1. INTRODUCTION

Foraging behaviour is a large part of the daily routines of many species and an essential link between prey availability and predator reproductive success. For central-place foraging species, including many birds, a key issue in this context is the extent of behavioural flexibility in response to changing environmental conditions encountered during trips, especially when parents need to travel long distances to obtain prey (Tarroux et al. 2016, Kokubun et al. 2018). Wind is a major component of the environmental conditions experienced by birds (Hernández-Pliego et al. 2017, La Sorte & Fink 2017), and increases in mean wind speeds and storm frequencies are predicted to occur as a result of anthropogenic climate change, particularly in mid-latitudes (McInnes et al. 2011, Young et al. 2011), along with increases in the frequency and intensity of extreme weather events (Coumou et al. 2015). Yet while research on the biological impacts of global climate change has focused extensively on the effects of changes in temperature and rainfall (Terraube et al. 2017, Zuckerberg et al. 2018), impacts of changing wind conditions have received much less attention (Elliott et al. 2014).

Marine birds are particularly exposed to wind conditions while foraging at sea and during commutes between terrestrial breeding sites and marine foraging grounds. Wind also influences wave patterns and turbulence (Salisbury et al. 2013, Albert et al. 2016),...
which can alter the vertical distribution of forage fish in the water column and make them more difficult for surface-feeding and shallow-diving birds to locate and pursue (Konarzewski & Taylor 1989, Finney et al. 1999, Baptist & Leopold 2010, Parker-Stetter et al. 2016), while adverse winds may also reduce the speed with which parents can return to feed their offspring and relieve their partner at the nest. Many seabirds forage over large areas of ocean, so how they are affected by wind conditions encountered at sea may thus have important consequences for trip durations, nest attendance patterns and chick provisioning rates. Yet while a number of recent studies have examined changes in flight behaviour and energy expenditure in relation to wind conditions (Kogure et al. 2016, Gibb et al. 2017, Goto et al. 2017, Shepard et al. 2019), impacts on time–activity budgets and overall foraging routines have rarely been examined (Lewis et al. 2015).

Wind conditions also influence flight heights of birds (Krüger & Garthe 2001, Villegas-Patraca & Herrera-Alsina 2015, Tarroux et al. 2016). Over both land and open water, flying lower into head winds allows birds to take advantage of wind shear, where wind speed may be reduced by ~15−20% at heights below 4 m, while flying less than 1.5× wingspan above the surface also allows birds to utilise ground effect, where lift is increased and aerodynamic drag is decreased as a result of the ground interrupting wingtip vortices and downwash behind the wing (Rayner 1991, Finn et al. 2012). Hence flying close to the surface reduces flight costs when flying into head winds while flying higher with tail winds enables faster and more efficient flight (Liechti et al. 2000, Krüger & Garthe 2001, Green 2004). Adjustments in flight height may thus be an important component of seabirds’ responses to changing wind conditions at sea, but there are few previous data to address this question. For seabirds that exploit prey close to the water surface, foraging efficiency may also be influenced by rainfall, but the effects of rain on foraging behaviour are poorly understood (Pistorius et al. 2015).

Northern gannets Morus bassanus (hereafter gannets) are plunge-diving predators that obtain most of their prey within 10 m of the water surface (Lewis et al. 2002, Cleasby et al. 2015a). During chick-rearing, adults make foraging trips lasting up to 1 d or longer and covering 10s to 100s of km (Hamer et al. 2000, Wakefield et al. 2013). Flight comprises ~50% of total trip time, and the dive rate of birds per daylight hour is apparently unrelated to trip duration (Lewis et al. 2004). Birds can reduce time away from the nest by returning to the colony at greater speeds from more distant foraging locations, but speeds decrease for the furthest destinations, probably due to constraints on energy expenditure during sustained flight (Hamer et al. 2007). Energy expenditure in flight is also strongly affected by wind speed and direction (Amélineau et al. 2014), but it is not clear how wind conditions affect birds’ average speed of travel at sea or to what extent they can adjust their behaviour to reduce potential impacts of adverse wind conditions on time away from the nest. In addition, birds fly higher when actively foraging than when commuting between the nest site and foraging sites (Cleasby et al. 2015b), but it is not known how wind conditions or rainfall affect flight heights during commuting or foraging. Here, we investigated variation in the 3-dimensional foraging behaviour of gannets in response to weather conditions in the North Sea. We first examined how wind speed and direction and rainfall affect birds’ foraging trip durations and time–activity budgets at sea. We then assessed how wind conditions affect birds’ speed of travel and to what extent birds adjust their time–activity budgets to reduce the impact of adverse wind conditions on their rate of return to the nest from distant foraging sites. We next examined the influence of wind and rainfall on the flight heights of birds during commuting and active foraging.

