantly from directions other than the vertical. Hydrophones were deployed only in calm seas (Douglas sea state 0–4), distant from breaking waves to exclude physical environmental noise. Resultant spectrograms were inspected for boat noise and marine mammals. Boat noise was manually excluded when detected. Marine mammals, which create a unique spectral signature, were not detected in the recordings taken during this field campaign.

The recorder was configured to operate at a sample rate of 80 000 samples s⁻¹, with 16-bit resolution. System sensitivity was -165 dB re 1 V μ Pa⁻¹ across the 0 to 20 kHz band. A duty cycle of 4 min of continuous recording every 5 min was employed to ensure battery power and memory capacity remained available over the entire 48 h deployment. Fig. 3 shows a typical 24 h period of recording in calm conditions during which no anthropogenic sound was evident. Sunrise

Fig. 3. Spectrogram showing typical reef sound patterns over a 24 h period from Ahukini, Kauai. The vertical dashed lines indicate (from left to right) sunset and sunrise times. The color scale indicates pressure spectral density (PSD) level

and sunset times were calculated using the GPS-derived coordinates of each field site and a celestial calculator. Spectrograms of recordings from each field site were visually assessed in order to minimize or eliminate periods of recording during which anthropogenic noise, such as divers and boat activity, was evident. One-hour long segments from 2 h before and 1 h after sunrise and sunset (each consisting of twelve 4 min recordings, as sequential as possible) were used for the acoustic component of this study. Spectral estimates used for statistical analysis of the sound field were obtained using a 1024-point fast Fourier transform (FFT) with a 50% overlap, shaded with a Kaiser–Bessel window function ($\beta = 2.5$).

When viewed at sufficient temporal resolution, the underwater biological soundscape near reefs is often characterized by quiet periods broken by highly transient, impulse-like signals (Fig. 4). Two signal processing approaches were utilized to more accurately represent the frequency content of these individual biologically produced sounds and to minimize level bias introduced during the temporal integration necessary during FFTs. The short (1024-point, or 6.4 ms duration) FFT was used to reduce the probability of 2 transient arrivals being smeared together in a single spectral density estimate. Secondly, a temporal intensity filter was applied in which spectral estimates that contained no bin level greater than 102 dB re 1 $\mu\text{Pa}^2 \text{Hz}^{-1}$ were excluded from analysis. These periods of relative quiet were less likely to contain biological sounds of interest and thus would skew means downward and toward lower frequency bins due to ever-present low-frequency wind and

Fig. 4. Spectrogram (A) and associated raw time series (B) of a 2 s recording of ambient coral reef sound, sampled at Lisiansk/Neva Shoals using a 1024-point fast Fourier transform (FFT). An estimate every 6.4 ms reveals high levels of variation in spectral density over much of the band above 2 kHz. Such variation is smeared by longer FFTs as the longer 'snapshot' time combines the spectra of multiple impulse-like arrivals at the hydrophone. The solid red diamonds in both subfigures indicate individual impulse-like arrivals that were retained by the intensity filter. The unique spectrum of each is shown under the solid red diamonds in (A). PSD: pressure spectral density

wave noise. The resultant, concatenated spectral estimates are thus more likely to contain a higher temporal density of biologically produced acoustic information. The intensity threshold value was selected based on the maximum spectral density level produced by the snapping shrimp *Synalpheus parneomeris* (124 dB re 1 $\mu\text{Pa}^2 \text{Hz}^{-1}$ at 1 m depth and 4 kHz frequency; Au & Banks 1998) over a circular area of 500 m^2 around the hydrophone, the approximate area over which visual ecological data were obtained (a circular area of 25 m diameter, the length of the photo transects). While *S. parneomeris* is louder than most reef-dwelling organisms, it is one of very few invertebrates common in Hawaiian waters that has been acoustically characterized. The direct arrival of a 'snap' from *S. parneomeris* at the outer perimeter of the circular area would create a received level of approximately 102 dB re 1 $\mu\text{Pa}^2 \text{Hz}^{-1}$ at the hydro-

phone. While this conservative threshold level reduces the radius of sensitivity for quieter sounds, it serves as a benchmark based on source levels of a known soniferous invertebrate. As a result of filter implementation, analysis was performed on sequential, short periods of louder sounds and not the intervening quiet periods. To reduce the number of acoustic variables, spectral bins were divided into bands between 0.1 and 0.5, 0.5 and 1, 1 and 2, 2 and 7, 7 and 13, and 13 and 20 kHz. The mean (over frequency) per-Hertz pressure spectral density was estimated in each band, before obtaining the average and standard deviation of the respective band values over each hour.

Comparative statistical analysis

Multivariate analyses were performed on both directly observed and acoustic data. These metrics included organism counts, total number of animals present in TLP counts, Shannon–Wiener diversity index and group richness from both SPC and TLP data. Acoustic variables for multivariate analysis were divided by time of day at which recordings were sampled (pre-sunrise, morning, afternoon and evening). All variables were normalized to a mean of 0 and a standard deviation of 1. A principal component analysis (PCA) was then conducted with the normalized multivariate data to ascertain the inter-relatedness between various data metrics and sites. Zero-inflated metrics were excluded from the PCA (Zuur et al. 2010). The PCA results presented here include a limited number of variables found to be most significant in earlier iterations. Pearson's correlations between all variables, including acoustic variables recorded at different times of day, were calculated over all field sites. Metrics for which Pearson's ρ values were greater than 0.6 with $p < 0.001$ (Bonferroni correction) were considered to be sufficiently correlated and were subject to further analysis. Correlations of particular interest were those that appeared to form a distinct pattern across several metrics (i.e. a high degree of correlation between the presence of an organism and multiple acoustic frequency bands) (Table S2 in Supplement 2 at www.int-res.com/articles/suppl/m561p069_suppl.xlsx).

RESULTS

Field sites ranged from intact coral reefs to rubble-strewn sand and algal mats. Fig. 5 provides an indication of the diversity of local environments sampled in this study. Similar data from TLP and SPC data collections are provided in Fig. S3 in Supplement 1. Stronger associations between acoustic and directly observed variables provide the basis for creating ecological proxies based on acoustic recordings. Consequently, observed relationships between the soundscape and visually obtained data are reported here, rather than the absence of correlative links. PCA outputs (Fig. 6) and Pearson's correlations (Table 1) reveal associations between acoustic variables and observations from TLP, SPC and photoquadrat data that were consistent across the entire Hawaiian archipelago, and within the 2 oceanographic habitats considered (Freeman et al. 2012).

TLP-derived benthic invertebrate counts (hermit crabs and urchins) were correlated with mean

Fig. 5. Benthic composition estimates of individual sites in the Hawaiian Islands (see Fig. S1, Table S1 in Supplement 1 at www.int-res.com/articles/suppl/m561p069_suppl.pdf). The proportions shown here were obtained from photoquadrat image analysis for each individual site (listed on the horizontal axis). The relative proportion of each bottom type is shown by the height of the color bar, stacked to show the full composition of each site. The results shown here are average percent benthic cover per site. Sites are ranked in order of decreasing latitude. KUR: Kure Atoll, PHR: Pearl and Hermes reef, LIS: Lisianski Island, FFS: French Frigate Shoals, KAU: Kauai, OAH: Oahu, MAU: Maui, BIG: Big Island

Fig. 6. Principal component analysis of passive acoustic, remote camera and directly observed ecological variables for 17 coral reef sites in the Hawaiian Islands (see Fig. 5 for abbreviations and Fig. S1, Table S1 in Supplement 1 for locations). The first 2 components plotted here explain 68% of the total variance. Black lines and filled circles indicate directly observed, non-acoustic variables. Grey lines and filled circles indicate mean acoustic pressure spectral density levels during the periods and within the bands indicated (k: kHz). Dark blue and cyan triangles indicate the position of field sites within the 'cool tropics' and 'high latitudes' oceanographic regimes, respectively (Freeman et al. 2012). A general trend from 07:00 to 14:00 h is evident in the sites ranging from more algae-dominated to more coral-dominated, which is also reflected in the acoustic metrics with low-frequency sounds characterizing reefs with positive ecological indicators, and high-frequency sounds characterizing reefs with negative ecological indicators

sound levels in the 1 to 2 kHz and 500 Hz to 1 kHz bands before dawn and in the morning, respectively (Fig. 7A,B). Sound levels in these same frequency bands were also correlated with SPC counts of reef-based predators of benthic fauna, such as triggerfish (*Melichthys* and *Rhinecanthus* sp., Fig. 7C) and peacock grouper (*Cephalopholis argus*, Fig. 7D).