2. MATERIALS AND METHODS

2.1. Study site and data collection

Fieldwork took place at Bass Rock, UK (56° 6’ N, 2° 36’ W) between mid-June and mid-August of 2015–2017. In total, 63 adult gannets with chicks were caught at the nest using a 6 m telescopic pole fitted with a metal noose or hook. Each bird was fitted with a metal British Trust for Ornithology ring and a coloured plastic ring with a unique alphanumeric code for easy identification at the nest site. We then recorded body mass to the nearest 10 g using an electronic scale. Each bird had a GPS logger (igotU-GT600, Mobile Action Technology) attached to the upper side of the central tail feathers and a logger recording atmospheric pressure and temperature (MSR-145W, MSR Electronics) attached to the central tail feather, on the underside to reduce Bernoulli effects during take-off from the water. GPS loggers weighed 30 g and recorded location at 2 min intervals; pressure loggers weighed 18 g and recorded at 1 Hz; both were attached using Tesa© tape. All sampled birds were recaptured after 7−14 d to retrieve loggers. Handling time of birds at both deployment
and recapture was no longer than 15 min, and on both occasions birds returned to their chick almost immediately and resumed normal behaviour. The combined weight of loggers was <2% of body mass, which was well within recommended guidelines (Phillips et al. 2003); previous studies at this colony recorded that such deployments had no discernible impact on trip duration or body mass (Hamer et al. 2007, 2009, Cleasby et al. 2015a).

2.2. Trip analysis

For each foraging trip we determined the duration (h), total distance travelled (km), maximum distance (km) on a direct bearing from the colony and departure angle (degrees) from the colony (an average of the first 5 bearings >10 km from the colony; Patrick et al. 2014). We used the furthest location from the colony to distinguish between outbound and inbound stages of each trip; inbound distance was the total distance travelled from the furthest location back to the colony. We also calculated the direction of travel throughout each trip as the bearing between successive locations. In addition, speeds and turning angles derived from GPS data were used to classify the behaviour of birds at sea into 3 categories: commuting, characterised by long step lengths and small turning angles; active foraging, characterised by short step lengths and large turning angles; and time spent on the water, characterised by short step lengths and small turning angles (Wakefield et al. 2013, Amélineau et al. 2014, Grecian et al. 2018). Validation of these discrimination criteria against a separate sample of birds equipped with GPS loggers and time−depth recorders (TDRs) showed that, within individuals, 99% of GPS locations occurring within 10 min of dives detected using TDRs were classified as foraging (Wakefield et al. 2013).

2.3. Weather conditions

We obtained data on wind speed and direction and rainfall during foraging trips from the ERA-Interim reanalysis data set produced by the European Centre for Medium-Range Weather Forecasts (ECMWF) (6-hourly data at 0.125 × 0.125° or approximately 8 × 8 km resolution) (Dee et al. 2011). For every bird location at sea, we extracted the nearest data in time and space for rainfall (mm h−1) and 10 m zonal (west-east) and meridional (south-north) wind components at 10 m a.s.l. (max. distance: 4 km; max. time difference: 3 h). We then calculated wind speed (m s−1) and direction (°) using Eqs. 1 and 2, respectively:

\[ W_s = \sqrt{U_w^2 + V_w^2} \tag{1} \]

\[ W_v = \frac{180}{\pi} \arctan(V_w, U_w) \tag{2} \]

where \( W_s \) = wind speed, \( U_w \) = zonal wind component, \( V_w \) = meridional wind component and \( W_v \) = meteorological wind direction.

Following Amélineau et al. (2014), we used bird−wind angle (BWA) to characterise the relationship between wind direction and the bird’s direction of travel. Absolute values of 0–45° (i.e. up to 45° to left or right of bird’s heading) were categorised as head winds, 45–135° as cross winds and 135–180° as tail winds.