Correlations were also observed between photoquadrat-derived benthic cover estimates and specific components of the acoustic spectrum. Rugosity (small-scale bottom complexity, obtained through direct measurement) and reef cavities (obtained through photoquadrat estimates) are both indicators of centimeter-scale surface roughness. These 2 data sets were obtained through unique methods. Both were correlated with low-frequency biological sounds in the 100 to 1000 Hz bands (Fig. 8). Rugosity (Fig. 8A) was positively correlated with mean sound levels in the 100 to 500 Hz and 500 Hz to 1 kHz bands recorded in the afternoon and evening, respectively. Reef cavities (Fig. 8B) were positively correlated with

mean sound levels in the 100 to 500 Hz band during all periods of recording. The proportion of hard reef substrate covered by CCA was correlated with mean sound levels in the 100 to 500 Hz and 500 Hz to 1 kHz bands, recorded during the day and after sunset, respectively (Fig. 9). Most correlations between directly observed and acoustic data pertained to sound below 2 kHz. However, photoquadrat-derived estimates of the proportion of substrate covered by fleshy macroalgae were correlated with almost all daytime acoustic metrics in the 2 to 20 kHz bands (Fig. 10).

DISCUSSION

The inclusion of a wide range of field sites along the Hawaiian Island chain provides broad-reaching inferences regarding associations of specific bandwidths with indicators of coral reef ecological state. Multivariate analysis teases apart local variation

Table 1. Correlations between ecological variables and mean acoustic pressure spectral density of coral reef sites in the Hawaiian Islands. Pairs of ecological and acoustic variables for which Pearson's correlation coefficient values were equal to or greater than 0.6 are shown (the complete data set is available in Table S2 in Supplement 2 at www.int-res.com/articles/suppl/m561p069_supp.xlsx). Acoustic recording periods are described by the time of day. Also shown are the acoustic frequency bands from which pressure spectral densities were obtained, as well as Pearson's correlation coefficient ρ . CCA: crustose coralline algae

Ecological variable	Time of day	Acoustic frequency band (kHz)	Pearson's coefficient, ρ
Urchin sp. (mean no.)	Morning	0.5–1	0.76
Hermit crab sp. (mean no.)	Pre-sunrise	1–2	0.61
	Afternoon	1–2	0.61
Triggerfish sp. (mean no.)	Evening	1–2	0.65
Peacock grouper (mean no.)	Morning	0.5–1	0.8
	Afternoon	0.5–1	0.61
Rugosity	Afternoon	0.1–0.5	0.6
	Evening	0.1–0.5	0.62
Reef cavities (% cover)	Pre-sunrise	0.1–0.5	0.6
	Morning	0.1–0.5	0.61
	Afternoon	0.1–0.5	0.67
	Afternoon	0.5–1	0.73
	Evening	0.1–0.5	0.66
	Evening	0.5–1	0.63
CCA (% cover)	Morning	0.1–0.5	0.61
	Afternoon	0.1–0.5	0.61
	Afternoon	0.5–1	0.62
	Evening	0.1–0.5	0.6
Fleshy algae (% cover)	Morning	2–7	0.63
	Morning	7–13	0.7
	Morning	13–20	0.68
	Afternoon	2–7	0.67
	Afternoon	7–13	0.68
	Afternoon	13–20	0.67

(Radford et al. 2010) from ecosystem-wide trends. Correlations between ecosystem indicators and components of the soundscape cannot provide definitive explanations of cause and effect. Apart from unknowns regarding how, why and what fauna create these sounds, the quantification of attenuation and scattering from highly heterogeneous substrates and complex bathymetry is also necessary to fully understand the connection between biological soundscapes and the organisms that create them.

In general, greater sound levels in the band below 1 kHz were associated with sites characterized by positive ecological metrics such as greater CCA cover, bathymetric complexity (associated with branching coral structures) and numbers of benthic organisms. Sites that were characterized by high levels of fleshy macroalgae, an indicator of a coral reef in decline or one in which an ecological shift to a more degraded state had occurred, were simultaneously characterized by relatively greater sound levels at higher frequencies (2 to 20 kHz). The PCA results

show frequency-gradated structure from left (high-frequency acoustic metrics, more degraded reef sites) to right (low-frequency acoustic metrics, more intact reef sites), nearly along the first principal component, which explained 43 % of the variance. Generally, the least degraded reefs, including several in marine protected areas, aligned towards the 2 o'clock position, while the more degraded reefs aligned towards the 7 o'clock position (Fig. 6).

The mapping of reef state along the first principal component is more pronounced when oceanographic habitat is considered (Figs. 1 & 6) (i.e. only the cool tropics reefs or only the high latitude reefs from Freeman et al. 2012). Measurements, particularly of algae-related metrics, from the high-latitude reefs may be confounded by differing oceanographic conditions in those areas (cooler temperatures, higher frequency of winter storms, etc.) that produce more favorable environments for algal growth. Consequently, reefs in this region may be associated with increased levels of higher frequency sound even if they

are relatively undisturbed (i.e. Kure Atoll, Fig. 10). This acoustic delineation may be important for passive acoustic monitoring in the study of climate change impacts, which are projected to be less severe in the high latitude reefs than the cool tropics reefs (Freeman 2015).

Sound levels below 1 kHz appear to be associated with indicators of a healthy coral reef ecosystem state. Studies in other regions (Piercy et al. 2014, Kaplan et al. 2015) have also observed a positive correlation between spectral levels in this band and indicators of ecosystem function. It is intuitive to surmise that greater numbers of acoustically active organisms would create louder biological soundscapes. However, the correlation between sound, rugosity, benthic porosity and CCA cannot be explained directly. Bottom roughness and CCA do not create sound by themselves, thus an additional layer of interaction between these environmental aspects and soniferous organisms must exist. The acoustic metrics derived from recordings at sites that are more disparate ecologically

Fig. 7. Correlation between benthic organisms, their predators and low-frequency acoustic pressure spectral density (PSD) at coral reef sites in the Hawaiian Islands (see Fig. 5 for abbreviations and Fig. S1, Table S1 in Supplement 1 for locations). Time-lapse photography (TLP)-derived (A) hermit crab counts, (B) urchins, stationary point count (SPC)-derived (C) triggerfishes and (D) peacock groupers shown against mean PSD levels of correlated acoustic bands and times of day. The left axes indicate the logarithm of organism counts, while the right axes indicate mean PSD levels in dB re 1 $\mu\text{Pa}^2 \text{Hz}^{-1}$. The horizontal axis indicates sites from which both data sets were available

(i.e. Ke'ei on the Big Island, Fig. 8) follow the correlative trend of greater sound levels at higher frequencies in more degraded ecosystems, and greater sound levels at low frequencies in more intact ecosystems, suggesting that the relationships between certain aspects of the soundscape, benthic algae and topography remain intact across very different reef ecosystem states.

The presence of some benthic organisms and their predators (Figs. 6 & 7) was associated with sound levels in low-frequency bands (generally 100 Hz to 1 kHz). The low-frequency sounds produced by invertebrates have been associated with feeding and motion (Radford et al. 2008, Freeman et al. 2015). Low-frequency sounds produced by predatory fishes (triggerfishes, groupers) in the same band have been associated with territorial and conspecific interactions (Tricas & Boyle 2014). Such communication between these predators shows that they are sensitive to sounds at frequencies less than 1 kHz. It is thus possible, although unproven, that adult fishes use invertebrate sound to locate areas with greater

numbers of potential prey. While the use of ambient underwater sound as a cue for larval fishes has been well studied (Simpson et al. 2004, 2005, Montgomery et al. 2006, Radford et al. 2007), the use of sound to guide adult fish to a food source has not been rigorously studied. The results shown here do not preclude such behavior.

The similar correlations between low-frequency (100 Hz to 1 kHz) sound levels with rugosity and the occurrence of reef cavities (Figs. 6 & 8) strengthen the link between these sounds and bathymetric complexity at centimeter scales. These 2 variables were sampled through independent means, each with a unique susceptibility to bias. Rugosity measurements, collected by divers using a fine chain and measuring tape, can be prone to bias through underestimation of bottom complexity as any tension on the measuring chain reduces estimates of surface roughness. Photoquadrat-derived estimates of reef cavity cover are subject to completely different bias mechanisms, such as the influence of incident light in illuminating or shading parts of the benthos, remov-