2.4. Flight height estimation

Following Cleasby et al. (2015b), we used the barometric equation to estimate the height of the bird (h) above sea level:

\[ h = \frac{K T}{m g} \ln \left( \frac{P}{P_0} \right) \tag{3} \]

where \( P_0 \) and \( P \) are the atmospheric pressures (Pa) at sea level and at height \( h \) (m) respectively; \( K \) is the universal gas constant for air (8.31432 N m mol⁻¹ K⁻¹); \( m \) is the molar mass of air (0.0289644 kg mol⁻¹); \( g \) is the acceleration due to gravity (9.80665 m s⁻²); and \( T \) is the temperature (K) of the atmosphere between \( h_0 \) and \( h \) (see Supplement 1 at www.int-res.com/articles suppl/m628p183_supp.pdf). We obtained calibration pressures (\( P_0 \)) when birds spent time on the water (Cleasby et al. 2015b) and we accounted for spatial and temporal changes in atmospheric pressure during long periods of sustained flight by adjusting calibration pressures throughout the duration of each flight bout using the ERA-Interim reanalysis sea surface pressure data set (6-hourly data at 0.125 × 0.125° or approximately 8 × 8 km resolution) (Dee et al. 2011).

2.5. Statistical analysis

All analyses were conducted using R v.3.2.2 (R Core Team 2016). We used linear mixed-effects models (LMMs) fitted using the R package ‘nlme’ (Pinheiro et al. 2018) to examine how wind speed, direction and rainfall affected trip durations and the proportion of each trip spent actively foraging, commuting and on
the water. Our rationale here was that birds show pronounced individual foraging site fidelity during chick-rearing (Hamer et al. 2001, Wakefield et al. 2015), so the distance travelled on each trip was modelled as a predictor variable that, together with different weather variables, could potentially affect both total trip duration and the proportion of time spent in different activities per trip. We included a mean value for wind speed, wind direction and rainfall per hour for each trip and we included year as a fixed effect to account for differences in trip parameters between years. We also included bird identity as a random effect to control for differences in trip parameters between years. We included bird identity as a random effect to control for repeated measures due to multiple trips per bird. Continuous predictor variables were normalised to increase the interpretability of parameter estimates (Schielleth 2010), and we tested for collinearity between predictor variables to ensure this would not cause difficulties for determining true relationships (Freckleton 2011).

In view of the large number of predictor variables and potential interactions, model simplification and selection were performed using a multi-model inference approach based on the methods and recommendations of Grueber et al. (2011), using the ‘MuMln’ package (Barton 2015). A set of candidate models was first identified for each response variable, with all possible subsets of predictor variables and interactions considered. Support for different candidate models was then assessed using Akaike’s information criterion adjusted for small sample size (AICc) and Akaike weights. Models with the greatest raw AICc weight and a ΔAICc > 2 from the next ranked model were considered to have the best model fit (Burnham & Anderson 2002), but where there was uncertainty over the top model, parameter estimates and the relative importance of each parameter were averaged across selected models, with test statistics and p-values extracted using MuMln.

To assess how wind conditions influenced flight speed and whether or not gannets adjusted their behaviour to compensate, we first used a LMM to examine how mean wind speed and direction affected mean ground speed during periods of commuting flight. This analysis included foraging trip identity nested within bird identity as a random effect, to account for repeated measures within each foraging trip and multiple trips per bird. A temporal autocorrelation structure was included to control for non-independence of successive data within each trip. We then used a linear model (LM) to examine the influence of wind speed on flight heights. For this analysis, wind speeds were binned at 1 m s\(^{-1}\) intervals, with head winds having negative speeds and tail winds positive speeds, and a mean height was used for each wind speed interval. Heights were right-skewed and were therefore square-root transformed prior to calculating means. Some estimated flight heights were below 0 m and, following Cleasby et al. (2015b), these were retained in the analysis by adding the minimum estimated height (absolute value) to all cases to permit square root transformation.

3. RESULTS

We acquired combined GPS and altitude data for 188 trips by 46 individuals (106 trips by 29 birds in 2015; 47 trips by 16 birds in 2016; 35 trips by 13 birds in 2017; data from 17 birds were incomplete). Most trips travelled northeast or southeast of the colony, with fewer travelling due east (Fig. 1). The prevailing wind direction was from the southwest (Fig. S1 in Supplement 2) and accordingly, birds spent most of their time in flight with cross winds and tail winds when commuting away from the colony, and with head winds and cross winds when returning to the colony (Fig. 2a,c). When actively foraging, however, birds spent significantly more time flying into the wind (mean ± SD: 33 ± 14 %) and less with the wind behind them (18 ± 10 %) than expected by chance (Fig. 2b; \(\chi^2 = 511.0, p < 0.0001\); birds frequently
changed direction while actively foraging so would have been expected by chance to spend 25% of their time with head winds, 50% with cross winds and 25% with tail winds).

3.1. Trip durations and time–activity budgets at sea

The mean duration of foraging trips was 24.3 ± 10.7 h (range: 1.5–70.3 h). Both trip duration and the proportion of each trip spent commuting were significantly positively related to total distance travelled (Fig. 3; LMM; $\chi^2_1 = 378.5$, $p < 0.001$ and $\chi^2_1 = 57.1$, $p < 0.001$, respectively) but no weather variables improved either model ($\Delta\text{AIC}_c > 5$ for trip duration, $>2$ for proportion of trip commuting; $\text{AIC}_c$ weight dropped from $>0.8$ to $<0.1$ and from $>0.5$ to $<0.2$, respectively; Table 1). The proportion of time spent actively foraging per trip increased significantly with increasing wind speed (Fig. 3c; $\chi^2_1 = 14.6$, $p < 0.001$) but the model was not improved by including any other variable ($\Delta\text{AIC}_c > 5$ in each case; Table 1). There was no clear top model for the proportion of daylight hours spent on the water, but model averaging of the top 3 models (i.e. those with $\Delta\text{AIC}_c < 2$; Table 1) found distance travelled per trip and wind speed to be the most significant factors (Table 2), indicating that the proportion of time on the water decreased as distance travelled increased and with increasing wind speed (Figs. 3d & 4).

Fig. 1. Tracks of foraging trips (n = 263) by adult northern gannets rearing chicks at Bass Rock between mid-June and mid-August of 2015–2017. Red dots: maximum distance from the colony on each trip; yellow triangle: colony location

Fig. 2. Frequency distribution of bird–wind angles for GPS locations of northern gannets during (a) outbound commuting (n = 19 238 locations), (b) active foraging (n = 20 446) and (c) inbound commuting (n = 21 233)
3.2. Flight speeds and rates of return to the nest

During periods of commuting, whether outbound or inbound, ground speeds were faster with a tail wind component than with a head wind component (LMM; \( \chi^2 = 301.5, p < 0.001 \); mean ± SD: 17.5 ± 3.4 and 12.6 ± 2.0 m s\(^{-1}\), respectively). As expected, ground speeds increased as the tail wind component increased and the head wind component decreased (Fig. 5a; \( \chi^1 = 278.67, p < 0.001 \)). The average speed of travel over the return leg of a trip was significantly related to both distance from the colony and distance\(^2\) (LMM; \( \chi^2 = 14.0, p < 0.001 \) and \( \chi^1 = 5.9, p < 0.05 \), respectively) indicating a non-linear relationship with distance, while the best-performing model according to AIC\(_c\) also included wind speed and direction (Table 3): average travel speed increased with increasing distance from the colony up to 100–200 km (fastest for birds returning with a tail wind, slowest for those returning into a head wind), beyond which the relationship levelled off (Fig. 5b). Time spent on the water during the return leg of a trip was also significantly related to inbound distance travelled (\( \chi^1 = 5.9, p < 0.05 \)) with the best-supported model also including distance\(^2\) and wind speed and direction (Table 3). For return legs up to 100–200 km, time on the water decreased with increasing distance and was greatest for birds returning with a tail wind and least for those returning into a head wind (Fig. 5c).

3.3. Flight heights

Median flight height was significantly lower during periods of commuting than active foraging (LMM; \( \chi^1 = 4.75, p < 0.05 \); Table 4) but was unaffected by rainfall. Birds also flew lower into head winds than with tail winds when commuting (\( \chi^1 = 37.6, p < 0.001 \)) but not while actively foraging, when median height was ~28 m irrespective of wind direction (Table 4). In addition, commuting flight heights increased with increasing tail wind speed and decreased as head wind speed increased (LM; \( F_{1,18} = \))
Table 1. Top model sets for estimating effects of weather parameters on different components of northern gannet behaviour during foraging trips. LogLik: log-likelihood; AICc: Akaike’s information criterion corrected for small sample size.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Estimate</th>
<th>Confidence interval</th>
<th>p</th>
<th>Relative importance</th>
</tr>
</thead>
<tbody>
<tr>
<td>Trip distance</td>
<td>5.13</td>
<td>-0.56 to -0.27</td>
<td>&lt;0.001</td>
<td>1.0</td>
</tr>
<tr>
<td>Wind speed</td>
<td>-0.42</td>
<td>-0.42 to -0.43</td>
<td>&lt;0.001</td>
<td>1.0</td>
</tr>
<tr>
<td>Rainfall</td>
<td>0.13</td>
<td>-0.01 to 0.27</td>
<td>0.06</td>
<td>0.22</td>
</tr>
<tr>
<td>Year (2016)</td>
<td>0.06</td>
<td>-0.26 to 0.40</td>
<td>0.69</td>
<td>0.79</td>
</tr>
<tr>
<td>Year (2017)</td>
<td>0.56</td>
<td>0.19 to 0.92</td>
<td>0.002</td>
<td>0.79</td>
</tr>
</tbody>
</table>