Fig. 8. Correlation between reef structure and low frequency acoustic pressure spectral density (PSD) at coral reef sites in the Hawaiian Islands (see Fig. 5 for abbreviations and Fig. S1, Table S1 in Supplement 1 for locations). (A) Rugosity ratio estimates and (B) photoquadrat (PQ)-derived reef cavities against mean PSD levels of correlated acoustic bands and times of day. The left axes indicate the logarithm of rugosity ratio in (A) and the logarithmic proportion of photoquadrat images identified as deep holes in the reef in (B). The right axes indicate mean PSD levels in dB re 1 $\mu\text{Pa}^2 \text{Hz}^{-1}$. The horizontal axis indicates sites from which both data sets were available

ing or producing the appearance of deep holes in the reef surface, respectively. The mechanisms behind these correlations are likely driven by the increased roughness providing more preferable habitat for cryptic organisms known to create sounds in these acoustic bands. Greater benthic complexity offers increased surface area for sessile food sources, and more opportunity to avoid predation through remaining hidden in the often complex labyrinth of subsurface voids and overhanging environments typically found on a healthy coral reef.

In addition to rugosity and surface porosity, sound levels in the 100 Hz to 1 kHz bands during all times of day was correlated with CCA. Rugosity and CCA are associated with a more intact coral reef ecosystem. CCA contributes significantly to reef calcification and formation, binding coral and rubble together

and, as a result, increasing resistance to storms (Fabricius & De'ath 2001). CCA increases the complexity of structures within the reef and the volume of available habitat for subsurface reef creatures (Birrell et al. 2008), thus CCA is also positively related to rugosity and surface porosity. Surfaces covered in CCA are preferred settlement sites for coral planulae (Tebben et al. 2015). The presence of CCA is also an indicator of active herbivory, as CCA must be cleaned of fleshy algae that continually colonize its surface (Steneck 1983). The relative abundance of CCA, and its correlation with low-frequency biological sound, further indicates that sound levels in the bands below 1 kHz are positively associated with many aspects of a healthy coral reef state.

It should be noted that while many marine organisms are known to produce sound below 1 kHz, physical processes such as sea state and breaking waves, and anthropogenic sources such as vessel traffic also ensonify this band. Care was taken both in the field, with site selection and deployment timing, as well as during processing, to minimize and remove noise from boat traffic and breaking waves. No marine mammals were observed or recorded during deployments.

The dominance of fleshy macroalgae over reef-building corals is an indicator of a degraded ecosystem state (Pandolfi et al. 2005). The results show that the proportion of fleshy algae covering hard substrate correlates with most acoustic metrics between 2 and 20 kHz, but only from recordings taken

during the day (Fig. 10). The uniformity of correlation between algal cover and acoustic variables from these acoustic bands was further underscored by the lack of correlation between these bands and any other directly observed metrics. The causal connection between high-frequency sound levels and macroalgae cannot be determined from the information published here. However, a causative link between high-frequency components of the soundscape and algal cover may involve the association between algae and acoustically active fauna that may graze on or reside in habitat created by fleshy algae. Sounds created by snapping shrimp dominate the high-frequency component of the soundscape in many coastal areas (Au & Banks 1998). It is possible that areas covered by higher proportions of fleshy algae are preferred habitats for some species of snapping

Fig. 9. Correlation between crustose coralline algae (CCA) and low-frequency acoustic pressure spectral density (PSD) at coral reef sites in the Hawaiian Islands (see Fig. 5 for abbreviations and Fig. S1, Table S1 in Supplement 1 for locations). Photoquadrat (PQ)-derived CCA cover against mean PSD levels of correlated acoustic bands and times of day. The left axis indicates the log proportion of photoquadrat images covered by CCA, while the right indicates mean PSD levels in dB re $1 \mu\text{Pa}^2 \text{Hz}^{-1}$. The horizontal axis indicates sites from which both data sets were available

Fig. 10. Correlation between fleshy macroalgae cover and high-frequency acoustic pressure spectral density (PSD) at coral reef sites in the Hawaiian Islands (see Fig. 5 for abbreviations and Fig. S1, Table S1 in Supplement 1 for locations). Photoquadrat (PQ)-derived fleshy macroalgae cover against mean PSD levels of correlating acoustic bands and times of day. The left axis indicates the log proportion of photoquadrat images covered by fleshy macroalgae, while the right indicates mean pressure PSD levels in dB re $1 \mu\text{Pa}^2 \text{Hz}^{-1}$. The horizontal axis indicates sites from which both datasets were available

shrimp, and that their presence contributes to an indirect association between algae and high-frequency sounds. Nondestructively determining whether there is any such relationship may be challenging as snapping shrimp are usually subterranean creatures and

are rarely observed above the substrate. Directional acoustic receivers may be employed to determine the location of snaps in an area (Ferguson & Cleary 2001, Chitre et al. 2012, Kaplan et al. 2015), producing estimates of snapping shrimp distribution in a localized area. Regardless of the process that connects high-frequency sound and the proportion of algal cover, the correlative findings shown here introduce the possibility of an acoustic indicator of algal dominance, and in some situations, of reef degradation. Controlled studies that exclude soniferous fauna are required to conclusively evaluate the mechanisms behind the association between algae and high-frequency components of the soundscape.

The passive acoustic evaluation techniques discussed here are not limited to use in shallow-water coral reef environments. Any underwater environment in which organisms ensnare the medium may be subject to passive ecological monitoring. These techniques may be particularly useful in environments that are difficult to access, such as benthic ecosystems under ice or those in deep water. Modern battery performance now enables multi-year deployments of persistently recording remote acoustic sensors. Recorders in shallow water equipped with satellite telemetry could relay data products, processed on-board, in real time. Such sensors are routinely mounted on autonomous vehicles, enabling the acoustic survey of large areas in relatively short time frames. However, different types of ecosystems may produce unique ecological-acoustic associations that would require independent validation.

The single hydrophone recorders used in this study, and most other underwater soundscape studies, are largely omnidirectional and do not permit sound source localization or spatial filtering of undesirable noise. These limitations are significant shortcomings that can be overcome using directional receivers such as hydrophone array systems and associated array processing algorithms. In a shallow-water coral reef environment, benthic

sound sources are sandwiched between the pressure-release surface and a hard bottom consisting of limestone bedrock. Consequently, the environment is a highly reverberant one, further complicated by scattering from the intricate wavelength-scale geo-

metries of reef-building corals. While this study observed correlations between recordings made by a single hydrophone and high-level ecological metrics, more detailed analysis of underwater soundscapes will most likely require directional receivers in order to filter out unwanted noise from other parts of the reef and from non-biological sources. Furthermore, in addition to array gain, modern array processing techniques such as adaptive and compressive beamforming (Cox et al. 1987, Edelmann & Gaumond 2011) may be applied to further enhance the spatial resolution of directional recorders in this setting.

CONCLUSIONS

This study reports on correlations between aspects of the underwater biological soundscape and concurrent, visually observed ecological metrics over the Hawaiian Islands archipelago. The associations remain consistent across substantially varying local underwater environments, implying that they represent the more fundamental ecological processes that characterize different types of underwater ecosystems in the archipelago. The relationships between acoustic metrics and coral reef ecological metrics are most pronounced when controlling for oceanographic habitat, suggesting that comparative acoustic metrics function best when sampling is conducted across an area homogeneous in oceanographic regime. Trends in coral reef state were identified that may be ascertained solely from acoustic metrics as a means of large-scale, passive remote monitoring. A frequency-dependent gradient was observed, where less impacted sites are typified by a low-frequency dominated soundscape, and greater high-frequency ambient sound levels typified sites where algae dominated the benthic structure. Positive correlations between low-frequency (<1 kHz) components of the soundscape and benthic invertebrates, predators of benthic invertebrates, centimeter-scale bathymetric complexity and CCA suggest that sound levels in this band may be positively associated with habitat availability and the density of benthic fauna. Positive correlations between components of the soundscape in the 2 to 20 kHz band and algal cover infer a connection between fleshy algae, an indicator of reef degradation, and higher frequency sound. The correlations reported here between directly observed ecosystem metrics and aspects of the biological soundscape encourage further, large-scale work toward the passive acoustic monitoring of reef environments. These results present the possibility of a more integrative,

deterministic and non-destructive means of evaluating ecosystem state that is unconstrained by the bias and error associated with traditional diver-based ecosystem monitoring techniques. The required technology exists in an inexpensive, field-proven form today, and our knowledge of underwater acoustic propagation and signal processing benefits from vast and exhaustive research efforts, albeit for military purposes, over the last 70 years. Such knowledge and mature technology, when brought to bear on complex problems such as ecological monitoring, could dramatically improve accuracy and spatiotemporal resolution when estimating the actual *in situ* impacts of overfishing, pollution, shipping, tourism and climate change.

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