17.9, p < 0.001; Fig. 6; slope [±SE] = 1.06 ± 0.25, R² = 0.47) whereas there was no discernible effect of wind speed on heights during active foraging (slope = -0.17 ± 0.25, R² = 0.02).

4. DISCUSSION

Wind conditions encountered at sea have complex effects on birds’ time–activity and energy budgets, with potentially contrasting effects on the time and energy spent commuting between the colony and distant foraging sites and during periods of active foraging. For black-legged kittiwakes Rissa tridactyla and little auks Alle alle, which are purely flapping species, energy expenditure increased and food-provisioning rates of chicks decreased during strong winds (Gabrielsen et al. 1987, 1991, Konarzewski & Taylor 1989, Christensen-Dalsgaard et al. 2018). In contrast, however, northern fulmars Fulmarus glacialis, which are flugliders, had lower energy expenditure due to a lower wing beat frequency during stronger winds (Furness & Bryant 1996), while higher average wind speeds led to enhanced foraging efficiency and breeding success in wandering albatrosses Diomedea exulans (Weimerskirch et al. 2012). For northern gannets, we found that while wind speed and direction had strong effects on the speed of travel between the colony and distant foraging sites, there was no effect on the proportion of each trip spent commuting, probably because with a constant wind direction, birds would encounter both head and tail winds over the outward and return portions of a trip. Birds spent more time flying into head winds during active foraging than when commuting, probably to provide additional lift and reduce ground speed to aid detection of prey (Machovský-Capuská et al. 2012, Amélineau et al. 2014). However, birds also spent more time actively foraging during stronger winds, probably because strong winds disrupted the water surface (Sundarabalan et al. 2016), reducing prey visibility and hence potentially leading to both more time spent locating prey and a greater number of dives to capture prey as a result of lower success rates per dive (Finney et al. 1999, Elliott et al. 2014, Pistorius et al. 2015). Frequent dives and associated take-offs from the water surface are
Fig. 4. Proportion of daylight hours spent on the water by northern gannets in relation to distance travelled per trip and mean wind speed encountered during the trip. Lines (with 95% CI) plotted using model-averaged estimates for each predictor variable (see Table 2).

Fig. 5. (a) Mean (±SE) ground speeds of commuting northern gannets in relation to the mean wind speed at 10 m a.s.l. over a trip for tail winds (speed > 0) and head winds (speed < 0). (b) Average speed of travel and (c) proportion of daylight hours on the water during the return leg of foraging trips in relation to distance (km) for different bird–wind angles. Lines: linear model predictions in (a) and predictions estimated with loess function in R (blue: tail winds; red: cross winds; green: head winds) in (b,c). Shaded areas: 95% CI. Based on 188 foraging trips.
energetically expensive (Sakamoto et al. 2013), so a greater time spent actively foraging in stronger winds may explain why, while energy spent in commuting flight decreased with increasing wind speed in northern gannets (Amélineau et al. 2014), overall energy expenditure during trips increased with increasing wind speed in closely related Cape gannets M. capensis (Mullers et al. 2009).

We found that the increase in time spent foraging as wind speed increased did not result in any increase in overall trip duration, because birds compensated by decreasing the time they spent on the water during stronger winds, presumably reflecting a benefit in returning quickly to feed dependent offspring and relieve the partner at the nest. We also found that adults returned to Bass Rock at higher speeds from more distant foraging locations up to ~200 km from the colony, a similar pattern to that recorded by Hamer et al. (2007), who also found that speeds decreased for the furthest destinations, probably due to constraints on energy expenditure during sustained flapping flight. In keeping with this notion, we found that the increase in average speed of travel for distances up to ~200 km was accompanied by a decrease in the proportion of time on the water, particularly for birds flying into head winds, with an asymptote in speed of travel corresponding with a levelling off in time on the water beyond this distance. These data strongly suggest that by reducing time spent on the water, birds were able to buffer trip durations against adverse effects of strong winds encountered both while commuting and during active foraging.

In addition to altering time spent on the water during trips, birds also adjusted their flight heights in relation to wind speed and direction. The higher proportion of commuting flight at low elevations into head winds compared with tail winds was similar to that recorded by Hamer et al. (2007), who also found that speeds decreased for the furthest destinations, probably due to constraints on energy expenditure during sustained flapping flight. In keeping with this notion, we found that the increase in average speed of travel for distances up to ~200 km was accompanied by a decrease in the proportion of time on the water, particularly for birds flying into head winds, with an asymptote in speed of travel corresponding with a levelling off in time on the water beyond this distance. These data strongly suggest that by reducing time spent on the water, birds were able to buffer trip durations against adverse effects of strong winds encountered both while commuting and during active foraging.

In addition to altering time spent on the water during trips, birds also adjusted their flight heights in relation to wind speed and direction. The higher proportion of commuting flight at low elevations into head winds compared with tail winds was similar to that recorded in a wide range of species during migration (Krüger & Garthe 2001) and supports the notion that individuals can make use of both wind shear and ground effect to ameliorate the impacts of strong head winds on ground speed and energy expenditure (Finn et al. 2012, Tarroux et al. 2016). During the breeding season, this flexibility in commuting flight height may provide an additional behavioural buffer against the adverse effects of strong head winds during foraging trips.

Oceanic winds affect the prey fields of marine predators by altering their ability to access, detect

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Table 3. Top model sets for estimating effects of different variables on average speed of travel and proportion of time resting on the water during the return leg of each trip by northern gannets. LogLik: log-likelihood; AICc: Akaike’s information criterion corrected for small sample size

<table>
<thead>
<tr>
<th>Model</th>
<th>df</th>
<th>LogLik</th>
<th>AICc</th>
<th>ΔAICc</th>
</tr>
</thead>
<tbody>
<tr>
<td>Speed</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Distance + distance² + wind speed</td>
<td>7</td>
<td>-182.16</td>
<td>379.0</td>
<td></td>
</tr>
<tr>
<td>+ wind direction</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Distance + wind speed + wind direction</td>
<td>6</td>
<td>-184.28</td>
<td>381.0</td>
<td>2.0</td>
</tr>
<tr>
<td>Distance² + wind speed + wind direction</td>
<td>6</td>
<td>-187.94</td>
<td>388.3</td>
<td>9.3</td>
</tr>
<tr>
<td>Resting</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Distance + distance² + wind speed</td>
<td>7</td>
<td>-376.47</td>
<td>767.6</td>
<td></td>
</tr>
<tr>
<td>+ wind direction</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Distance + wind speed + wind direction</td>
<td>6</td>
<td>-378.48</td>
<td>769.4</td>
<td>1.8</td>
</tr>
<tr>
<td>Distance² + wind speed + wind direction</td>
<td>6</td>
<td>-379.72</td>
<td>771.9</td>
<td>4.3</td>
</tr>
</tbody>
</table>

Table 4. Flight heights of northern gannets during commuting and active foraging with head and tail winds. IQR: interquartile range

<table>
<thead>
<tr>
<th></th>
<th>Head wind</th>
<th>Tail wind</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>n</td>
<td>Flight height (m)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Median</td>
</tr>
<tr>
<td>Commuting</td>
<td>8600</td>
<td>12.6</td>
</tr>
<tr>
<td>Active foraging</td>
<td>7072</td>
<td>27.8</td>
</tr>
</tbody>
</table>

Fig. 6. Mean (±SE) flight heights of commuting northern gannets in relation to the mean wind speed at 10 m a.s.l. over a trip for tail winds (speed > 0) and head winds (speed < 0). Line (shading): linear model prediction (95 %CI)
and capture prey, acting as an additional dimension in their N-dimensional niche space (Raymond et al. 2010, Wilson et al. 2011, Weimerskirch et al. 2012). While gannets were able to buffer adverse effects of strong winds by reducing time spent drifting on water during trips and also by altering their flight heights in relation to wind conditions, other species may have different behavioural responses. For instance, Brünnich’s guillemots Uria lomvia and black-legged kittiwakes buffered the adverse effect of high winds on food-provisioning rates of chicks by switching to other food sources during windy days or increasing food delivery rates when weather improved (Elliott et al. 2014). Such behavioural flexibility is likely to be critical to maintaining fitness across variable environmental conditions encountered at sea, and parallels that recorded at an annual time-scale in a number of species in response to climate-related variation in prey abundance and availability (Grémillet et al. 2012, Kokubun et al. 2018).

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